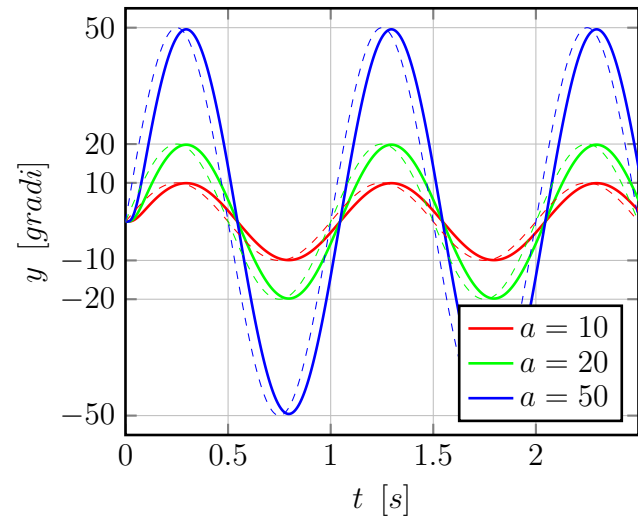


Uscite per $T_0 = 1$ [sec] con controllo integrale



Uscite per $T_0 = 1$ [sec] con modello interno

