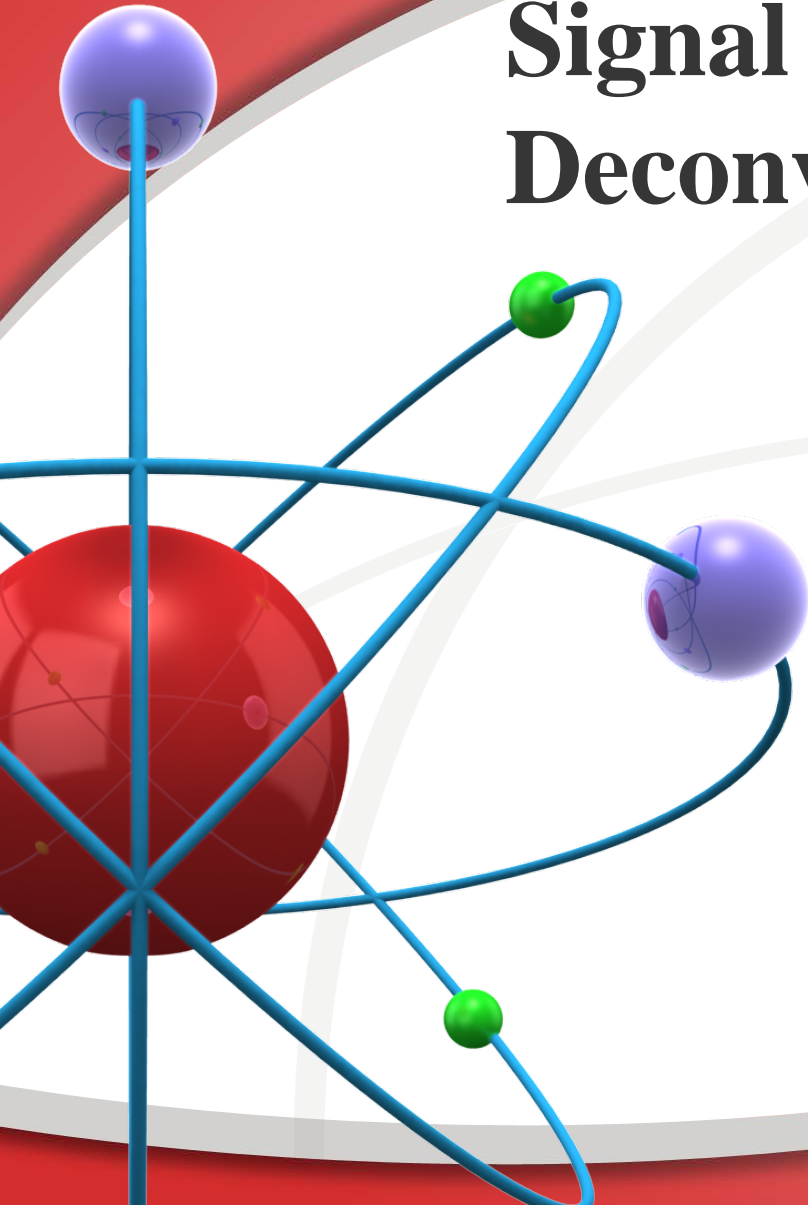
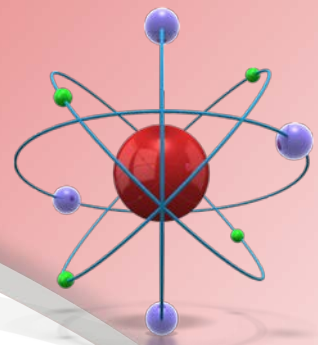


Signal Filtering and Deconvolution

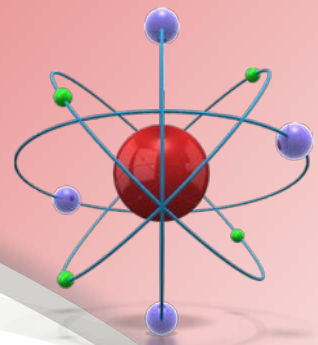


Filters

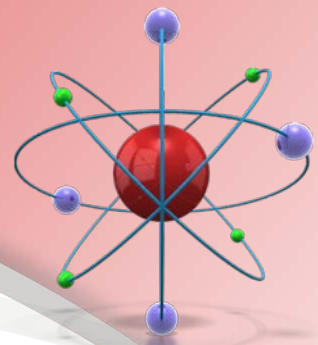


- Filters are mathematical functions that are multiplied into the frequency domain set to change the frequency distribution of the power spectrum.
- A filter is a magnitude vs. frequency function.

Ramp Filters



- A Ramp Filter emphasizes the high frequency components in our data sets.
- Therefore, a ramp filter enhances or emphasizes noise in our data sets.
- Since we use the ramp filter for filtered back projection reconstruction, we must somehow get rid of this additional noise in our image data sets. (smoothing filters)



3 Types of filters

- Low pass

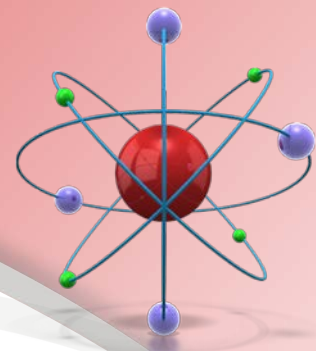
- Used to allow low frequencies through the filter and to reduce high frequencies (to attenuate)

- High pass

- Used to allow high frequencies through the filter and to reduce or attenuate low frequencies.
- Used to enhance edges or small objects

- Band pass

- Used to allow a certain band or range of frequencies through the filter.



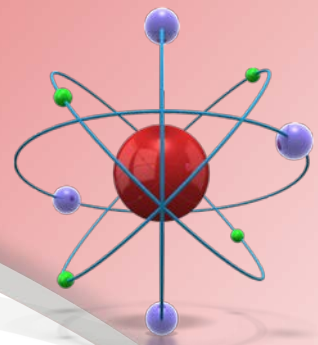
Filter Characteristics

- Characterized by 2 parameters
 1. Cutoff frequency
 2. Order

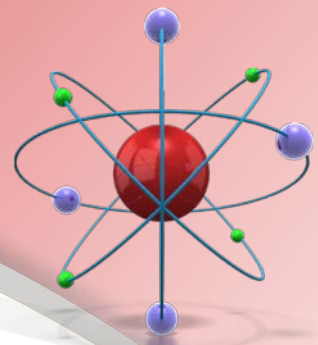
Note: Different facilities and manufacturers use different definitions and/or units to describe similar filters.

When using filters, make sure to know which set of definitions and units you are working with.

Commonly used filters



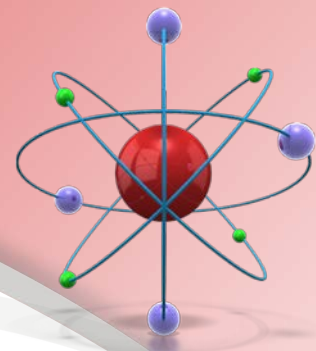
- Ramp filter
- Hann filter
- Hamming filter
- Shepp-Logan
- Parzen filter
- Butterworth filter
- Combination filter
- Weiner Filter (for restoration)
- Metz Filter (for restoration)



Ramp Filters

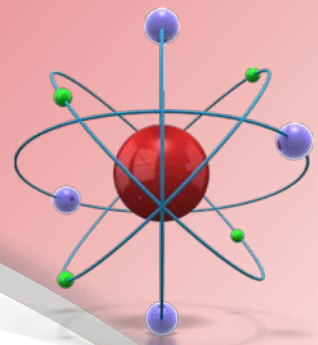
- High pass filter
- Used for edge enhancement
- Drawback: Propagate high frequency noise in the images

$$|H(\omega)|^2 = m\omega, \text{ m is positive}$$



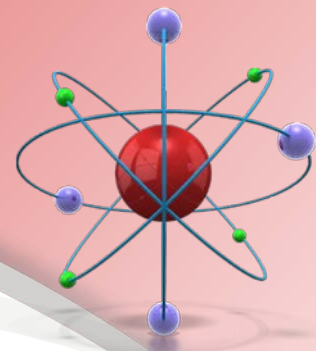
Hann and Hamming Filter

- Low pass filters
 - Used to remove high frequency noise
- The only parameter used to describe a Hann or Hamming filter is it's cutoff frequency.
- **Hamming** = $|H(\omega)|^2 = 0.5 + 0.5 \cos\left(\frac{\omega}{n}\right)$
- **Hann** = $|H(\omega)|^2 = 0.54 + 0.46 \cos\left(\frac{\omega}{n}\right)$
 - where $n = \text{cut-off frequency (point where amplitude} = 0)$



Hann vs. Hamming filters

- Functionally, the Hann and Hamming filters are very similar except that the Hamming filter goes to a non-zero value at the Nyquist Frequency
- These filters are used for studies where higher statistical accuracy is needed at the expense of a loss in spatial resolution.



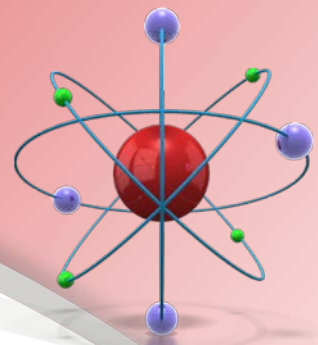
Butterworth Filter

- Low pass filter

- Better suited for studies where higher resolution needed to be preserved at the expense of higher statistical count fluctuations.
- A BF needs 2 parameters to describe the filter.
 - Cutoff frequency
 - Order of the filter

$$\left| H(\omega) \right|^2 = \frac{1}{1 + \left(\frac{\omega}{\omega_c} \right)^{2n}}$$

- The order of the filter is related to how fast the filter is cutoff.



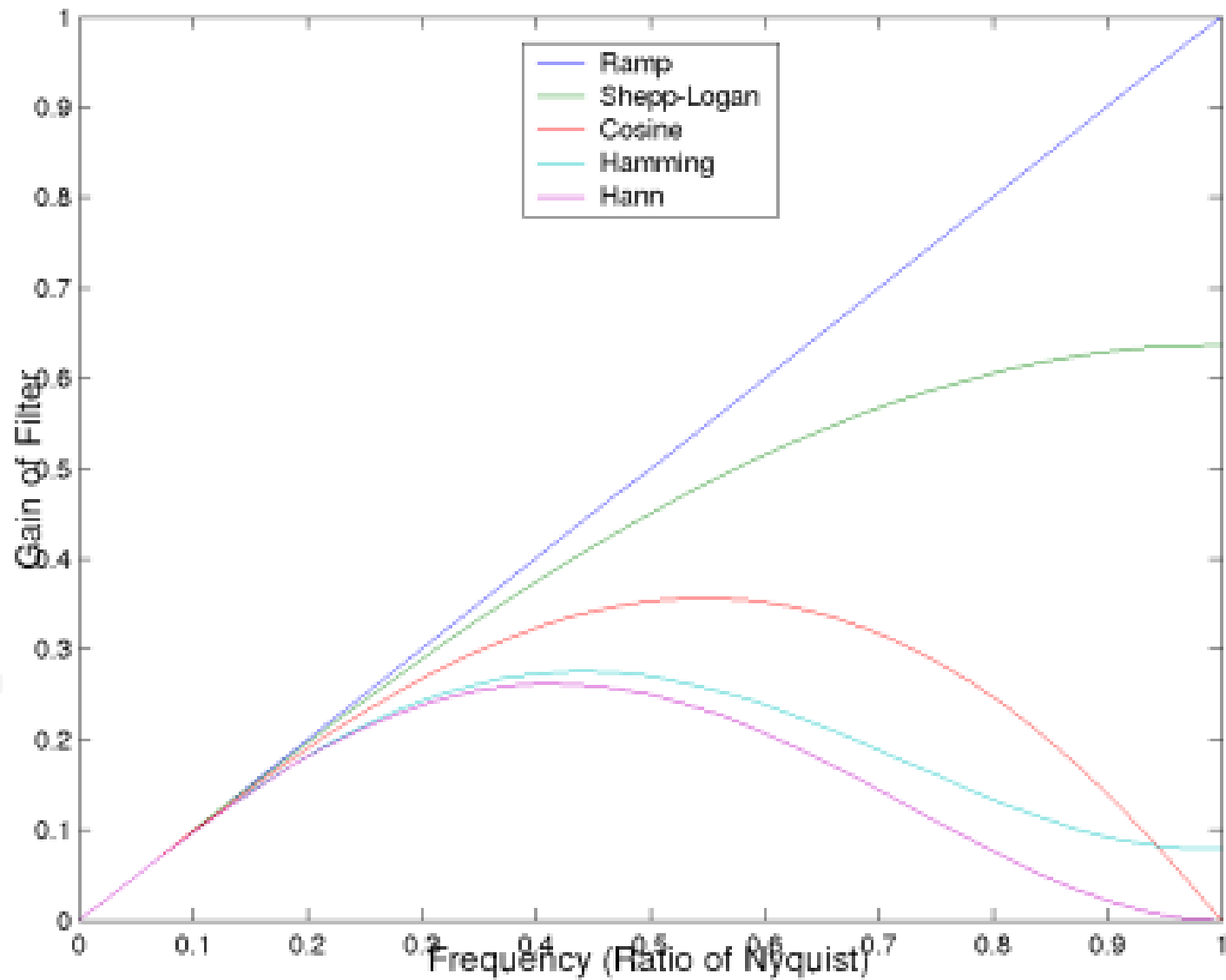
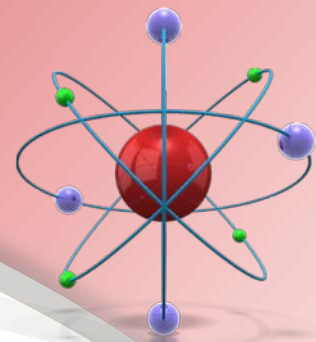
Cutoff Frequency & Order

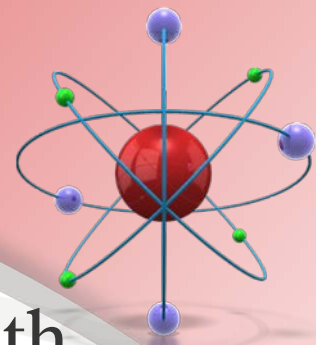
• Cutoff

- Allows us to retain information at higher frequencies while still eliminating noise.
- Remember, frequency and size are related by the Fourier transform (larger objects are represented by lower frequencies of sine and cosines)

• Order

- Determines how quickly the transition is made between frequencies that are kept and frequencies that are eliminated



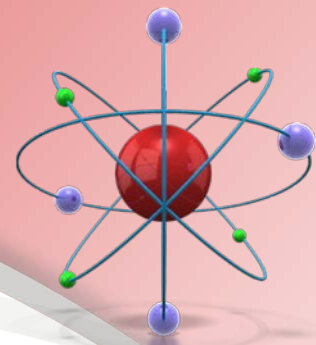


Combined Filters

- Filters designed to deconvolve (remove) both PSF and noise
 - **Wiener filter**
 - In frequency domain, Wiener filter $G(f)$ is given by:

$$G(f) = \frac{H^*(f)S(f)}{|H(f)|^2S(f) + N(f)}$$

- $G(f)$ and $H(f)$ are the FT's of g and h (the PSF), respectively, $S(f)$ is the mean power spectral density of the input signal, and $N(f)$ is the mean power spectral density of the noise



The Metz Filter

- Modification to inverse filter.

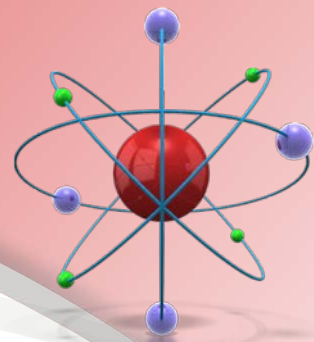
$$L_M = \frac{1 - [1 - H^2(\omega)]^\chi}{H(\omega)}$$

Where H is the FT of the PSF

- Suppresses the high frequency noise instead of amplifying it.
- Selection of factor χ such that that mean-square error (MSE) between ideal and filtered spectrum is minimized.
- Alternative to $H(\omega)$ as transform of PSF

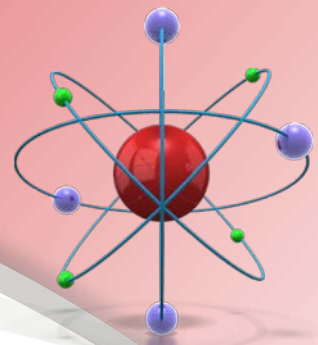
$$H(\omega) = e^{\frac{-\omega^p}{s}}$$

Setting Filter Parameters



- The Cutoff Frequency is probably the most important parameter in filtering work.
 - The CF should be chosen based on the Frequency space distribution of the data and the associated noise level in the images.
 - One criteria is to set the CF to a value approximately equal to the NF
 - Match the point of the filter where it drops to zero.
- Note: Noise level in spectra or images will depend on the count density
 - i.e. how many counts per channel/pixel
- The higher the count density the lower the noise level in relation to the image's power spectrum
 - Think signal to noise ratio

Order or Roll off of the filter



- How quickly the transition is made between frequencies that are kept and frequencies that are eliminated.
- The only real “rule of thumb” is that if the order is set too high, then oscillations in signal intensity will be introduced.