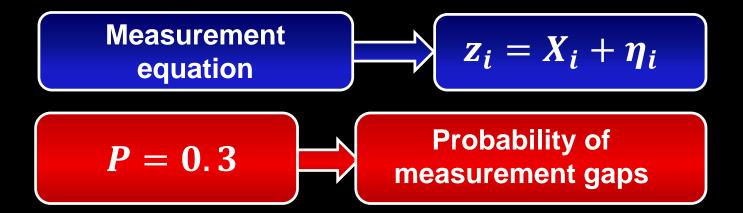
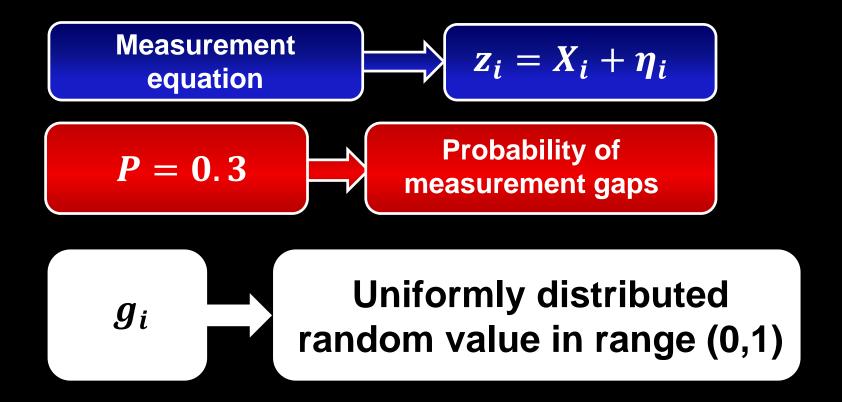


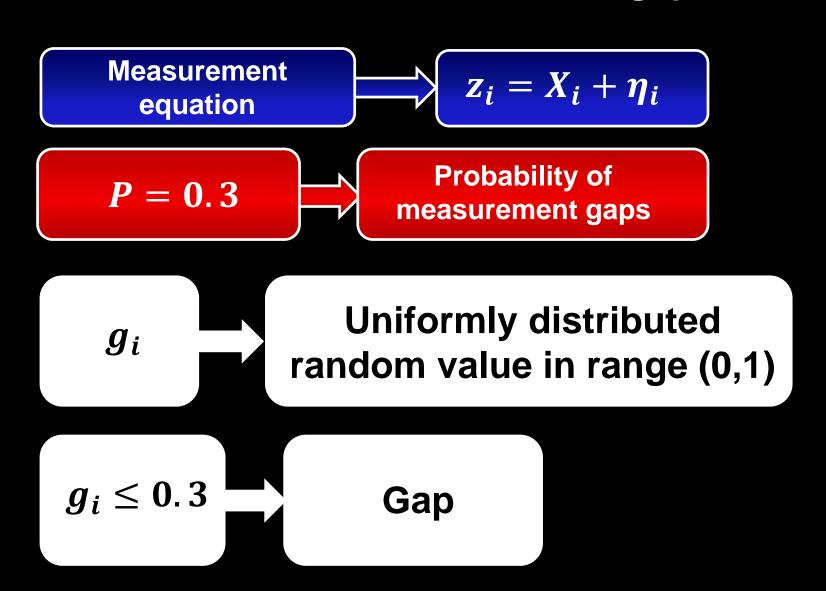
"Space Data Processing: Making Sense of Experimental Data"

Laboratory work 8
Tracking and forecasting
in conditions of measurement gap

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Term 1B, October 2017
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Filtration is done only if measurements at step i are available $X_{i+1,i+1}$ Filtered estimate

Filtration error covariance matrix

Prediction (extrapolation) $X_{i+1,i}$ Extrapolated estimate $P_{i+1,i}$ Prediction error covariance matrix

Filtration is done only if measurements at step i are available

$$X_{i+1,i+1}$$
 Filtered estimate

 $P_{i+1,i+1}$ Filtration error covariance matrix

If measurements at step i are not available, then filtered estimate is equal to extrapolated estimate

$$X_{i+1,i+1} = X_{i+1,i}$$
 $P_{i+1,i+1} = P_{i+1,i}$