JOHN DOE

Ph.D. Student in Computer Science

jdoe@cs.uw.edu nickwalker.us

EDUCATION

2018—

The University of Washington, Seattle, WA.

• Ph.D. Computer Science

2014 - 18

The University of Texas, Austin, TX.

- BSA Computer Science
- Polymathic Scholar (Interdisciplinary Honors)

CONFERENCE

[c2]

"Human Perceptions of a Curious Robot that Performs Off-Task Actions." N. Walker, K. Weatherwax, J. Alchin, L. Takayama, M. Cakmak. *ACM/IEEE Int. Conf. Human-Robot Interaction*. Oxford, UK, March 2020

[c1]

"Open-World Reasoning for Service Robots." Y. Jiang, <u>N. Walker</u>, J. Hart, P. Stone. *Proc.*

29th Int. Conf. Automated Planning Scheduling. Berkeley, July 2019

JOURNAL

[j1]

"Jointly Improving Parsing and Perception for Natural Language Commands through Human-Robot Dialog." J. Thomason, A. Padmakumar, J. Sinapov, N. Walker, Y. Jiang, H. Yedidsion, J. Hart, P. Stone, R. J. Mooney. *Journal of Artificial Intelligence Research*. February 2020

REFEREED SYMPOSIUM, WORKSHOP

[w2]

"Desiderata for Planning Systems in General-Purpose Service Robots." N. Walker, Y. Jiang, M. Cakmak, P. Stone. *Proc. of 2019 ICAPS Workshop Planning Robotics*. Berkeley, July 2019

[w1]

"Neural Semantic Parsing with Anonymization for Command Understanding in General-Purpose Service Robots." N. Walker, Y.-T. Peng, M. Cakmak. *RoboCup 2019: Robot Soccer World Cup XXIII*. Sydney, July 2019

PRESENTATIONS

Human Perceptions of a Curious Robot that Performs Off-Task Actions. N. Walker. Hon-

da Research Institute Curious Minded Machines Workshop. San Jose. Oral.

2019 Desiderata for Planning for Planning Systems in General Purpose Service Robots. N.

Walker. ICAPS PlanRob Workshop. Berkeley. Oral.

Neural Semantic Parsing with Anonymization for Command Understanding in General

Purpose Service Robots. N. Walker. RoboCup Symposium. Sydney. Oral.

2018 UT Austin Villa@Home. N. Walker for UT Austin Villa. RoboCup@Home Domestic

Standard Platform League. Sydney. Oral. Best DSPL Poster.

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2017 Automatic Curriculum Graph Generation for Reinforcement Learning Agents. N. Walker,

R. Shah. AAAI. San Francisco. Poster.

RECOGNITION

2020— Graduate Research Fellowship – *National Science Foundation*

2018–19 Computer Science & Engineering Research Fellowship – *Allen School*, *UW*

RESEARCH COMPETITIONS

5th Place, UT Austin Villa@Home – RoboCup@Home DSPL
3rd Place, UT Austin Villa@Home – RoboCup@Home DSPL

RESEARCH AFFILIATIONS

2018— Human-Centered Robotics Lab – *University of Washington*

• PI: Maya Cakmak

2017–18 UT Austin Villa@Home – University of Texas at Austin

• PIs: P. Stone, L. Sentis, S. Niekum, A. Thomaz, R. Mooney. Supervisor: Justin Hart

2015–18 Building-Wide Intelligence Project – *UT AI Lab*

• PI: Peter Stone. Supervisors: Matteo Leonetti, Jivko Sinapov, Justin Hart

OUTREACH

2019 Demo Assistant – UW Engineering Discovery Days

• Organized and helped run an exhibit demonstrating our lab's research

2019 Program Assistant – UTCS Robotics Camp

• Helped high school students assemble robot kit, program intelligent behaviors

SERVICE

2019— Technical Committee – *RoboCup@Home*

2019— Peer Mentor – Allen School First Year Graduate Student Mentoring, UW

GRANTS RECEIVED

2020 A Speech and Language Dataset of GPSR Commands (League Development Grant) –

RoboCup Federation

MEETING PARTICIPATION

2019 Honda Research Institute Curious Minded Machine Workshop, San Jose

2019 ICAPS, Berkeley2019 RoboCup, Sydney

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WORK AND TEACHING EXPERIENCE

Winter 2019 Teaching Assistant – UW CSE 481C

• Developed assignments and supported undergraduates using the Kuri robot for their robotics capstone course

Summer 2016 Research Engineer Intern – USAA

- Developed experimental brain-computer interface software and hardware
- Work contributed to a SPIE conference publication

SKILLS

- Experienced with robotics software ROS, C++, Python
- Proficient with web technologies PHP, Typescript, HTML, CSS

PERSONAL

nickwalker.us

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orcid.org/0000-0001-7711-0003

github.com/nickswalker