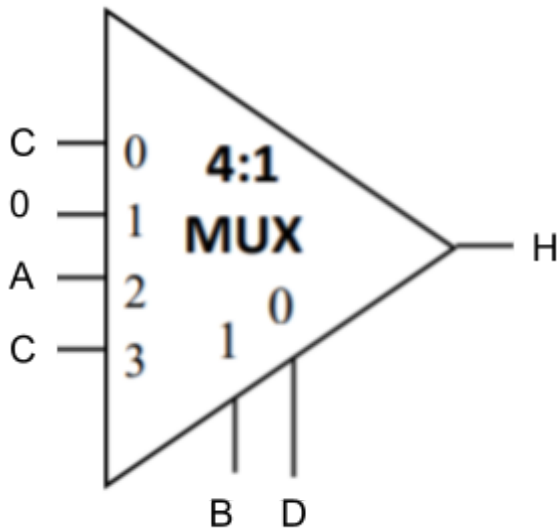
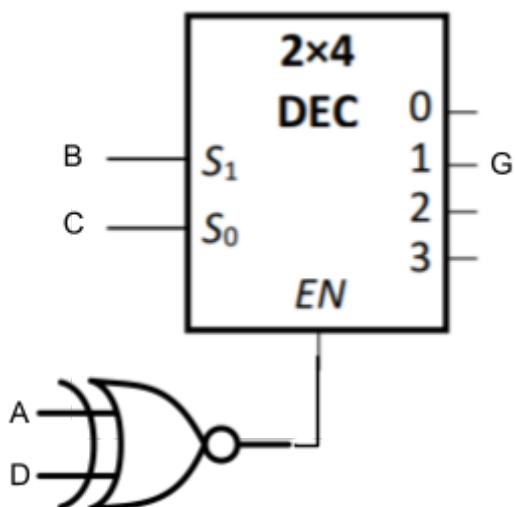


1.
 a)
 $B + C.D$

b)
 Selector lines BD
 Inputs C0AC



c)
 SOP is $A.B'.C.D + A'.B'.C.D'$
 G is given by C and B' and (A xnor D)
 $EN = (A \text{ xnor } D)$
 $S1 = B$
 $S0 = C$
 G = output 1



d)
 $F_2 = A_7 + A_6 + A_5 + A_4$

$$F_1 = A_7 + A_6 + A_5 \cdot A_4' \cdot A_3 + A_5 \cdot A_4' \cdot A_2$$

$$F_0 = A_7 + A_6' \cdot A_5 + A_6' \cdot A_4' \cdot A_3 + A_6' \cdot A_4' \cdot A_2' \cdot A_1$$

2.

$$JA = X \cdot B \cdot C'$$

$$KA = X'$$

$$JB = X$$

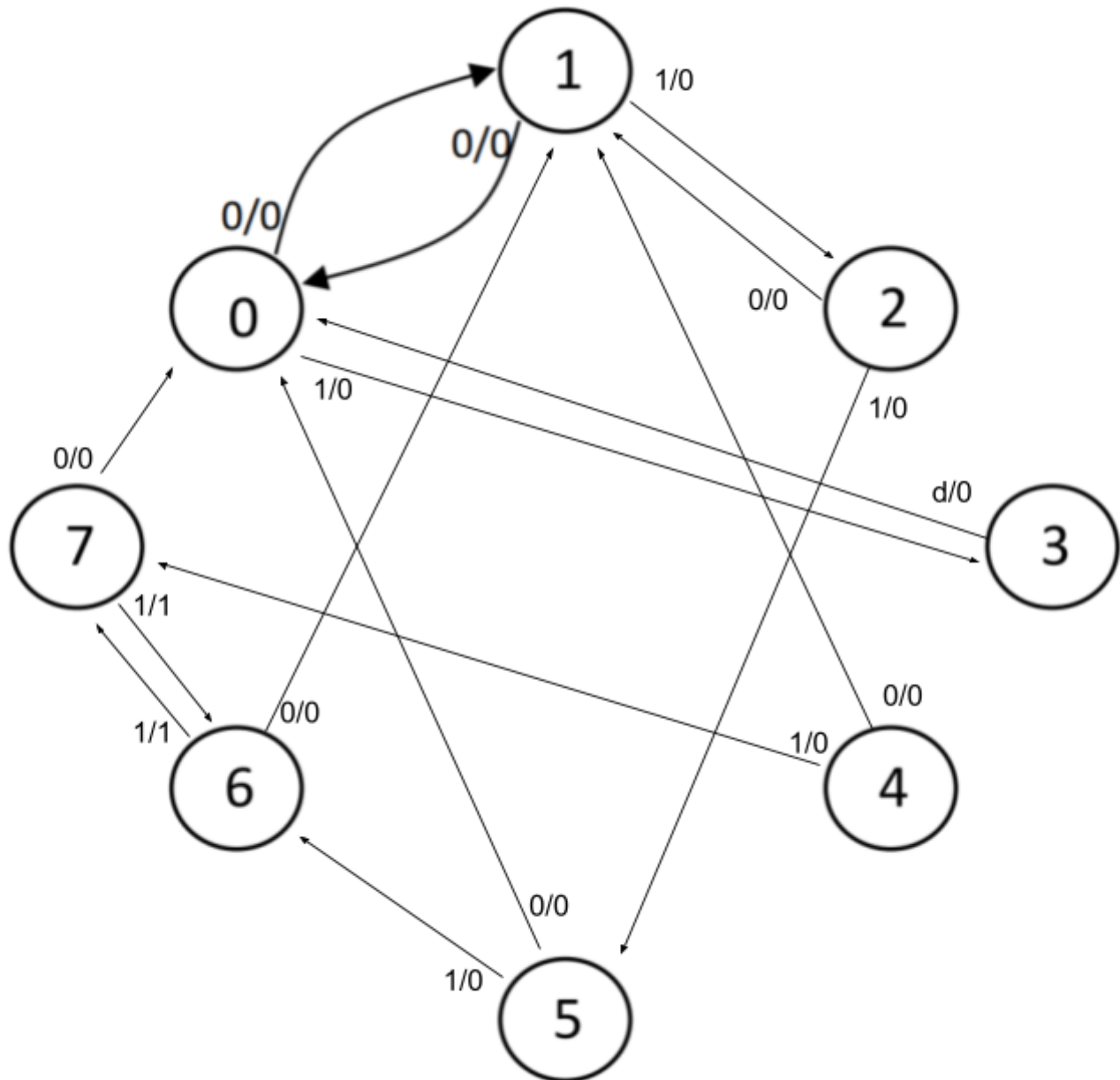
$$KB = A' + X'$$

$$JC = 1$$

$$KC = 1$$

$$Z = X \cdot A \cdot B$$

Because the inputs for flip flop C are always 1, its state always changes.



3.

a) 13

b) 27

c) 17

d) the branch will be taken if the array value is not smaller (greater or equal) than cutoff. In the initial case where the values are all smaller, then the branch will not be taken, hence it is better to predict branch not

taken, which will not cause any delays (saves 1 cycle). If we predict that the branch is not taken but it is taken (because the value is not smaller than cutoff), then this will cause the same delay of 1 cycle as in part c because we have executed uncorrected instructions. In the opposite case, if we assume branch taken, but the branch is not taken (because the value is smaller than cutoff), then this will also cause a similar delay. It is best to choose the case with higher probability of occurrence, i.e. if it is more likely that the values are smaller, then we should assume branch not taken, and vice versa.