

LO2: The Expectation Operator and Gaussians

* Def Expectation Operator

$$E\{x\} = \int_{-\infty}^{+\infty} x p(x) dx = \mu_x \quad (\text{Weighted average})$$

- Note: $p(x)$ is a pdf not probability (class conv.)

* Properties of $E\{\cdot\}$ Linear operator

$$E\{A\} = A$$

$$E\{Ax\} = A E\{x\}$$

$$E\{A+x\} = A + E\{x\}$$

$$E\{x+y\} = E\{x\} + E\{y\}$$

$$\text{Proof: } E\{x+y\} = \iint (x+y) p(x,y) dx dy =$$

$$= \iint x p(x,y) dx dy + \iint y p(x,y) dx dy =$$

$$= \int x \underbrace{\int p(x,y) dy}_{\text{marginalization or total probability (see LO1.5 on Convs)}} dx + \int y \int p(x,y) dx dy =$$


marginalization or total probability (see LO1.5 on Convs)

$$= \int x p(x) dx + \int y p(y) dy //$$

• Anti-properties

$$E\{x \cdot y\} \neq E\{x\} E\{y\} \text{ (in general)}$$

$$\text{If } x, y \text{ uncorrelated } (\sigma_{xy}^2 = 0) \Rightarrow E\{xy\} = E\{x\}E\{y\}$$

$$\text{If } x, y \text{ independent} \Rightarrow x, y \text{ uncorrelated}$$


• Expectation of a multidimensional c.v.


$$E\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} E\{x\} \\ E\{y\} \end{bmatrix}$$

• Conditional expectation $E\{x|y\} \triangleq \int_{-\infty}^{\infty} x f(x|y) dx$

Covariance Scalar form (cross covariance)

$$\sigma_{xy}^2 = \text{cov}(x, y) = E\{(x - E\{x\})(y - E\{y\})\}$$

$$\begin{aligned} \sigma_{xx}^2 = \text{cov}(x, x) &= E\{(x - E\{x\})^2\} \quad (\text{Autocovariance}) \\ &= E\{x^2\} - E\{x\}^2 = \text{var}(x) \quad (\text{or variance}) \end{aligned}$$

Exercise: Show this 

Property: $\sigma_{xx}^2 \geq 0$

Covariance. Vectorial form

(cross covariance)

$$\Sigma_{xy} = \text{cov}(x, y) = E\{(x - E\{x\})(y - E\{y\})^T\}$$

$$\Sigma_x = \text{cov}(x, x) = \text{cov}(x) = E\{(x - E\{x\})(x - E\{x\})^T\}$$

Ex: expand Σ_{xy}

$$\begin{aligned} & E\{xy^T + x(-E\{y\})^T - E\{x\}y^T + E\{x\}E\{y\}^T\} = \\ & = E\{xy^T\} - E\{x\}E\{y\}^T - E\{E\{x\}y^T\} + E\{E\{x\}E\{y\}^T\} = \\ & = E\{xy^T\} - E\{x\}E\{y\}^T - \cancel{E\{x\}E\{y\}^T} + \cancel{E\{x\}E\{y\}^T} \end{aligned}$$

*Note: $\Sigma_{xy} = 0 \Leftrightarrow E\{xy^T\} = E\{x\}E\{y\}^T$

UncorrelatedExer: expand Σ_x Col 1: Σ_x is symmetric: $\Sigma_x = \Sigma_x^T$ (not Σ_{xy} !)

$$\Sigma_x = E\{x \cdot x^T\} = E\left\{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix}\right\} = E\left\{\begin{bmatrix} x_1x_1 & x_1x_2 & x_1x_3 \\ x_2x_1 & x_2x_2 & x_2x_3 \\ x_3x_1 & x_3x_2 & x_3x_3 \end{bmatrix}\right\}$$

$\mu_x = 0$

Col 2: Σ_x is Positive Semi definite (psd)

$$v^T \Sigma_x v \geq 0, \quad \forall v$$

proof: $v^T E\{(x-\mu)(x-\mu)^T\} v =$
 $= E\{ \underbrace{v^T(x-\mu)}_{u \in \mathbb{R}} (x-\mu)^T v \} = E\{u^2\} \geq 0$

Sample mean and sample covariance.

$x_i \sim p(x)$ iid (independent and identically distributed)

Sample mean: $\bar{x} = \frac{1}{N} \sum_{i=1}^N x_i$

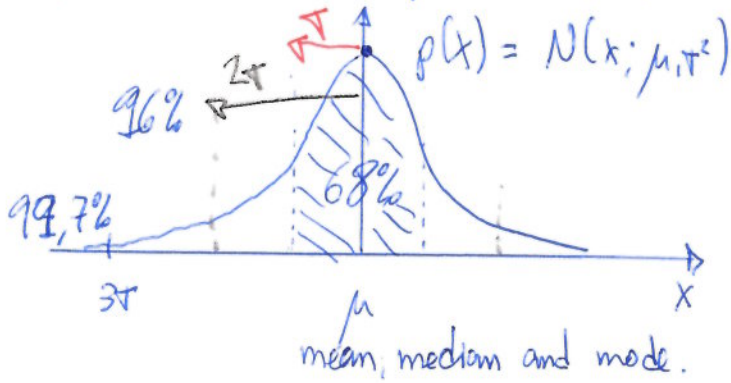
Sample covariance $\bar{\Sigma}_x = \frac{1}{N-1} \sum_{i=1}^N (x_i - \bar{x})(x_i - \bar{x})^T$

Gaussian distribution (univariate)

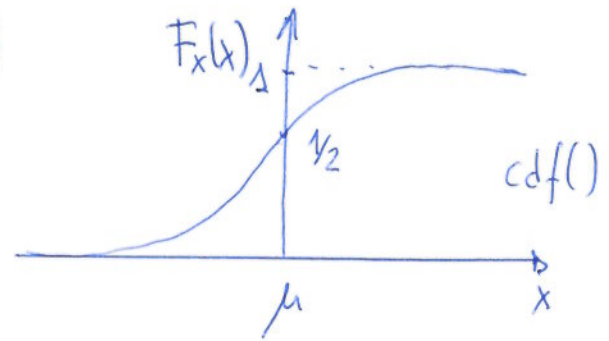
$$p(x) = \underbrace{\frac{1}{\sqrt{2\pi\tau^2}}}_{\text{normalization factor}} e^{-\frac{1}{2\tau^2}(x-\mu)^2} = \mathcal{N}(x; \mu, \tau^2)$$

normalization factor $\Rightarrow \int \mathcal{N}(x; \mu, \tau^2) dx = 1$

* Probability density function (pdf)



Cumulative distribution F



$$\mu = E\{x\} = \int_{-\infty}^{\infty} x p(x) dx$$

$$\sigma^2 = \text{var}(x) = E\{(x - \mu)^2\}$$

All required parameters
to describe a Gaussian.

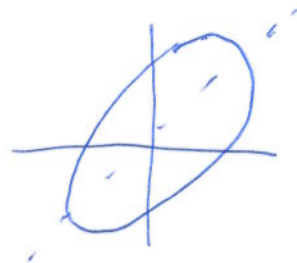
$x \sim N(\mu, \sigma^2)$ draw a sample. Most functions for $\mu=0, \sigma=1$

* Multivariate Gaussian.

$$p(x) = \frac{1}{(2\pi)^{n/2} |\Sigma_x|^{1/2}} e^{-\frac{1}{2}(x-\mu)^T \Sigma_x^{-1} (x-\mu)} = N(x; \mu, \Sigma_x)$$

Ex: Intuition on a 2D Gaussian.

$$\Sigma_x = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$



positive
correlation.

$$\Sigma_x = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$$



negative
correlation.

* Covariance Projection

$$\text{i.i.d } x \sim N(\mu_x, \Sigma_x) \quad , \quad \text{i.i.d } y = f(x)$$

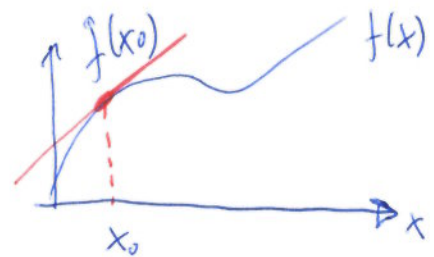
+ Affine transformation $f: y = Ax + b$

$$\mu_y = E[y] = E[Ax + b] = A E[x] + b = A\mu_x + b$$

$$\begin{aligned} \Sigma_y &= E[(y - \mu_y)(y - \mu_y)^T] = & (AB)^T &= B^T A^T \\ &= E[(Ax + b - A\mu_x - b)(Ax + b - A\mu_x - b)^T] = \\ &= E[A(x - \mu_x)(x - \mu_x)^T A^T] = & A \cdot \Sigma_x \cdot A^T \end{aligned}$$

+ Non-linear covariance projection

$$y = f(x)$$



-1D

$$y = f(x_0) + \underbrace{\frac{df(x)}{dx}}_{x_0} \cdot (x - x_0) + O((x - x_0)^2)$$

computed analytically or numerically.

Taylor expansion

- N-Dimensions

$$y = f(x_0) + \sum_{i=1}^d \underbrace{\frac{\partial f(x)}{\partial x^i}}_{\big|_{x_0}} \cdot (x^i - x_0^i) + O(\|x - x_0\|^2) =$$

$$\text{Jacobian: } \left[\frac{\partial f}{\partial x^1}, \frac{\partial f}{\partial x^2}, \dots, \frac{\partial f}{\partial x^d} \right] = J$$

$$= f(x_0) + J \cdot (x - x_0) + O(\|x - x_0\|^2) \simeq$$

$$\simeq f(x_0) + Jx - Jx_0 = \underbrace{J}_{A} \cdot x + \underbrace{f(x_0) - Jx_0}_b$$

$$\Rightarrow y \sim N(f(\mu_x), A \Sigma_x A^T)$$

Linearization is not exempt of problems

Error assumed $O(\Delta x^2)$

Uncented transformation alleviates this (L07).