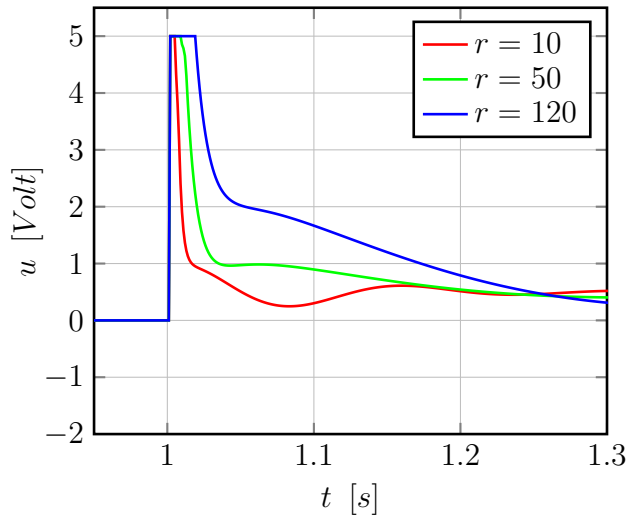


Ingressi di controllo per $d = -0.5$ Uscite del motore per $d = -0.5$ 