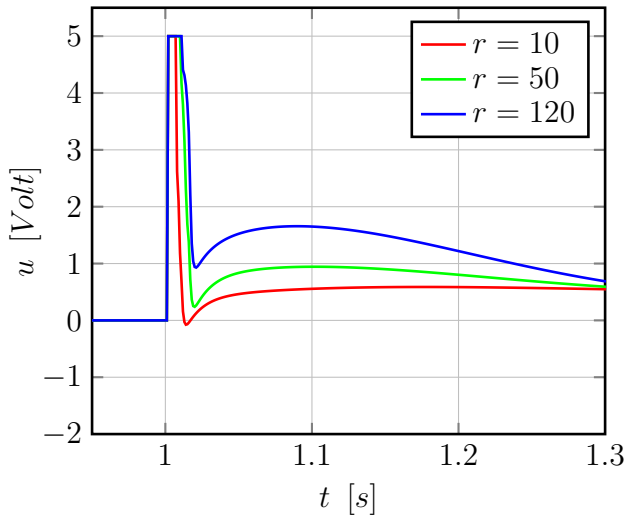


Ingressi di controllo per  $d = -0.5$ Uscite del motore per  $d = -0.5$ 