

Faculty of Engineering, Mathematics and Science School of Mathematics

JF Mathematics

Trinity Term 2017

JF Theoretical Physics

JF Two Subject Mod

MA1111: Linear Algebra I

Saturday, May 13

Goldsmith Hall

09:30 - 11:30

Prof. Larry Rolen

Instructions to Candidates:

Attempt all questions. All questions will be weighted equally.

Materials Permitted for this Examination:

Formulae and Tables are available from the invigilators, if required.

Non-programmable calculators are permitted for this examination,—please indicate the make and model of your calculator on each answer book used. This is a closed-book exam, so no notes or other study materials are allowed.

You may not start this examination until you are instructed to do so by the Invigilator.

- 1. The solutions of the differential equation y''' 2y'' y' + 2y = 0 are those functions of the general form $y(x) = c_1 e^x + c_2 e^{2x} + c_3 e^{-x}$, where c_1, c_2, c_3 are arbitrary real constants. A particular solution can be specified by giving initial conditions.
 - (a) Suppose y(x) is a solution to the differential equation above, and satisfies the initial conditions y(0) = 1, y'(0) = 3, and y''(0) = 2. Give a system of linear equations for c_1, c_2, c_3 (plug in the initial conditions into the general form of y(x)).
 - (b) Solve the system of equations from (a) to find c_1, c_2, c_3 , and hence y(x).
- 2. Consider the linear transformation $T \colon \mathcal{P}_{\leq 3}(\mathbb{R}) \to P_{\leq 3}(\mathbb{R})$, from the vector space of real-coefficient polynomials of degree at most 3 to itself, given by $T(f(x)) = f(x) + x^3 f\left(\frac{1}{x}\right)$.
 - (a) Find a matrix representation of T with respect to the standard basis $\{1,x,x^2,x^3\}$.
 - (b) Use (a) to find bases for the image and kernel of T.
- 3. (a) Use Laplace expansions to find the determinant $\det \begin{pmatrix} \frac{3}{2} & \frac{1}{0} & \frac{1}{0} & \frac{0}{-1} & \frac{4}{0} \\ \frac{3}{2} & 0 & 0 & -1 & 0 \\ 0 & 0 & 1 & 0 & -1 \\ 0 & -1 & 2 & 0 & 1 \\ 1 & 0 & 0 & 0 & -2 \end{pmatrix}$.
 - (b) Explain why $\det \begin{pmatrix} \frac{3}{2} & \frac{4}{9} & \frac{6}{4} & \frac{8}{100} \\ \frac{1}{2} & \frac{11}{12} & \frac{2}{7} & \frac{2}{7} \\ \frac{2}{7} & \frac{1}{3} & \frac{4}{7} & \frac{10}{7} \end{pmatrix} = 0.$
- 4. Are the following sets bases for \mathbb{R}^3 ? If so, show it, and if not, explain why.
 - (a) $\{(1,2,3),(-1,2,4),(0,5,-1)\}.$
 - (b) $\{(1,2,3),(4,7,1),(0,0,1),(1,-2,3)\}.$
- 5. Suppose that $\{v_1, \ldots, v_k\}$ is a set of vectors in a vector space V and T is a linear transformation from V to another vector space W.
 - (a) Show that if $\{T(v_1), \ldots, T(v_k)\}$ is a linearly independent set of vectors in W, then $\{v_1, \ldots, v_k\}$ is also linearly independent.
 - (b) Show that if T is injective and $\{v_1, \ldots, v_k\}$ is linearly independent, then $\{T(v_1), \ldots, T(v_k)\}$ is also linearly independent.