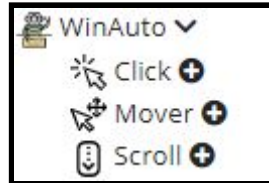


MÓDULO WINAUTO

Este módulo te permite utilizar la librería de Python pywinauto

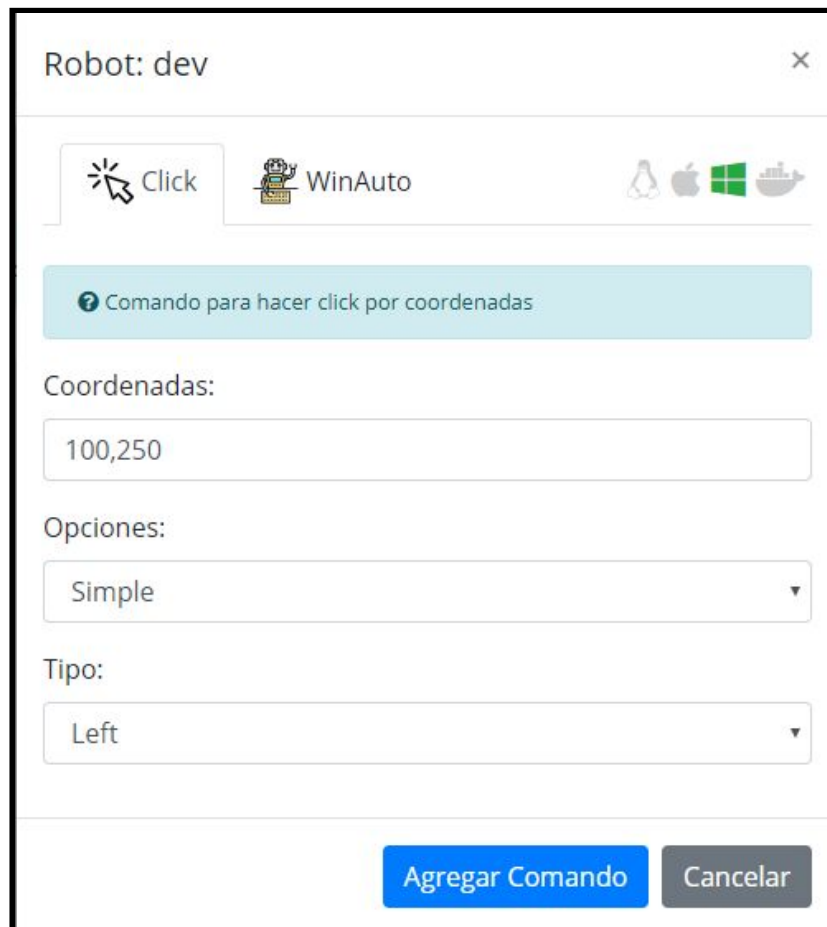
1. Ir al menú **"Mods"** y abrir el módulo **"Autogui"**



2. Click

Para utilizar los métodos de mouse de pywinauto, completar lo siguiente:

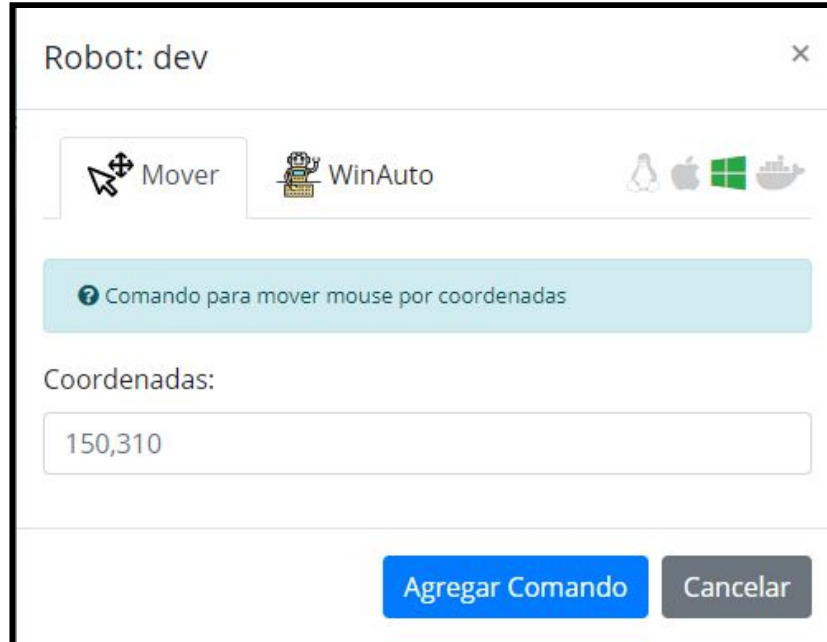
- **Coordenadas:** Coordenadas donde se quiere hacer click
- **Opciones:** Click simple, doble, mantener o soltar
- **Tipo:** Izquierda, derecha o medio
-

A screenshot of a web-based configuration window titled 'Robot: dev'. The window has a sidebar with a 'Click' button and a 'WinAuto' button. The main area contains a light blue header with a question mark icon and the text 'Comando para hacer click por coordenadas'. Below this, there are three sections: 'Coordenadas:' with a text input field containing '100,250'; 'Opciones:' with a dropdown menu showing 'Simple'; and 'Tipo:' with a dropdown menu showing 'Left'. At the bottom right, there are two buttons: 'Agregar Comando' (blue) and 'Cancelar' (grey).

3. Mover

Para usar el método mover de mouse de pywinauto, ingresar:

- **Coordenadas:**Coordenadas a donde se quiere mover el mouse



The screenshot shows a window titled "Robot: dev" with a close button (X) in the top right corner. Below the title bar, there is a toolbar with two buttons: "Mover" (with a mouse cursor icon) and "WinAuto" (with a robot icon). To the right of these buttons are four small icons: a Linux penguin, an Apple logo, a Windows logo, and a Docker whale. Below the toolbar, there is a light blue informational bar with a question mark icon and the text "Comando para mover mouse por coordenadas". Underneath this bar, the label "Coordenadas:" is followed by a text input field containing the value "150,310". At the bottom right of the window, there are two buttons: "Agregar Comando" (blue) and "Cancelar" (gray).

4. Scroll

Para usar el método scroll de mouse de pywinauto, indicar lo siguiente:

- **Coordenadas:**Coordenadas a donde se quiere hacer scroll
- **Vueltas:** Vueltas de la rueda del mouse que se desea simular



The screenshot shows a window titled "Robot: dev" with a close button (X) in the top right corner. Below the title bar, there is a toolbar with two buttons: "Scroll" (with a mouse wheel icon) and "WinAuto" (with a robot icon). To the right of these buttons are four small icons: a Linux penguin, an Apple logo, a Windows logo, and a Docker whale. Below the toolbar, there is a light blue informational bar with a question mark icon and the text "Comando para scroll por coordenadas". Underneath this bar, the label "Coordenadas:" is followed by a text input field containing the value "150,310". Below that, the label "Vueltas:" is followed by a text input field containing the value "3". At the bottom right of the window, there are two buttons: "Agregar Comando" (blue) and "Cancelar" (gray).