Math 375

Geonho Roh

(1) 2.8 Pr 19

- Determine one-to-one
 - Describe its range
 - Find inverse

$$T(x, y, z) = (x, x + y, x + y + z)$$

Check one-to-one

Let
$$A = (x_1, y_1, z_1) B = (x_2, y_2, z_2)$$

If it is one-to-one it must follow T(A) = T(B) then A = B

$$T(A) = T(B) \ (x_1, x_1 + y_1, x_1 + y_1 + z_1) = (x_2, x_2 + y_2, x_2 + y_2 + z_2)$$

$$x_1 = x_2 \ x_1 + y_1 = x_2 + y_2 \ x_1 + y_1 + z_1 = x_2 + y_2 + z_2$$

Solving the equation we get

$$x_1 = x_2, y_1 = y_2, z_1 = z_2$$

So $A = B$

Therefore it is one-to-one

$$x(1,1,1)+y(0,1,1)+z(0,0,1)=(x,x+y,x+y+z)$$
 $(1,1,1),(0,1,1),(0,0,1)$ form a basis for range of T The Range is \mathbb{R}^3

$$T(x,y,z) = (u,v,w) \ (x,x+y,x+y+z) = (u,v,w) \ x = u,y = v-u,z = w-v \ T^{-1}(u,v,w) = (x,y,z) \ T^{-1}(u,v,w) = (u,v-u,w-v)$$

$$\operatorname{Check} TT^{-1}(x,y,z) = (x,y,z)$$

$$T(x,y-x,z-y) = (x,x+y-x,z+y-x+z-y) = (x,y,z)$$

Answer) It is one-to-one

Spanned by
$$(1, 1, 1), (0, 1, 1), (0, 0, 1)$$
 which is \mathbb{R}^3
 $T^{-1}(u, v, w) = (u, v - u, w - v)$

(2) 2.8 Pr 22

If S and T commute, prove that $(ST)^n = S^n T^n$ for all integers $n \ge 0$

Before proving for the $(ST)^n=S^nT^n$ we are going to show for $ST^n=T^nS$. It is trivial for n=0 Since $T^0=I$ for n=1 it is true because $ST^1=ST=TS$. Assume it is true for n and prove for n+1

$$ST^{n+1} = STT^n$$

$$= TST^n \text{ since we assume it is true for } n$$

$$= TT^nS$$

$$= T^{n+1}S$$

It is true for n+1 therefore it is true

Prove $(ST)^n = S^n T^n$ for all integers $n \ge 0$

It is trivial for n=0 Since $T^0=I$ for n=1 it is true because $(ST)^1=S^1T^1$ Assume it is true for n prove for n+1

For
$$n+1$$
 $(ST)^{n+1}=(ST)^n(ST)=S^nT^n(ST)$
Since they commute $S^nT^n(ST)=S^nST^nT=S^{n+1}T^{n+1}$
 $(ST)^{n+1}=S^{n+1}T^{n+1}$ is true

Therefore statement $(ST)^n = S^n T^n$ for all integers $n \ge 0$ is true

(3) 2.8 Pr 24

If S and Tare invertible and commute, prove that their inverses also commute.

$$ST = TS$$
 and $S^{-1} T^{-1}$ exist

$$ST = TS$$
 $S^{-1}ST = S^{-1}TS$
 $IT = S^{-1}TS$
 $T = S^{-1}TS$
 $T = T^{-1}S^{-1}TS$
 $I = T^{-1}S^{-1}TI$
 $I = T^{-1}S^{-1}TS$
 $I = T^{-1}S^{-1}TS$

Therefore inverse is also commute

(4) 2.12 Pr 3

A linear transformation $T:V_2\to V_2,$ maps the basis vectors i and j as follows:

$$T(i) = i + j \ T(j) = 2i - j$$

a) Compute T(3i-4j) and $T^2(3i-4j)$ in terms of i and j.

Since it is a linear transformation it must follow $T(a\alpha + b\beta) = aT(\alpha) + bT(\beta)$ where $\alpha, \beta \in V_2$ and scalars a, b

$$T(3i-4j) = 3T(i) - 4T(j) = 3(i+j) - 4(2i-j) = -5i + 7j$$

$$T^{2}(3i - 4j) = TT(3i - 4j) = T(-5i + 7j)$$

= $-5T(i) + 7T(j) = -5(i + j) + 7(2i - j) = 9i - 12j$

b) Determine the matrix of T and T^2

basis is
$$(i, j)$$

$$T(i) = (1)i + (1)j, \ T(j) = (2)i + (-1)j$$

$$T(i) = \begin{bmatrix} 1\\1 \end{bmatrix}, T(j) = \begin{bmatrix} 2\\-1 \end{bmatrix}$$
So $[T] = \begin{bmatrix} 1&2\\1&-1 \end{bmatrix}$

$$T^2 = egin{bmatrix} 1 & 2 \ 1 & -1 \end{bmatrix} egin{bmatrix} 1 & 2 \ 1 & -1 \end{bmatrix} = egin{bmatrix} 3 & 0 \ 0 & 3 \end{bmatrix}$$

c) Solve b if basis is replaced by (e_1,e_2) $e_1=i-j,e_2=3i+j$

$$T(e_1) = T(i-j) = -i + 2j = a(i-j) + b(3i+j)$$
 using problem a

$$a+3b=-1$$
 $-a+b=2$
 $a=rac{-7}{4},b=rac{1}{4}$
So $T(e_1)=\left[rac{-7}{4}
ight]$

$$T(e_2)=T(3i+j)=5i+2j=a(i-j)+b(3i+j)$$
 using problem a $a+3b=5$
$$-a+b=2$$

$$a=\frac{-1}{4},b=\frac{7}{4}$$

So
$$T(e_2) = \begin{bmatrix} \frac{-1}{4} \\ \frac{7}{4} \end{bmatrix}$$

$$[T] = \begin{bmatrix} \frac{-7}{4} & \frac{-1}{4} \\ \frac{1}{4} & \frac{7}{4} \end{bmatrix}$$

$$T^{2} = \begin{bmatrix} \frac{-7}{4} & \frac{-1}{4} \\ \frac{1}{4} & \frac{7}{4} \end{bmatrix} \begin{bmatrix} \frac{-7}{4} & \frac{-1}{4} \\ \frac{1}{4} & \frac{7}{4} \end{bmatrix} = \begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix}$$

a) Compute T(2i-3j) and determine the nullity and rank of T.

Since it is a linear transformation it must follow $T(a\alpha+b\beta)=aT(\alpha)+bT(\beta) \text{ where } \alpha,\beta\in V_2 \text{ and scalars } a,b$

$$T(2i-3j) = 2T(i) - 3T(j) = 2(1,0,1) - 3(-1,0,1) = (5,0,-1)$$

Representative matrix of T

$$T(i) = (1,0,1) = 1(1,0,0) + 0(0,1,0) + 1(0,0,1)$$

 $T(j) = (-1,0,1) = -1(1,0,0) + 0(0,1,0) + 1(0,0,1)$

$$[T] = egin{bmatrix} 1 & -1 \ 0 & 0 \ 1 & 1 \end{bmatrix}$$
 So $T(v), v = egin{bmatrix} x_1 \ x_2 \end{bmatrix} v \in V_2$ $T(v) = egin{bmatrix} 1 & -1 \ 0 & 0 \ 1 & 1 \end{bmatrix} egin{bmatrix} x_1 \ x_2 \end{bmatrix} = egin{bmatrix} x_1 - x_2 \ 0 \ x_1 + x_2 \end{bmatrix}$

The nullity of T

When
$$x_1 = 0, x_2 = 0$$

$$\begin{bmatrix} x_1 - x_2 \\ 0 \\ x_1 + x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Therefore nullity of T is 0

Range of T is spanned by
$$\begin{bmatrix} 1 & -1 \\ 0 & 0 \\ 1 & 1 \end{bmatrix}$$

Rank is 2

b) Determine the matrix of T

In part a we showed the matrix of T

$$[T] = egin{bmatrix} 1 & -1 \ 0 & 0 \ 1 & 1 \end{bmatrix}$$

c) Find bases (e_1, e_2) for V_2 and (w_1, w_2, w_3) for V_3 relative to which the matrix of T will be in diagonal form.

$$T(e_1)=a_1w_1+a_2w_2+a_3w_3 \ T(e_2)=b_1w_1+b_2w_2+b_3w_3 \ ext{to be a diagonal form } a_2=a_3=0, b_1=b_3=0 \ T(e_1)=a_1w_1 \ T(e_2)=b_2w_2$$

$$T(v) = egin{bmatrix} x_1 - x_2 \ 0 \ x_1 + x_2 \end{bmatrix}$$

$$e_1 = egin{bmatrix} c_1 \ c_2 \end{bmatrix} e_2 = egin{bmatrix} d_1 \ d_2 \end{bmatrix}$$
 $T(e_1) = egin{bmatrix} c_1 - c_2 \ 0 \ c_1 + c_2 \end{bmatrix}$ $T(e_2) = egin{bmatrix} d_1 - d_2 \ 0 \ d_1 + d_2 \end{bmatrix}$

- (6) 2.16 Pr 1
- (7) 2.16 Pr 3
- (8) 2.16 Pr 4