

Faculty of Engineering, Mathematics and Science School of Mathematics

Trinity Term 2016

MA1111: Linear Algebra I

Tuesday, May 10

RDS

14:00 - 16:00

Prof. V. Dotsenko

Instructions to Candidates:

ATTEMPT **ALL** QUESTIONS

The number of marks you can get for a complete solution to any individual question is written next to the question. A complete solution to a question includes coherent explanations of answers you give.

Unless otherwise specified, you may use all statements proved in class without proof; when using some statement, you should formulate it clearly, e.g. "in class, we proved that a square matrix A is invertible if and only if $\det(A) \neq 0$ ".

Non-programmable calculators are permitted for this examination.

You may not start this examination until you are instructed to do so by the Invigilator.

1. Denote by
$$A$$
 the matrix $\begin{pmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{pmatrix}$ and by b the vector $\begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix}$.

- (a) (15 points) Show how to compute the matrix A^{-1} using elementary row operations, and use the matrix A^{-1} to solve the system Ax = b.
- (b) (10 points) Show how to use Cramer's rule to solve the system Ax = b.
- 2. (a) (10 points) Outline the proof from class of the fact the determinant of a matrix does not change if we add to one of its rows a multiple of another row.
 - (b) (15 points) For the matrix $A=\begin{pmatrix}1&2&3&4\\-2&1&4&-3\\-3&-4&1&2\\-4&3&-2&1\end{pmatrix}$, compute the matrix product of A and its transpose matrix, and explain how to use your result to calculate the determinant of A.
- 3. (a) (12 points) State the definition of a basis of a vector space. Show that the vectors $f_1=\begin{pmatrix}3\\-1\end{pmatrix}$ and $f_2=\begin{pmatrix}1\\-1\end{pmatrix}$ form a basis of \mathbb{R}^2 .
 - (b) (13 points) Suppose that the matrix of a linear transformation of \mathbb{R}^2 relative to the basis f_1 , f_2 from (b) is $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$. Compute the matrix of the same linear transformation relative to the basis of standard unit vectors of \mathbb{R}^2 .

- 4. (a) (5 points) State the definition of an eigenvalue and of an eigenvector of a linear transformation of a vector space V.
 - (b) (15 points) What are the eigenvalues of the linear transformation T of the four-dimensional space of 2×2 -matrices which sends every matrix X to AX-XA, where $A=\begin{pmatrix} 1 & 0 \\ 2 & -1 \end{pmatrix}$?
 - (c) (5 points) Does the linear transformation T from (b) have a basis of eigenvectors?