# **Nick Allison**

# **Education**

BSc. Electrical Engineering; Bsc. Computer Science; Minor in Computer Engineering, GPA: 3.93/4.00

2020 - 2020

University of Calgary

# **Skills**

Hardware: Software:

Digital Design, SystemVerilog, Synopsys Tools (VCS & Verdi), Verilator, Embedded Systems, Electromagnetics Analysis, Circuit Analysis (Semiconductors, MOS Circuits), LTSpice

C++, C, Rust, GDB, Python, Java, Linux, Git / ClearCase, Bash, CMake, Make, ROS Noetic, Machine Learning

# **Relevant Experience**

## SoC Design Intern

Qualcomm &

CMake Implementation

- Proposed a transition to using CMake as the new build system.
- Led this transition and achieved a best case speed up of 85%, with 67 minutes being the previous best for compilation to 10 minutes as the new best case, or 25 minutes as the average
- Fixed Rebuilding Process. Previously, rebuilding was not guaranteed to produce the correct binaries & libraries. After implementation, rebuilding time was reduced to 5 seconds as the new best case
- Hardware Design
  - Implemented, connected, and debugged new module instantiations
  - Created a script to list every wire and module within a module.
  - Used that script to find every instance of a counter that needed updating, and make the changes.
- Power Optimized Design
  - Implemented clock gating on DMA module for the display team.
  - Debugging 8-bit fixed point vs. 16-bit floating point power discrepancy.
  - Found other clock gating opportunities, determined whether gating was practical based on clock domain.

## **Robotics Engineering Intern**

MapaRobo ∂

May 2022 - Aug 2022 | Calgary, Alberta

May 2023 - Aug 2024 | Markham, Ontario

- Overhauled landscaping robot's localization and navigation on ROS Noetic and Ubuntu Linux. Solved issues with inaccurate conditions with GPS and IMU signals using PID control and A-Star planning. Kept location accuracy to within 0.02m and 3 degrees.
- Created a custom sensor fusion algorithm based on a Kalman filter in C++, as well as created a custom local path planning algorithm. Lowered accuracy degradation from 10 degrees/minute to 0 degrees/minute.
- Refined robot perception system to recognize objects at a 2x increase in distance, and lowered false positive rate by 90%.
- Designed and created a convolutional neural network with Pytorch to recognize adverse conditions with a 300% increase in performance from the previous system.

#### PASS Leader

Jan 2021 - present | Calgary, Alberta

University of Calgary - Peer Assisted Study Sessions

- Mentored and tutored first-year engineering students, understanding their levels of understanding. Improved grades of regular attendees by an average of at least 1 letter grade.
- Spoke publicly to 40 200 attendees and worked as a team with another PASS leader.

Private Tutor Sep 2020 – present

- Tutoring in courses ranging from Grade 10 science and math to Digital Systems Design.
  - "I got my math test back last week. I got 96% and my average was 98% which is a good improvement. Thank you for your help this year."
  - "hey nick! just wanted to say thanks for ur help this semester, i got an 100 on my physics final:)"
  - "I got 90 on my math final!! Thank you so much for your help this semester"

2020 - 2026

# Additional Experience

#### **Software Team Lead**

Jul 2022 - Apr 2023 | Calgary, Alberta

Alberta Collegiate Robotics - Canis Quadruped Team

- Managed a team of 4+ software engineering students, and increased productivity from the previous team using Agile Design practices including Kanban and hands-off mentoring.
- Created forwards and inverse kinematics models for robot legs and body in C++.
- Implemented a walking gait model for locomotion using an IMU and PID control for orientation and balance.

# VP Academic

Jun 2022 - Sep 2022

DeepRacer Calgary

- Developed an intro to math, coding, and machine learning curriculum covering topics from high school trigonometry to advanced Reinforcement Learning, including Q-Learning, Proximal Policy Optimization, and Soft Actor-Critic.
- Helped run competitions to which 200+ people attended and helped network and market the events.

# **Projects**

## Robot Hand, Helping Hands ∂

Jan 2023 - Apr 2023

- Led a team of 6 people to create and program a robot hand to translate speech into sign language.
- Used ROS and C++ to program and control the robot, and natural language processing to transcribe the speech

### Signal Generator @

Dec 2022

- Created a signal generator with an FPGA.
- Used a linear interpolation core to run at frequencies from 1Hz to 1MHz at 1Hz steps
- Used an R2R Ladder Digital-Analog-Converter to generate the sine wave
- Later updated to build and run with Verilator

## Note Linker and Markdown File Parser ∂

Jun 2024

- Created a plugin to parse markdown files and find links between notes.
- Created custom data structure to efficiently find links between files.
- Links 658 files in 4.70 seconds when running with no cache, or 0.12 seconds when using serialized file loader, and windows cache

# Python Scripter for Obsidian ∅

Aug 2023

• Created a plugin for the Program Obsidian to allow the user to use their own custom python plugins to interact with Obsidian.

## Huffman Coding Algorithm ∂

Nov 2022

Implemented a Huffman coding algorithm in C.

#### Wordle Solver ∅

Feb 2022

- Used C++ to most efficiently solve wordle with an average of 4.0 guesses.
- Chose the word with the highest weighted sum of likelihoods of its possible states as the next most likely guess.

## **Root Finding Algorithm**

Dec 2021

- Implemented using C++ to find all roots, real and imaginary, of an arbitrary degree polynomial.
- Used a Gradient Descent method on a grid of points in the complex plane until a certain local minimum is detected.

# **Node Voltage Calculator**

Sep 2021

• Developed a calculator to solve a circuit using the node-voltage method using the Eigen library for C++.

## References

Yuriy Zaporozhets, Engineer, Principal, Qualcomm

**Email Available Upon Request** 

**Victor Li**, *Engineer*, *Principal/Manager*, Qualcomm vli@ati.gualcomm.com

Bobby Man, Engineer, Staff, Qualcomm

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