

More About Filter Design

Digital Signal Processing

April 11, 2023



Zero-Phase Filters

Say we want to design a filter with **zero phase delay**.

This is equivalent to the condition:

$$\text{Arg}(H(e^{i\omega})) = 0.$$

Or, in other words, or frequency response is a **real-valued function**:

$$H(e^{i\omega}) = A(\omega).$$

Inverse DTFT of Zero-Phase Condition

Because $h[n]$ is real, we have an even function: $A(\omega) = A(-\omega)$.

The DTFT is:

$$\begin{aligned}h[n] &= \frac{1}{2\pi} \int_{-\pi}^{\pi} A(\omega) e^{i\omega n} d\omega && \text{definition of DTFT} \\&= \frac{1}{2\pi} \int_{-\pi}^{\pi} A(\omega) (\cos(\omega n) + i \sin(\omega n)) d\omega && \text{expanding } e^{i\omega} \\&= \frac{1}{2\pi} \int_{-\pi}^{\pi} A(\omega) \cos(\omega n) d\omega && A(\omega) \sin(\omega n) \text{ is odd} \\&= \frac{1}{2\pi} \int_{-\pi}^{\pi} A(\omega) \cos(-\omega n) d\omega && \text{cosine is even} \\&= h[-n]\end{aligned}$$

Impulse Response of Zero-Phase Filter

Fact

An LTI system has zero phase only if it has an even impulse response function, i.e.,

$$h[n] = h[-n]$$

Note: This means that the only interesting zero-phase filters are **not causal**.

Also, note: All zero-phase filters have an **odd** length (of non-zero coefficients).

Not All Even $h[n]$ Are Zero-Phase

If $h[n]$ is zero-phase, then it is even.

The impulse response $-h[n]$ is also even. It has frequency response:

$$-H(e^{-i\omega}) = -A(\omega) = A(\omega)e^{i\pi}.$$

So, it has phase $\text{Arg}(-H(e^{-i\omega})) = \pi$.

Linear-Phase Causal Filters

Let's say that we want a causal filter. Zero-phase is out of the question, so the next best thing is a linear phase response.

This implies:

$$\text{Arg}(H(e^{i\omega})) = -\omega\alpha,$$

for some positive constant α . Note, both the **phase delay** and **group delay** are equal to α .

In other words,

$$H(e^{i\omega}) = A(\omega)e^{-i\omega\alpha},$$

where $A(\omega) = |H(e^{i\omega})|$.

Linear-Phase as Shifted Zero-Phase

We can get a linear-phase causal filter by shifting the impulse response of a zero-phase filter.

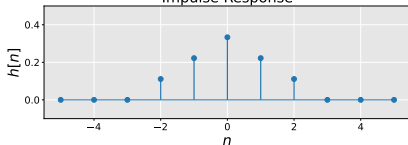
Let $h_{\text{ZP}}[n]$ be a zero-phase filter with L non-zero coefficients. These will be at time points $-\frac{L-1}{2} \leq n \leq \frac{L-1}{2}$.

Then, $h[n] = h_{\text{ZP}}[n - \frac{L-1}{2}]$ is a causal filter with phase delay $\frac{L-1}{2}$. In other words, it has linear phase:

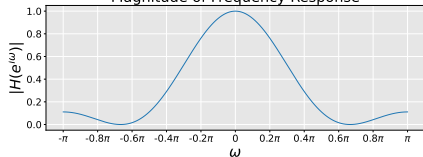
$$\text{Arg}(H(e^{i\omega})) = -\omega \frac{L-1}{2}.$$

Linear-Phase Causal Filter Example

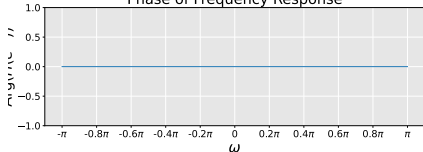
Impulse Response



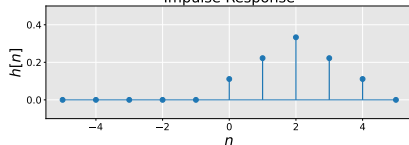
Magnitude of Frequency Response



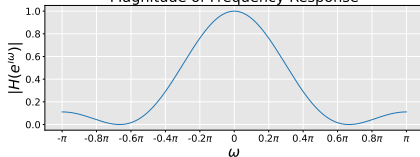
Phase of Frequency Response



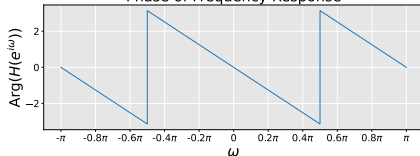
Impulse Response



Magnitude of Frequency Response



Phase of Frequency Response



Even-Length Linear-Phase Filters

Shifting zero-phase filters can only give us odd-length filters.

These filters have symmetry:

$$h[n] = h[L - n - 1].$$

We can also get an **even-length**, linear-phase, causal filter if we have a similar symmetry.

Even-Length Linear-Phase Example

