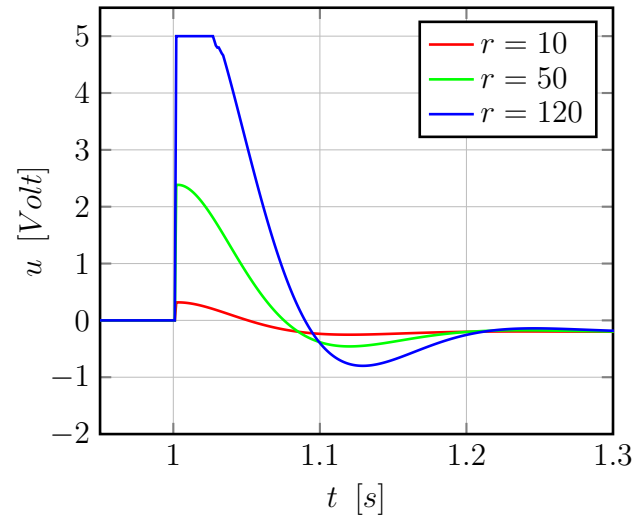


Ingressi di controllo per $d = 0.2$ Uscite del motore per $d = 0.2$ 