

# Mastering physics

- Rounding tolerance for numerical answers is 2% by default.
- Default precision: Always state the result with 3 significant digits, e.g.  $15.15789=15.2$  .
- If units are required, a separate answer box for it will be there. Single box means numerical answer only. **In my questions I only ask you for the numerical answer (in units that are stated in the question)**
- Introduction to Mastering Physics assignment available (not graded) to get used to it

**Statistics assignment available:**

**Due date:**

**Monday 15.10, 9:00**

**Monday 5.11, 9:00**

# Problem set solutions

## Question 1

Let  $x$  be a continuous random variable governed by the following probability density function:

$$f(x) = \begin{cases} C(x^2 - 1) & \text{for } 1 \leq x \leq 3 \\ 0 & \text{elsewhere} \end{cases}$$

- (a) Use the normalisation condition to find the value of  $C$ .
- (b) Find the mean of  $f(x)$ .
- (c) Find the second moment of  $f(x)$ .
- (d) Use the definition of the variance to show, that in general, it is given by  $\sigma_x^2 = \langle x^2 \rangle - \langle x \rangle^2$ . Use this formula to calculate the variance of  $f(x)$ .

# Question 1

(a) Normalization requires

$$\int_1^3 C(x^2 - 1)dx = 1$$

$$C \left[ \frac{1}{3}x^3 - x \right]_1^3 = 1$$

$$C \left( 9 - 3 - \frac{1}{3} + 1 \right) = 1$$

$$C = \frac{3}{20}$$

# Question 1

(b) Find the mean

$$\langle x \rangle = \int_1^3 xP(x)dx = C \int_1^3 x(x^2 - 1)dx$$

$$= C \left[ \frac{1}{4}x^4 - \frac{1}{2}x^2 \right]_1^3 = C \left( \frac{81}{4} - \frac{9}{2} - \frac{1}{4} + \frac{1}{2} \right)$$

$$C \frac{64}{4} = \frac{3}{20} 16 = \frac{12}{5} = 2.4$$

# Question 1

(c) Find the second moment:

$$\begin{aligned}\langle x^2 \rangle &= \int_1^3 x^2 P(x) dx = C \int_1^3 x^2 (x^2 - 1) dx \\ &= C \left[ \frac{1}{5} x^5 - \frac{1}{3} x^3 \right]_1^3 = \frac{3}{20} \left( \frac{243}{5} - \frac{27}{3} - \frac{1}{5} + \frac{1}{3} \right) \\ &= 5.96\end{aligned}$$

# Question 1

Prove  $\sigma^2 = \langle x^2 \rangle - \langle x \rangle^2$

$$\sigma^2 = \int (x - \langle x \rangle)^2 P(x) dx$$

$$\sigma^2 = \int (x^2 - 2x\langle x \rangle + \langle x \rangle^2) P(x) dx$$

$$\begin{aligned}\sigma^2 &= \int x^2 P(x) dx - 2\langle x \rangle \int x P(x) dx + \langle x \rangle^2 \int P(x) dx \\ &= \langle x^2 \rangle - 2\langle x \rangle^2 + \langle x \rangle^2 = \langle x^2 \rangle - \langle x \rangle^2\end{aligned}$$

$$= 5.96 - (2.4)^2 = 0.2$$

## Question 2

A student monitors the activity of a radioactive source with a detector. The number of counts measured in a given time window obey the Poisson distribution  $P_{\mu}(x) = e^{-\mu} \frac{\mu^x}{x!}$ .

- (a) Show explicitly that the mean of this distribution is  $\mu$ . [Hint: Start with the normalisation condition.]
- (b) In the course of 10 minutes, the detector registers a total of 2540 counts. What is the corresponding rate  $R_{tot}$  (in counts per minute) and its uncertainty?
- (c) The student removes the source in order to record counts due to the background radiation. The detector registers 95 counts in the 3 minutes. What is the corresponding rate of the background,  $R_{bkg}$ , and its uncertainty?
- (d) What are the rate and its uncertainty due to the radioactive source alone?

# Question 2

(a) Start from normalization:  $\sum_{x=0}^{\infty} P_{\mu}(x) = \sum_{x=0}^{\infty} e^{-\mu} \frac{\mu^x}{x!} = 1$

Differentiate w.r.t  $\mu$  (use product rule):

$$\begin{aligned} \sum_{x=0}^{\infty} -e^{-\mu} \frac{\mu^x}{x!} + x e^{-\mu} \frac{\mu^{x-1}}{x!} &= 0 \\ - \sum_{x=0}^{\infty} e^{-\mu} \frac{\mu^x}{x!} + \sum_{x=0}^{\infty} x e^{-\mu} \frac{\mu^{x-1}}{x!} &= 0 \\ -1 + \sum_{x=0}^{\infty} x e^{-\mu} \frac{\mu^{x-1}}{x!} &= 0 \\ \sum_{x=0}^{\infty} x e^{-\mu} \frac{\mu^{x-1}}{x!} &= 1 \end{aligned}$$

Multiplying both sides with  $\mu$ , we get

$$\sum_{x=0}^{\infty} x e^{-\mu} \frac{\mu^x}{x!} = \sum_{x=0}^{\infty} x P_{\mu}(x) = \langle x \rangle = \mu$$



## Question 2

(b)

$$R_{tot} = \frac{2540 \pm \sqrt{2540}}{10min} = 254 \pm 5 \text{ min}^{-1}$$

(c)

$$R_{bg} = \frac{95 \pm \sqrt{95}}{3min} = 32 \pm 3 \text{ min}^{-1}$$

(d)

$$\begin{aligned} R_{sr} &= R_{tot} - R_{bg} = (254 \pm 5 \text{ min}^{-1}) - (32 \pm 3 \text{ min}^{-1}) \\ &= 222 \pm 6 \end{aligned}$$

Where error has been found through  $\sqrt{5^2 + 3^2}$   
(subtraction: absolute errors add in quadrature)

# Question 3

- a) What is the name of the distribution that governs the number of non-overlapping events that have a low probability of occurring during a given time window?
- b) A new medicine A is suspected of causing a rare disease. In a clinical trial with 1200 patients taking this medicine, 2 people contract this rare disease. What is the uncertainty in this number of incidents?
- c) The clinical trial ran over a period of 2 years. Based on your answer in (b), state the number of incidents of this rare disease per 1000 people per year taking medicine A including its uncertainty.
- d) In Ireland, 4870 people have contracted this disease in the last 3 years. The population in Ireland is 4.6 million. Calculate the incidence rate including its uncertainty per 1000 people per year.
- e) Assuming that nobody in Ireland has taken medicine A, is there enough evidence to conclude that medicine A is causing this rare disease? Justify your answer.

# Question 3

a) Poisson distribution

b)  $\sqrt{2} = 1.41$

c) Incidence rate per year per 1000 people:  $\frac{2}{1200} 1000 \frac{1}{2} = 0.83$ , uncertainty =  $\frac{\sqrt{2}}{1200} 1000 \frac{1}{2} = 0.59$ .

**Answer  $0.83 \pm 0.59$**

d) Incidence rate per year per 1000 people:  $\frac{4870}{4.6 \cdot 10^6} 1000 \frac{1}{3} = 0.353$ , uncertainty =  $\frac{\sqrt{4870}}{4.6 \cdot 10^6} 1000 \frac{1}{3} = 0.005$ .

**Answer  $0.353 \pm 0.005$**

e) No, error bars of the two incidence rates overlap.

Alternatively, compute difference in incidence rate:

$$0.83 - 0.35 = 0.48 \pm \sqrt{0.59^2 + 0.005^2} = 0.48 \pm 0.59$$

Error bar in difference is larger than the difference itself.

# Question 4

- a) Given two independent variables  $p$  and  $q$ , with an associated uncertainty  $\Delta p$  and  $\Delta q$ , state the general error propagation formula that yields the uncertainty of a function  $f(p, q)$  of these two variables.
- b) The lens formula relates the focal length  $f$  to the image and object distance given by  $p$  and  $q$ , respectively:  $f = \frac{pq}{p+q}$
- c) Show that the error in  $f$  is given by  $\Delta f = \frac{\sqrt{q^4 \Delta p^2 + p^4 \Delta q^2}}{(p+q)^2}$
- d) For  $p = (3.1 \pm 0.1)cm$  and  $q = (6.5 \pm 0.1)cm$ , calculate the focal length including its uncertainty.

## Question 4

$$a) \quad \Delta f = \sqrt{\left(\frac{\partial f}{\partial p} \Delta p\right)^2 + \left(\frac{\partial f}{\partial q} \Delta q\right)^2}$$

$$b) \quad \frac{\partial f}{\partial p} = \frac{(p+q) \cdot q - pq \cdot 1}{(p+q)^2} = \frac{q^2}{(p+q)^2}$$

$$\frac{\partial f}{\partial q} = \frac{(p+q) \cdot p - pq \cdot 1}{(p+q)^2} = \frac{p^2}{(p+q)^2}$$

$$\text{So } \Delta f = \frac{1}{(p+q)^2} \sqrt{(q^2 \Delta p)^2 + (p^2 \Delta q)^2}$$

$$c) \quad \text{Substituting the numbers gives } f = (2.10 \pm 0.05) \text{ cm.}$$

Note: Uncertainty only needs to be stated with one (or at most two) significant figure(s). Last significant figure of result should be of the same order of magnitude as the uncertainty.