i2c_base.cpp

```
260 I2C Base::mStateMachineStatus t I2C_Base::i2cStateMachine()
261 {
262
       enum {
263
           // General states :
                            = 0x00,
264
           busError
           start
265
                            = 0x08,
266
           repeatStart
                            = 0x10,
267
           arbitrationLost = 0x38,
268
269
           // Master Transmitter States:
270
           slaveAddressAcked = 0x18,
271
           slaveAddressNacked = 0x20,
272
           dataAckedBySLave
                               = 0x28,
           dataNackedBySlave = 0x30,
273
274
275
           // Master Receiver States:
276
           readAckedBySLave
277
           readModeNackedBySlave = 0x48,
278
           dataAvailableAckSent = 0x50,
279
           dataAvailableNackSent = 0x58,
280
281
           // Slave Receiver States
282
           slaveAddressReceived
                                    = 0x60,
283
           slaveDataReceived
                                    = 0x80,
284
           slaveStoporRptStartRecv = 0xA0,
285
286
           // Slave Transmitter States
287
           slaveDataSend
                                    = 0xA8,
288
           dataAckedByMaster
                                    = 0xB8,
           masterNackRecv
                                    = 0xC0
289
290
291
       };
```