

Generación de entornos virtuales usando algoritmos estocásticos

Curso: MA4402 – Simulación estocástica: Teoría y laboratorio.

Profesor: Joaquín Fontbona T.

Auxiliares: Catalina Liana, Álvaro Márquez, Matías Ortiz.

Integrantes: Jose Badilla, Jorge Novoa.

Contexto

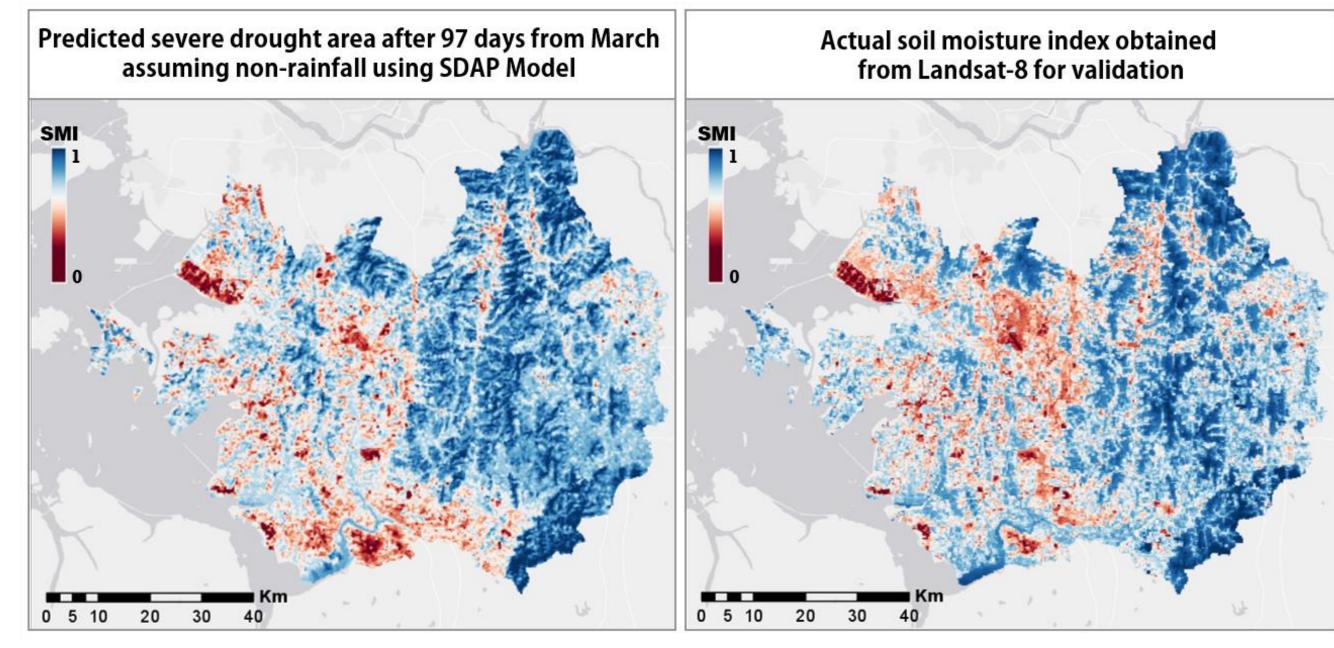
La simulación de entornos virtuales es un desafío multidisciplinario





Problemática:

La creación de entornos virtuales manualmente es caro, de manera que es necesario desarrollar alternativas que generen estos entornos para poder entrenar redes neuronales o poder generar contenido procedural:



Propuesta: Usar herramientas estocásticas conocidas

Cadenas de Markov

Simulated Annealing

Pseudocodigo de la Cadena de Markov:

```
función markov_chain_terrain(tamaño, iteraciones, transición_std):
terreno = initialize_terrain(tamaño)
por cada _ en rango(iteraciones):
   nuevo_terreno = copiar_matriz(terreno)
   por cada x en rango(1, tamaño-1):
     por cada y en rango(1, tamaño-1):
        vecindario = obtener_submatriz(terreno, x-1, x+2, y-1, y+2)
        nuevo_terreno[x, y] = promedio(vecindario) + normal_aleatoria(0, transición_std)
   terreno = nuevo_terreno
```

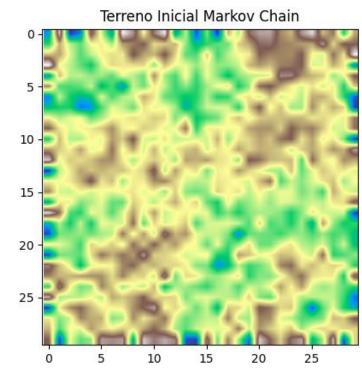
Funcion de costo en Simulated Annealing:

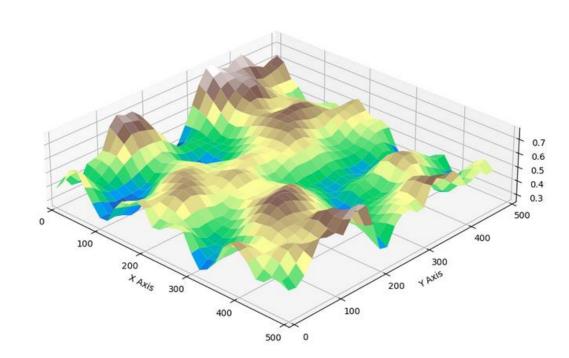
energía = Cohesion - elevación + promedio gradiente where:

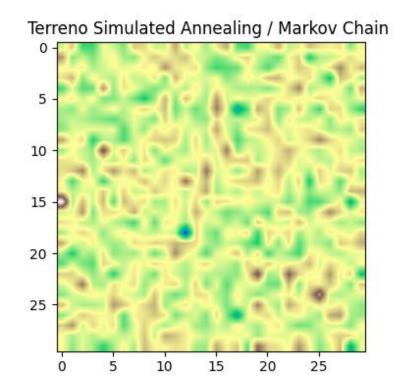
$$\begin{aligned} \text{Cohesion} &= \sum_{(i,j) \in [2,\mathbf{n}-1]^2} \sum_{(a,b) \in [\mathbf{i}-1,\mathbf{i}+1] \times [\mathbf{j}-1,\mathbf{j}-1]/(\mathbf{i},\mathbf{j})} |(i,j)-(a,b)| \\ \text{elevation penalty} &= \max_{(i,j) \in [1,\mathbf{n}]^2} (\text{altura}(\mathbf{i},\mathbf{j})) - \min_{(i,j) \in [1,\mathbf{n}]^2} (\text{altura}(\mathbf{i},\mathbf{j})) \\ \text{promedio gradiente} &= \bar{E}(\nabla(matriz)) \end{aligned}$$

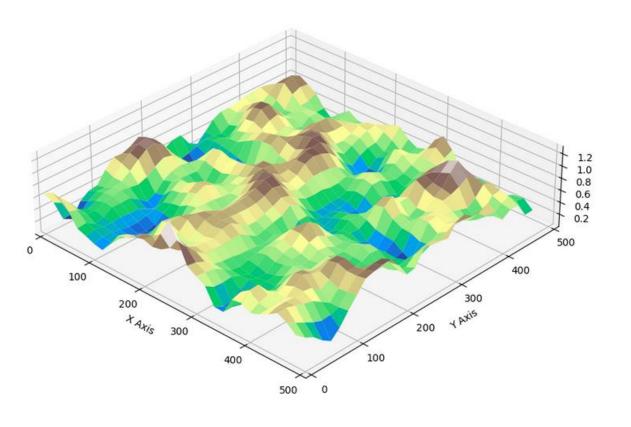
Resultados

Markov Chain

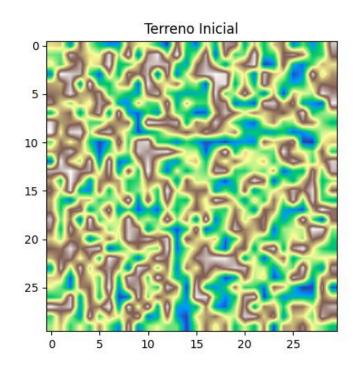


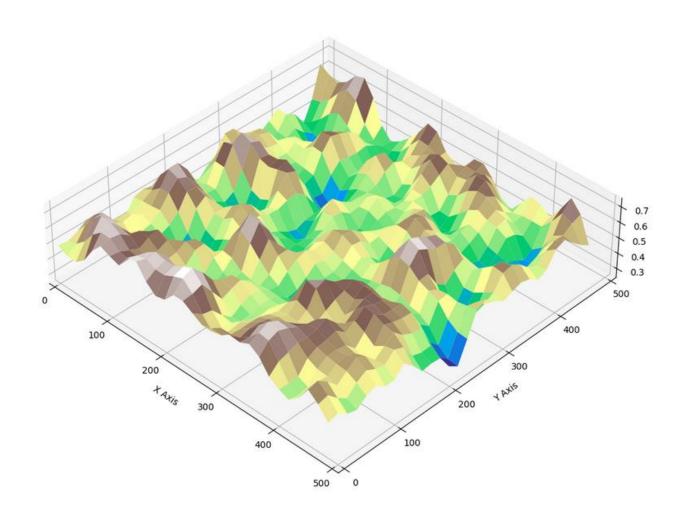


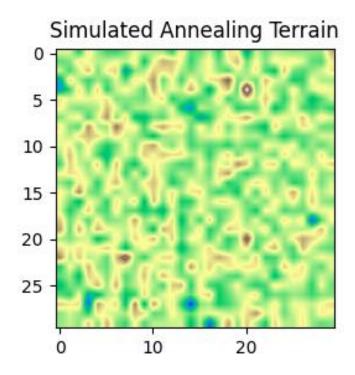


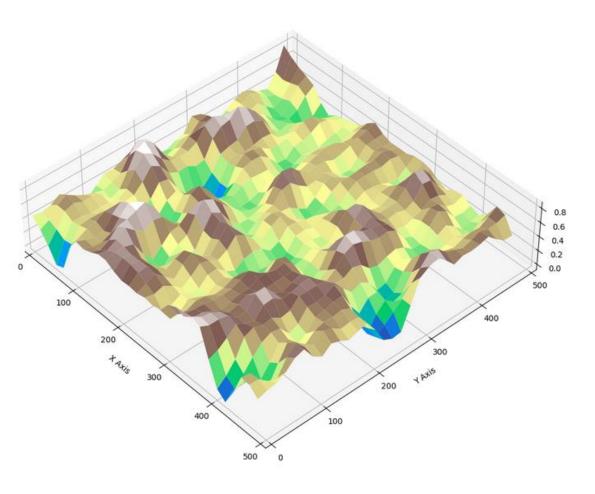


Simulated Annealing solo

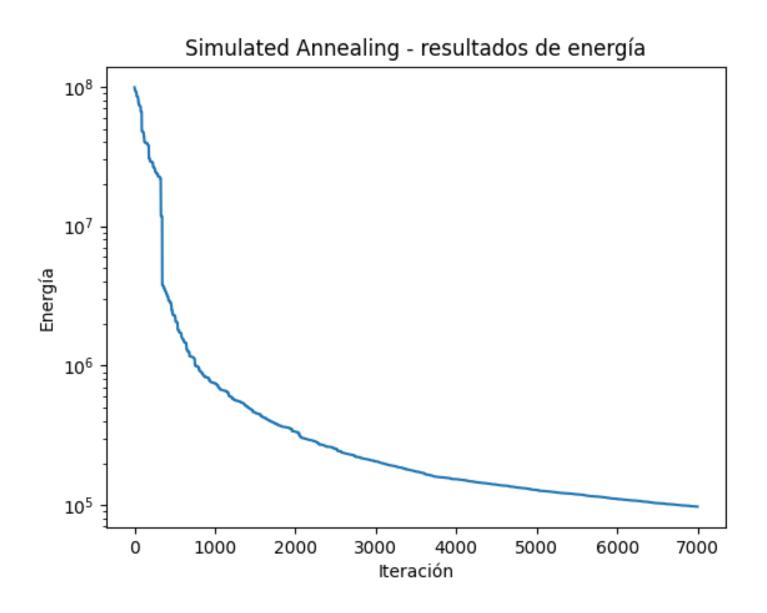




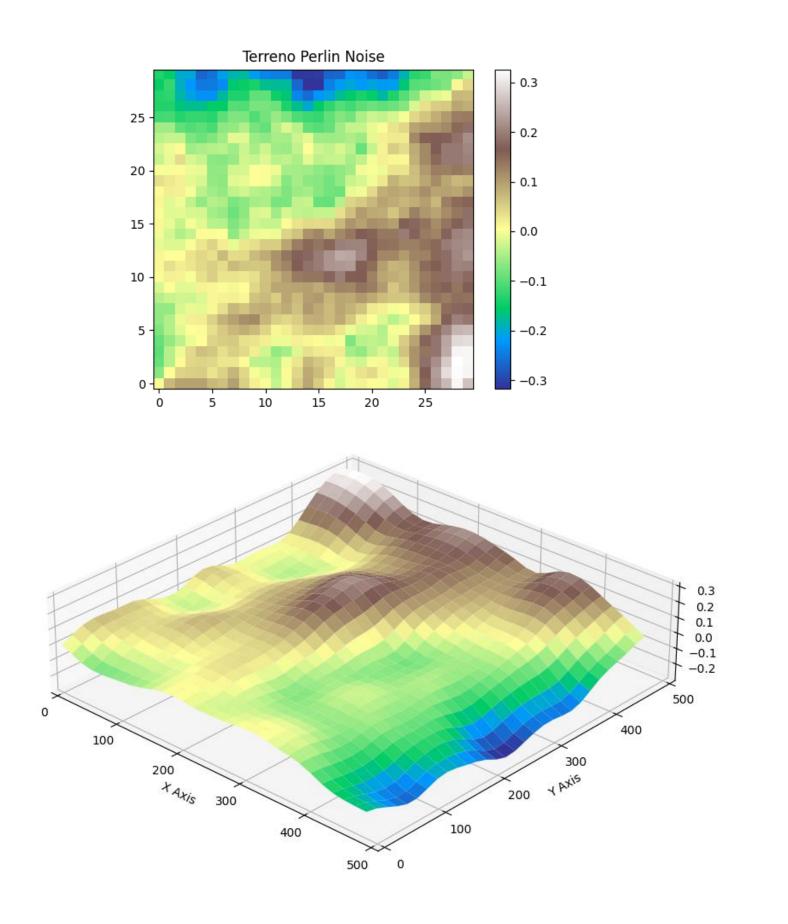


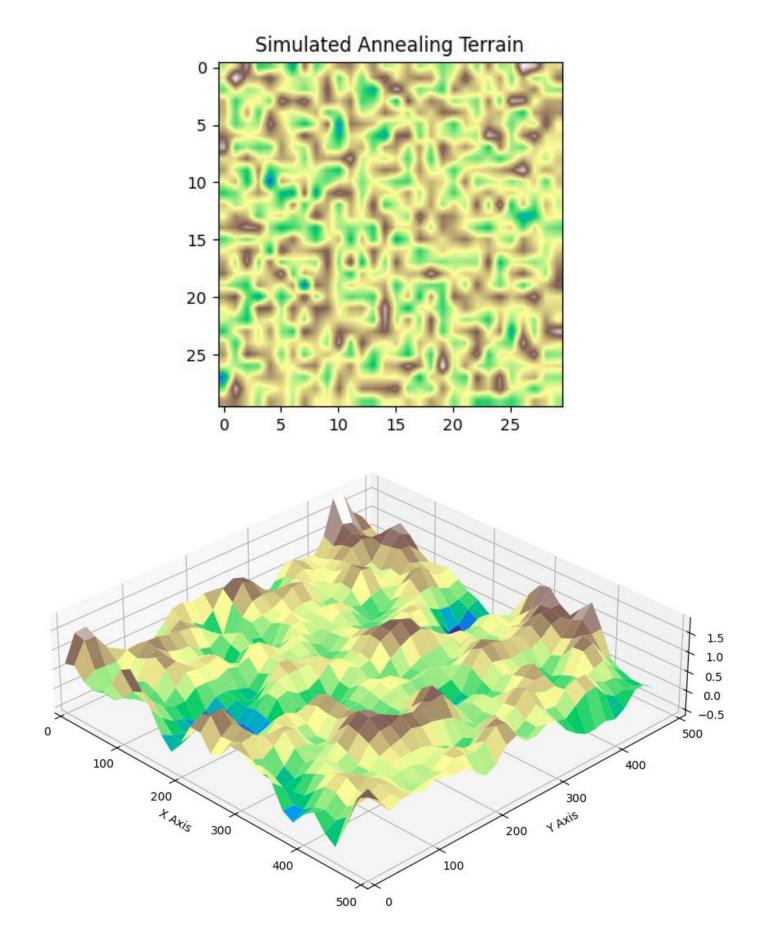


Simulated Annealing: Curva de minimización de energía

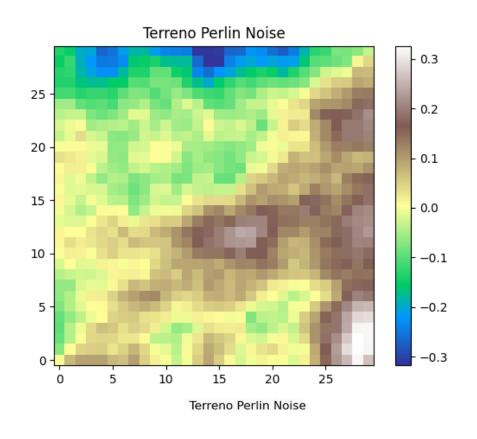


Comparación entre Simulated Annealing y Perlin Noise

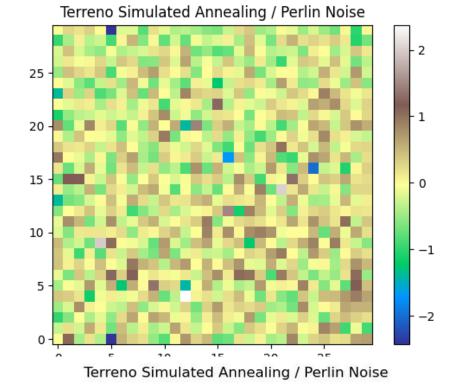




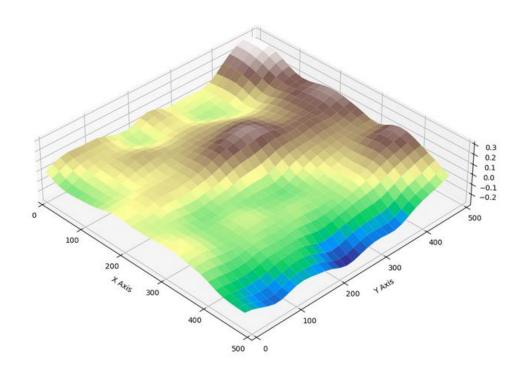
Metodología de Simulated Annealing sobre Perlin Noise



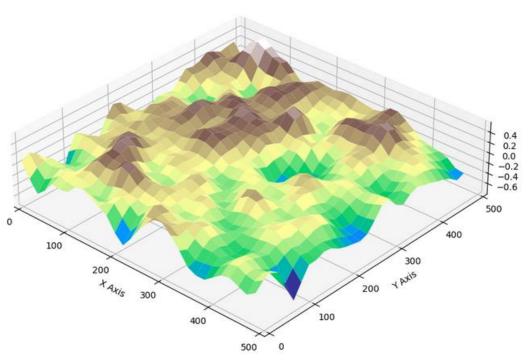


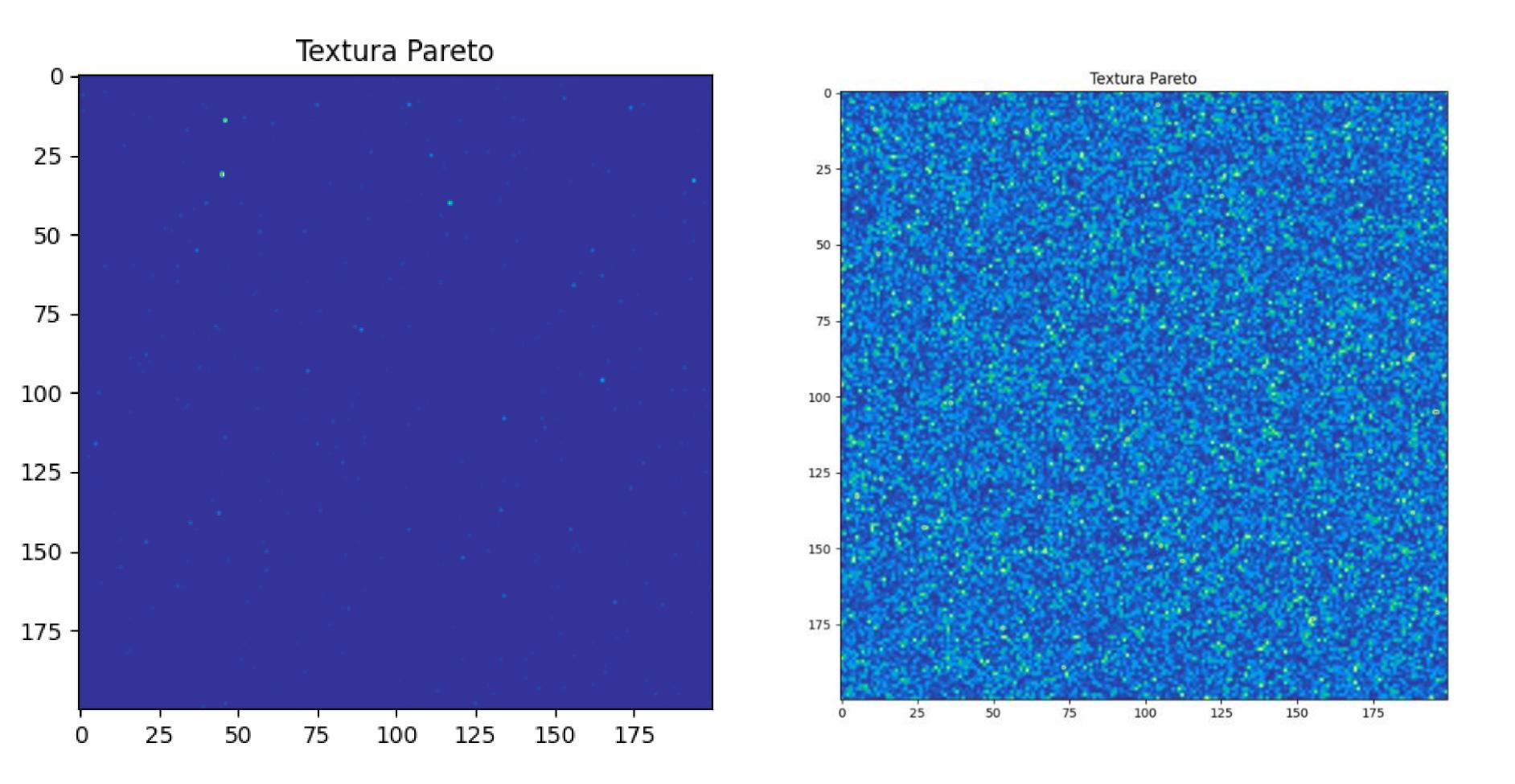


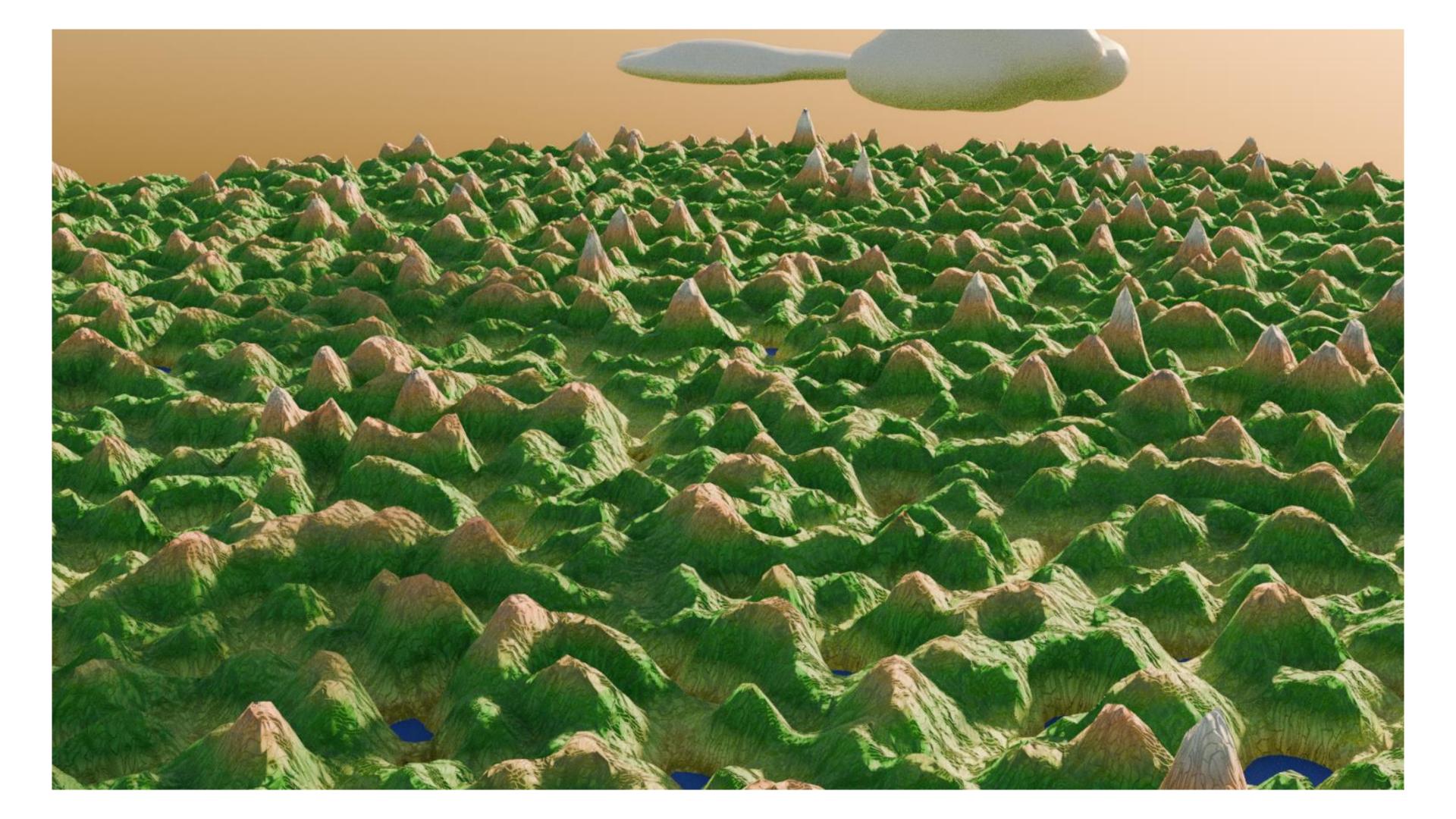














Conclusiones

- [1] Fundamentals of Terrain Generation. CMU School of Computer Science. (n.d.). https://www.cs.cmu.edu/112/notes/student-tp-guides/Terrain.pdf
- [2] Tuomo Hyttinen. Terrain synthesis using noise, MS thesis, 2017.
- [3] McDonald, N. M. (2019). Markov Chains for Procedural Buildings. Nick's blog. https://nickmcd.me/2019/10/30/markov-chains-for-procedural-buildings/

Muchas Gracias