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Objective	A full-time systems engineering management position in the robotics industry Targeting the San Francisco Bay Area
Education	<b>McGill University (Montreal, Canada)</b> 2009-2014 Bachelor of Mechanical Engineering Louis C. Ho Scholarship & Dean's Honour List CGPA: 3.9/4.0
Leadership	<b>Founder and Project Manager, McGill Robotics</b> 2011-2014 <ul style="list-style-type: none"><li>Supervised 98 members across Mechanical, Software, Electrical, and Business divisions</li><li>Planned yearly design cycles, from concept to deployment, of an autonomous under-water vehicle and a lunar excavator</li><li>Raised and allocated \$90,000 of cash and in-kind donations from sponsors</li><li>Manufactured numerous parts on the lathe, mill, and other machine tools</li><li>International competition results: 1st in branding, 3rd in design &amp; presentation, 10th overall out of 39 teams at RoboSub 2014. 12th out of 50 at NASA in 2013</li></ul>
Academic Projects	<b>Propulsion and Control System for an Autonomous Underwater Vehicle</b> <ul style="list-style-type: none"><li>Implemented a 5-DOF control system in C++ and ROS</li><li>Established and iterated upon interface requirements using Agile design principles</li></ul> <b>Braille University: iOS Application</b> <ul style="list-style-type: none"><li>Built an iOS app that leverages external hardware to help blind users learn braille</li><li>Conducted usability tests to study human-computer interaction</li></ul>
Research Experience	<b>McGill Aerospace Mechatronics Lab</b> Summer 2013 <i>Prof. Inna Sharf &amp; Prof. Meyer Nahon</i> <ul style="list-style-type: none"><li>Designed and conducted experiments on a quadrotor aircraft to facilitate autonomous takeoff and landing</li><li>Published work on thruster performance characteristics at very low altitudes in the 2014 International Conference on Unmanned Aircraft Systems</li><li>Studied a variety of sensors for altitude measurement, with a focus on LiDAR</li></ul> <b>McGill Shockwave Physics Group</b> Summer 2012 <i>Prof. Andrew Higgins</i> <ul style="list-style-type: none"><li>Independently developed a granular dynamics physics simulator in MATLAB</li><li>Collaborated to perform detonation experiments and source components for a Photon Doppler Velocimeter for hypervelocity measurements</li></ul> <b>McGill Structural Dynamics and Vibrations Lab</b> Summer 2011 <i>Prof. Christophe Pierre</i> <ul style="list-style-type: none"><li>Created a Graphical User Interface in Python for turbomachinery simulations</li></ul>
Software Skills	MATLAB, Python, C/C++, Objective-C, L <sup>A</sup> T <sub>E</sub> X ROS, Unix, GitHub, Agile Development, Excel, AutoDesk Inventor