

浙江大学爱丁堡大学联合学院 ZJU-UoE Institute

Geometric image transformations

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Learning objectives

- Describe use cases for geometric transformations of images
- Use Python to crop images (in 2 or more dimensions)
- Explain the theory of affine transformations
- Implement basic transformations in Python (translation, scaling, rotation)



Outline

A brief recap

Geometric image transformations

Cropping

Translation

Rotations

Scaling

Python tools for image processing

Last time we learnt how to open and display images using Python.





Specific functions for image manipulation



Reading images as Numpy arrays

matpl tlib

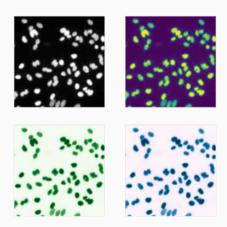
```
import matplotlib.pyplot as plt
img = plt.imread("cells.jpg")
plt.imshow(img)
plt.show()
```



```
from skimage import io
img = io.imread("cells.jpg")
io.imshow(img)
io.show()
```

Colour mapping

```
fig, ax = plt.subplots(ncols=2, nrows=2)
ax[0, 0].imshow(img, "gray")
ax[0, 1].imshow(img, "viridis")
ax[1, 0].imshow(img, "Greens")
ax[1, 1].imshow(img, "PuBu")
```



Check out the Matplotlib website for a list of colourmaps! https://matplotlib.org/stable/tutorials/colors/colormaps.html

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Geometric image transformations

Geometric image transformations are operations that change the image geometry without altering its pixel values (mostly...).

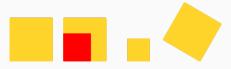
Examples are cropping, translating, scaling rotating an image.

Geometric image transformations

Geometric image transformations are operations that change the image geometry without altering its pixel values (mostly...).

Examples are cropping, translating, scaling rotating an image. Example use cases:

- · Analysing only part of an image (cropping)
- Making sure all input images for a pipeline are the same size (scaling, cropping)
- Aligning multiple images (e.g. in video stabilization) (rotating, translating)
- ...



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Translation

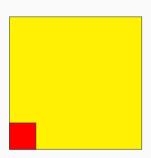
Rotations

Scaling

Cropping

Cropping is as easy as subsetting the image matrix.

```
# img contains a 512 x 512 image
# Take the top-left 100 x 100 pixels
img1 = img[0:100, 0:100] # shape (100, 100)
```

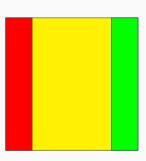


Cropping

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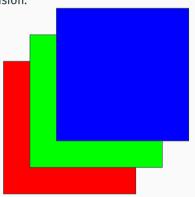
# A 100 pixel wide strip on the left...
img2 = img[:, 0:100] # shape (512, 100)
# ...or on the right!
img3 = img[:, -100:] # shape (512, 100)
```



Cropping in more than two dimensions

Since images are just tensors, we can crop them in any dimension.

```
# img is a 512 x 512 RGB image
# img.shape is (3, 512, 512)
# Extract the green channel
img_green = img[1] # Shape (512, 512)
```

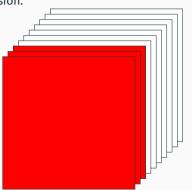


Cropping in more than two dimensions

Since images are just tensors, we can crop them in any dimension.

```
# img is a 512 x 512 RGB image
# img.shape is (3, 512, 512)
# Extract the green channel
img_green = img[1] # Shape (512, 512)

# video is a 512 x 512 video of 300 frames
# video.shape is (300, 512, 512)
# Take the first 50 frames
video_crop = video[0:50]
```



Question time

We have a 100 frames video of a 512 x 512 z-stack with 60 planes loaded in zstack.

zstack.shape is (100, 60, 512, 512)

What does this code give you?

result = stack[50:70, :, 100:300]



Affine transformations

In Euclidean geometry, an affine transformation is a geometric transformation that preserves lines and parallelism but not necessarily distances and angles. [Wikipedia]



We want to transform P(x; y) into P'(x'; y').

$$P':\begin{cases} x'=f(x,y)+a\\ y'=f(x,y)+b \end{cases}$$

where f is a linear function

Affine transformations

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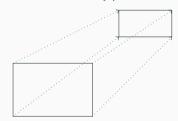


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We can generalise this to an image, by applying the transformation to every pixel.



Affine transformations

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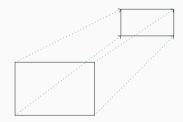
We want to transform P(x; y) into P'(x'; y').

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where f is a linear function

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \mathbf{A} \begin{bmatrix} x \\ y \end{bmatrix} + \mathbf{B} \qquad \mathbf{A} = \begin{bmatrix} a_{00} & a_{01} \\ a_{10} & a_{11} \end{bmatrix}; \ \mathbf{B} = \begin{bmatrix} b_{00} \\ b_{10} \end{bmatrix}$$

We can generalise this to an image, by applying the transformation to every pixel.



The transformation matrix

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This can be combined into*

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} a_{00} & a_{01} & b_{00} \\ a_{10} & a_{11} & b_{10} \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

This is the transformation matrix.

^{*} Don't remember how matrix multiplication works? Check out Wikipedia!

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Transformation matrices are easily created using the skimage.transform.SimilarityTransform function.

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Translation

To translate we offset the points by (t_x, t_y) : $\begin{cases} x' = x + t_x \\ y' = y + t_y \end{cases}$

The translation matrix is: $\begin{bmatrix} 1 & 0 & t_x \\ 0 & 1 & t_y \\ 0 & 0 & 1 \end{bmatrix}$

Translation

To translate we offset the points by (t_x, t_y) : $\begin{cases} x' = x + t_x \\ y' = y + t_y \end{cases}$

The translation matrix is: $\begin{bmatrix} 1 & O & t_x \\ O & 1 & t_y \\ O & O & 1 \end{bmatrix}$

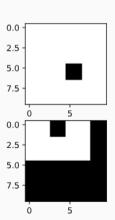
```
from skimage.transform import SimilarityTransform, warp
m = SimilarityTransform(translate = (2, 5))
img = np.ones(shape=(10, 10))
img[5:7, 5:7] = 0
img_translated = warp(img, m)
```

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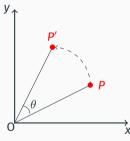
Cropping

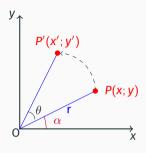
Translation

Rotations

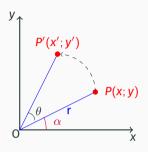
Scaling

We want to rotate a point P(x, y) around the origin by an angle θ to get P'(x', y').





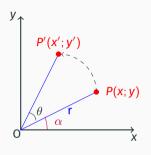
$$P: \begin{cases} x = r\cos(\alpha) \\ y = r\sin(\alpha) \end{cases} \quad P': \begin{cases} x' = r\cos(\alpha + \theta) \\ y' = r\sin(\alpha + \theta) \end{cases}$$



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$$P': \begin{cases} x' = r\cos(\alpha)\cos(\theta) - r\sin(\alpha)\sin(\theta) \\ y' = r\sin(\alpha)\cos(\theta) + r\sin(\theta)\cos(\alpha) \end{cases}$$

Why? Wikipedia to the rescue!

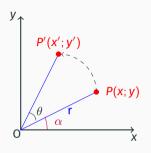


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$$P':\begin{cases} x' = x\cos(\theta) - y\sin(\theta) \\ y' = y\cos(\theta) + x\sin(\theta) \end{cases}$$



Thus:

$$P: \begin{cases} x = r\cos(\alpha) \\ y = r\sin(\alpha) \end{cases} \quad P': \begin{cases} x' = r\cos(\alpha + \theta) \\ y' = r\sin(\alpha + \theta) \end{cases}$$

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Why? Wikipedia to the rescue!

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

Transformation (rotation) matrix

Rotating in Scikit Image

To rotate an image we will:

- Offset our image so that it is centered on the origin
- · Generate a rotation matrix
- Multiply the coordinates of each pixel by the rotation matrix

Rotating in Scikit Image

To rotate an image we will:

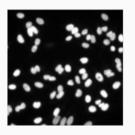
- Offset our image so that it is centered on the origin
- · Generate a rotation matrix
- Multiply the coordinates of each pixel by the rotation matrix

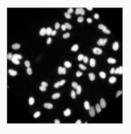
Luckily, Scikit Image has a ready function for that, skimage.transform.rotate.

```
import matplotlib.pyplot as plt
from skimage.transform import rotate

img = plt.imread("cells.jpg")
img_rotated = rotate(img, 20)

plt.imshow(img_rotated, cmap="gray")
plt.show()
```





Note: we lost part of the image and we "gained" black pixels around it.

Optional exercise - want to try by yourself?

It might be interesting to try to code image rotation by yourself.

Hints:

- Generate the transformation matrices using skimage.transform.SimilarityTransform
- You will need three matrices: one translation matrix to offset your image by (-xcenter,
 -ycenter); a rotation matrix to rotate your image around (o, o); and finally another translation
 matrix to translate your image back to its original position.
- You can combine the matrices as m1+m2+m3
- You can use skimage.transform.warp to apply the combined transformation matrix to your image.

Are there any differences between your result and the results from rotate?

If you are stuck, try to look at the source code for rotate!

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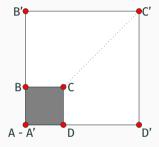
Cropping

Translation

Rotations

Scaling

Scaling

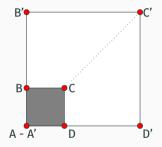


Scaling transforms the coordinates as:

$$\begin{cases} x' = s_x * x \\ y' = s_y * y \end{cases}$$

$$\begin{cases} x' = s_x * x \\ y' = s_y * y \end{cases}$$
 Transformation matrix =
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Scaling



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 $\begin{cases} x' = s_x * x \\ y' = s_y * y \end{cases}$ $Transformation matrix = \begin{bmatrix} s_x & o & o \\ o & s_y & o \\ o & o & 1 \end{bmatrix}$

from skimage.transform import SimilarityTransform m = SimilarityTransform(scale = (2, 3))

Scaling



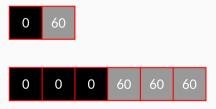
Two problems:

When **upscaling** we need to generate new information. When **downscaling** we need to decide "how to lose" information.

Interpolation is the solution!

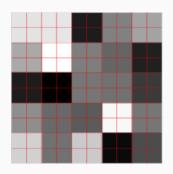
Nearest-neighbour interpolation

The simplest way to resize an image is to use nearest-neighbour interpolation. Each pixel of the scaled image will have the colour of the nearest pixel in the original image. In this "1D" example, we resize a 1x2 image to 1x6



Nearest-neighbour interpolation

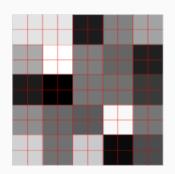




Upscaling of a 5x5 image by a factor of 2, to get a 10x10 image, with nearest neighbour interpolation

Nearest-neighbour interpolation





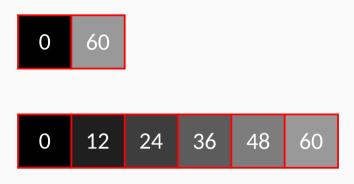
Upscaling of a 5x5 image by a factor of 2, to get a 10x10 image, with nearest neighbour interpolation

from skimage.transform import rescale
img_scaled = rescale(img, 2, order=0)

Scaling with interpolation

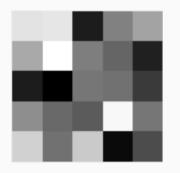
Better ways to scale an image involve changing the pixel values of the rescaled image based on their neighbourhood.

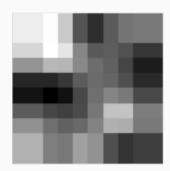
For example we could use linear interpolation



Linear interpolation

The same applies in 2D, although we need to take into accounts the values of both horizontal and vertical neighbours (bilinear interpolation).

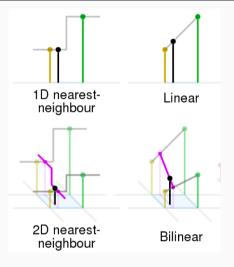




Upscaling of a 5x5 image by a factor of 2, to get a 10x10 image, with bi-linear interpolation

```
from skimage.transform import rescale
img_scaled = rescale(img, 2, order=1)
```

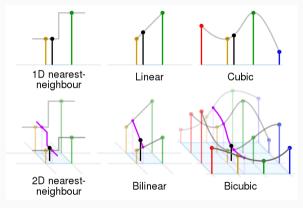
Nearest neighbour vs linear interpolation



Comparison of nearest neighbour and linear interpolation - Source: Wikipedia

Higher orders of interpolation

We can use higher orders of interpolation to produce smoother results.



Comparison of nearest neighbour and linear interpolation - Source: Wikipedia

Scikit Image supports values from 0 to 5 in the order parameter of the rescale function. O is nearest neighbour, 1 is bi-linear, 2 is bi-quadratic and so on.

Scaling to a target size

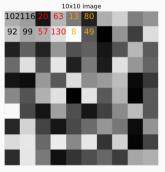
To scale to a target size, rather than by a specific factor, we can use resize instead of rescale.

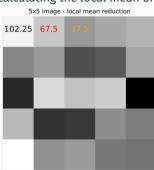
```
import matplotlib.pyplot as plt
from skimage.transform import resize, rescale

img = plt.imread("cells.jpg")
img_scaled1 = rescale(img, 2)
img_scaled2 = resize(img, (150, 150))
```

Local mean downscaling

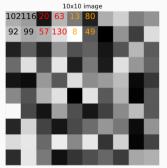
Another simple solution for downscaling is calculating the local mean of each pixel

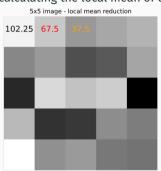




Local mean downscaling

Another simple solution for downscaling is calculating the local mean of each pixel





```
from skimage.transform import downscale_local_mean
img_small = downscale_local_mean(img, (2,2))
```

Image needs to be padded if the size is not a multiple of the downscaling factor. This method is fast but not good at keeping fine details.

Scaling summary

skimage.transform.rescale \rightarrow scales an image by a specific factor (>1 upscaling; <1 downscaling.). Can specify a different scaling factor for each dimension of the image.

 $\mathtt{skimage.transform.resize} \rightarrow \mathtt{scales} \ \mathtt{animage} \ \mathtt{to} \ \mathtt{a} \ \mathtt{target} \ \mathtt{size}.$

 ${\tt skimage.transform.downscale_local_mean} \rightarrow {\tt downscales} \ the \ image \ by \ a \ specific \ factor \ (>1), \\ using \ the \ local \ mean \ of \ each \ pixel.$

Summary

- Affine transformations are simple yet powerful way to modify an image.
- Scikit Image allows generation of any transformation matrix...
- ... but also provides several pre-made functions for rotating, scaling, etc
- Workshop 1 will allow you to practice what learned so far!