

Info 251: Applied Machine Learning
Lab 9
4/1/2020

Topics

- ▶ Support Vector Machines (SVM)
- ▶ Decision Trees
- ▶ Random Forests
- ▶ Neural Networks (next lab...)

SVM

- ▶ Dataset of N pairs x_i, y_i with $y_i \in \{-1, 1\}$ and $x_i \in \mathbb{R}^n$
- ▶ Classifier function $f(x) = \text{sign}(w^T x + b) \in \{-1, 1\}$
- ▶ Intuition: In logistic regression we classify with
$$g(w) = \frac{1}{1+e^{-b-w^T x}}$$
- ▶ The higher the value of $w^T x$ the more confident we are that label is 1 and the lower the more likely that the label is -1 .

SVM

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- ▶ Classifier function $f(x) = \text{sign}(w^T x + b)$
- ▶ Solve:

$$\begin{aligned} & \max_{w,b} \quad \alpha \\ \text{s.t.} \quad & w^T x_i + b \geq \alpha \text{ if } y_i = 1 \\ & w^T x_i + b \leq -\alpha \text{ if } y_i = -1 \\ & \|w\|_2 = 1 \end{aligned} \tag{1}$$

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- ▶ Classifier function $f(x) = \text{sign}(w^T x + b)$
- ▶ Solve:

$$\max_{w,b} \alpha$$

$$\text{s.t. } y_i(w^T x_i + b) \geq \alpha \quad i = 1, \dots, N \quad \textcolor{red}{Why?}$$

$$\|w\|_2 = 1$$

SVM

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- ▶ Solve:

$$\max_{w,b} \quad \alpha$$

$$\text{s.t.} \quad y_i(w^T x_i + b) \geq \alpha \quad i = 1, \dots, N$$
$$||w||_2 = 1 \quad \text{non-convex : (}$$

SVM

Let $\hat{\alpha} = \alpha \|\mathbf{w}\|_2$ equivalent problem

$$\begin{aligned} & \max_{\mathbf{w}, b} \quad \frac{\hat{\alpha}}{\|\mathbf{w}\|_2} \\ \text{s.t.} \quad & y_i(\mathbf{w}^T \mathbf{x}_i + b) \geq \hat{\alpha} \quad i = 1, \dots, N \end{aligned}$$

SVM

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$$\begin{aligned} & \max_{\mathbf{w}, b} \quad \frac{\hat{\alpha}}{\|\mathbf{w}\|_2} \\ \text{s.t.} \quad & y_i(\mathbf{w}^T \mathbf{x}_i + b) \geq \hat{\alpha} \quad i = 1, \dots, N \end{aligned}$$

\mathbf{w} and b can be scaled arbitrarily so

$$\begin{aligned} & \max_{\mathbf{w}, b} \quad \frac{1}{\|\mathbf{w}\|_2} \\ \text{s.t.} \quad & y_i(\mathbf{w}^T \mathbf{x}_i + b) \geq 1 \quad i = 1, \dots, N \end{aligned}$$

SVM

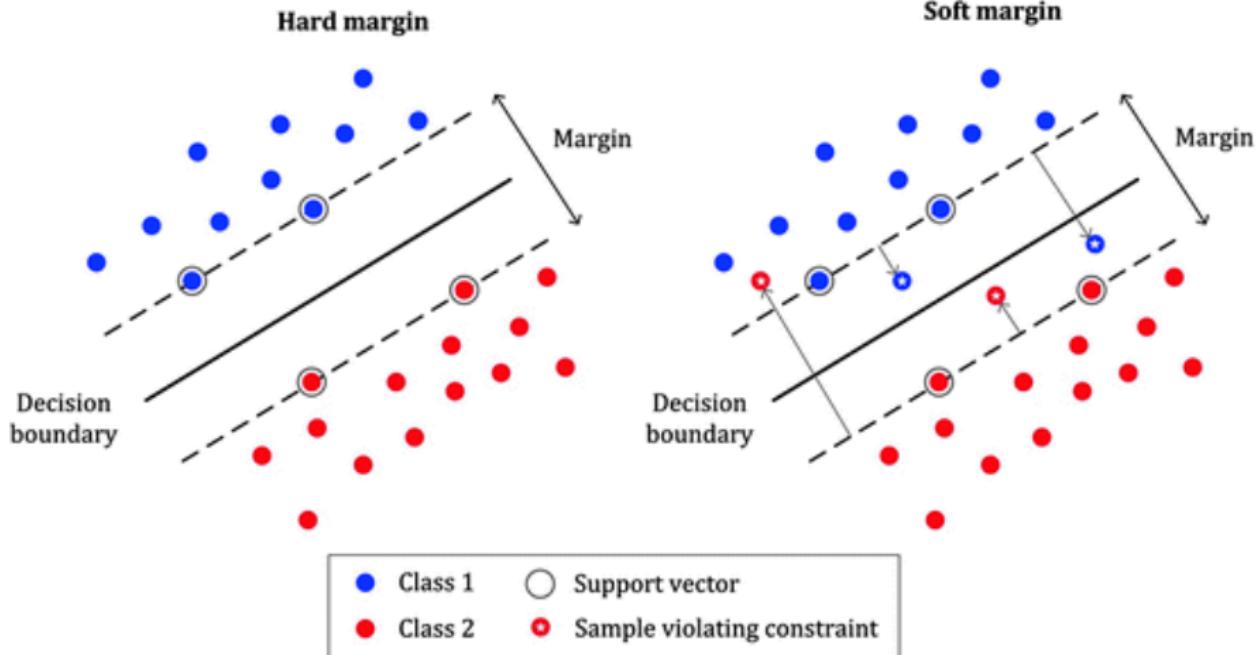
- ▶ Support vector machine optimization formulation

$$\min_{w,b} ||w||_2$$

$$\text{s.t. } y_i(w^T x_i + b) \geq 1 \quad i = 1, \dots, N$$

SVM

- If data not linear separable?



Soft Margin SVM

- ▶ Support vector machine optimization formulation

$$\begin{aligned} \min_{w,b,\xi_i} \quad & ||w||_2 + C \sum_{i=1}^n \xi_i \\ \text{s.t.} \quad & y_i(w^T x_i + b) \geq 1 - \xi_i, \quad \xi_i \geq 0 \quad i = 1, \dots, N \end{aligned}$$

- ▶ 1-norm soft margin SVM
- ▶ Do we need to normalize our data?

SVM Pros and Cons

Pros

- ▶ Scales relatively well to high dimensions
- ▶ In practice, they tend to over-fit less

Cons

- ▶ Not suitable for large data sets
- ▶ No probabilistic explanation for the classification
- ▶ Don't perform very well, when classes overlap

Decision Trees

- ▶ SVMs are linear classifiers
- ▶ Check link in notebook for generalization of SVMs in nonlinear settings

Decision Trees

- ▶ SVMs are linear classifiers
- ▶ Check link in notebook for generalization of SVMs in nonlinear settings
- ▶ Decision trees **Classification or Regression?**

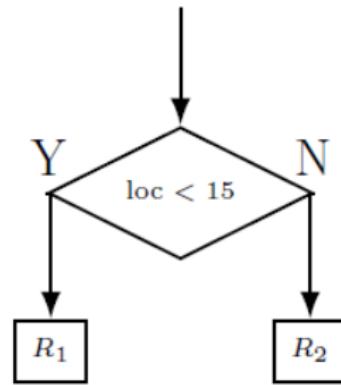
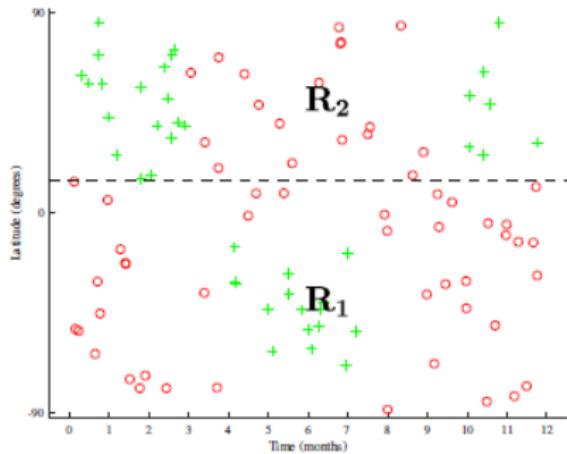
Decision Trees

- ▶ SVMs are linear classifiers
- ▶ Check link in notebook for generalization of SVMs in nonlinear settings
- ▶ Decision trees Classification or Regression?
- ▶ Decision trees Linear or Non-linear?

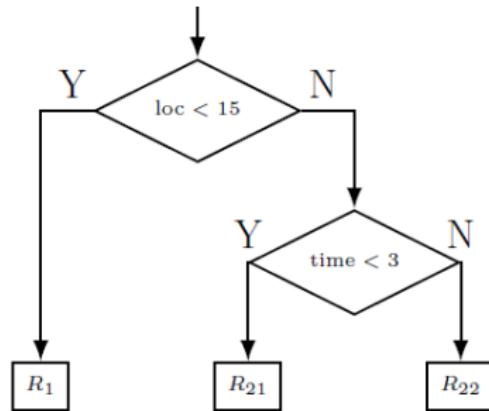
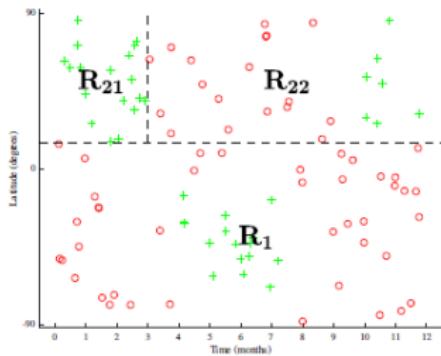
Decision Trees (Example)

- ▶ Assume we want to predict given a time and a location whether or not skiing is possible
- ▶ Features: latitude (-90 to 90 degrees) and time of the year (month)

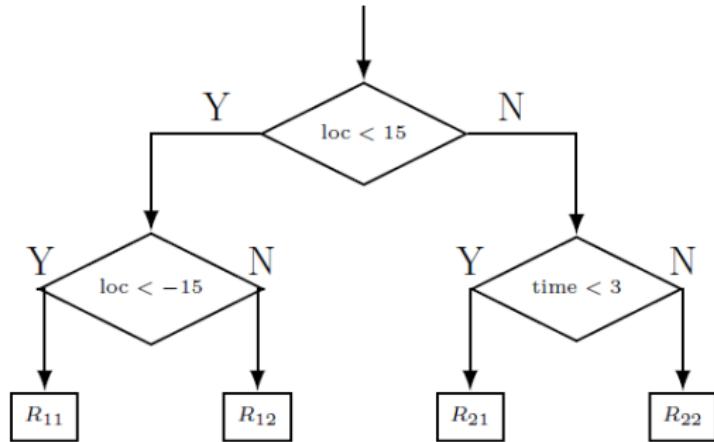
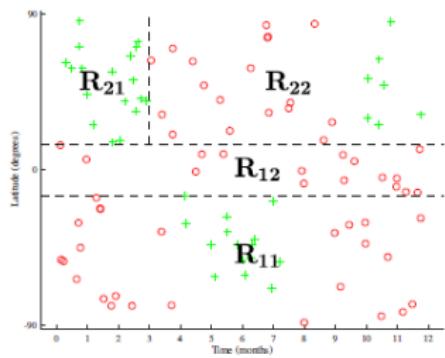
Decision Trees (Example)



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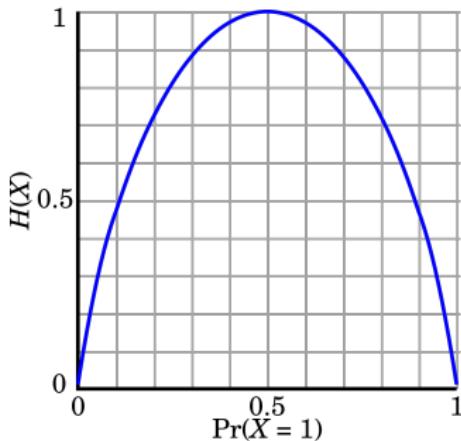


Decision Trees

- ▶ Optimal regions is an intractable problem
- ▶ Instead greedy recursive-partitioning
- ▶ How split node?
- ▶ Choose split with maximum information gain
- ▶ Feature normalization?

Decision Trees

- ▶ entropy $H = - \sum p_i \log_2(p_i)$
- ▶ $H = -p \log_2(p) - (1-p) \log_2(1-p)$
- ▶ Information gain is the entropy of parent node minus weighted entropies of children



Information Gain (Example)

$$E(S) = \sum_{i=1}^c -p_i \log_2 p_i$$

| Play Golf | |
|-----------|----|
| Yes | No |
| 9 | 5 |



$$\begin{aligned}\text{Entropy(PlayGolf)} &= \text{Entropy}(5,9) \\ &= \text{Entropy}(0.36, 0.64) \\ &= -(0.36 \log_2 0.36) - (0.64 \log_2 0.64) \\ &= 0.94\end{aligned}$$

Information Gain (Example)

$$E(T, X) = \sum_{c \in X} P(c)E(c)$$

| | | Play Golf | | |
|---------|----------|-----------|----|----|
| | | Yes | No | |
| Outlook | Sunny | 3 | 2 | 5 |
| | Overcast | 4 | 0 | 4 |
| | Rainy | 2 | 3 | 5 |
| | | | | 14 |



$$\begin{aligned} E(\text{PlayGolf}, \text{Outlook}) &= P(\text{Sunny}) * E(3,2) + P(\text{Overcast}) * E(4,0) + P(\text{Rainy}) * E(2,3) \\ &= (5/14) * 0.971 + (4/14) * 0.0 + (5/14) * 0.971 \\ &= 0.693 \end{aligned}$$

Information Gain (Example)

| | | Play Golf | |
|--------------|----------|-----------|----|
| | | Yes | No |
| Outlook | Sunny | 3 | 2 |
| | Overcast | 4 | 0 |
| | Rainy | 2 | 3 |
| Gain = 0.247 | | | |

| | | Play Golf | |
|--------------|------|-----------|----|
| | | Yes | No |
| Temp. | Hot | 2 | 2 |
| | Mild | 4 | 2 |
| | Cool | 3 | 1 |
| Gain = 0.029 | | | |

| | | Play Golf | |
|--------------|--------|-----------|----|
| | | Yes | No |
| Humidity | High | 3 | 4 |
| | Normal | 6 | 1 |
| Gain = 0.152 | | | |

| | | Play Golf | |
|--------------|-------|-----------|----|
| | | Yes | No |
| Windy | False | 6 | 2 |
| | True | 3 | 3 |
| Gain = 0.048 | | | |

Decision Trees

- ▶ Possible to keep splitting until all training points are classified correctly (over-fitting)
- ▶ We want the smallest tree that explains the data

Decision Trees

- ▶ Ways to avoid over-fitting
- ▶ Minimum Leaf Size – Do not split tree if its cardinality falls below a fixed threshold.
- ▶ Maximum Depth – Do not split R if more than a fixed threshold of splits were already taken to reach R.
- ▶ Maximum Number of Nodes – Stop if a tree has more than a fixed threshold of leaf nodes

- ▶ Tree pruning
- ▶ Pruning: After whole tree is generated compute significance level for each split (eg χ^2 "measures independence" between features)
- ▶ Starting from leaves delete split that has χ^2 score less than threshold
- ▶ Even simpler, starting from leaves delete a split if that makes performance on test set increase

DT Pros and Cons

Pros

- ▶ Simple to understand and interpret
- ▶ No normalization, little data processing

Cons

- ▶ Unstable as small changes in features can lead to very different trees
- ▶ Other methods usually perform better with similar data

Random Forests

- ▶ Train decision trees by sampling from data set with replacement
- ▶ Use all these models for prediction (bagging)
- ▶ Works better with uncorrelated models
- ▶ At each split use a random subset of the features ("feature bagging")

Random Forests

Pros

- ▶ Very good predictive performance
- ▶ Reliable feature importance estimate
- ▶ Stable

Cons

- ▶ Harder to interpret than a single DT
- ▶ Computationally more challenging