

# Segment Tree

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[https://github.com/projetosufal/  
data-structures-project](https://github.com/projetosufal/data-structures-project)

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Intro

Segment tree

Operations

Peek: Segtree as  
a base for  
advanced  
algorithms

Conclusion

# Outline

- 1 Intro
- 2 Segment tree
- 3 Operations
- 4 Peek: Segtree as a base for advanced algorithms
- 5 Conclusion

# Stock Exchange

## The problem

- Data from thousands of companies worldwide, active for decades
- Usage of multiple operations requiring a range/interval of data in any capacity
- Resources are not infinite, must be optimized as best as possible

$O(n)$  operations? No!



# Segment tree

## Intervals of a $A[6]$

### How it is structured?

- The Segtree is a binary tree that's represented from an array, where each node represents a unique interval or segment of the tree and stores a **specific** value.
- The value, is usually represented by *maximum*, *minimum* or *sum* of the segment.

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tree[0]	=	A[0:5]
tree[1]	=	A[0:2]
tree[2]	=	A[3:5]
tree[3]	=	A[0:1]
tree[4]	=	A[2:2]
tree[5]	=	A[3:4]
tree[6]	=	A[5:5]
tree[7]	=	A[0:0]
tree[8]	=	A[1:1]
tree[9]	=	NULL
tree[10]	=	NULL
tree[11]	=	A[3:3]
tree[12]	=	A[4:4]

---

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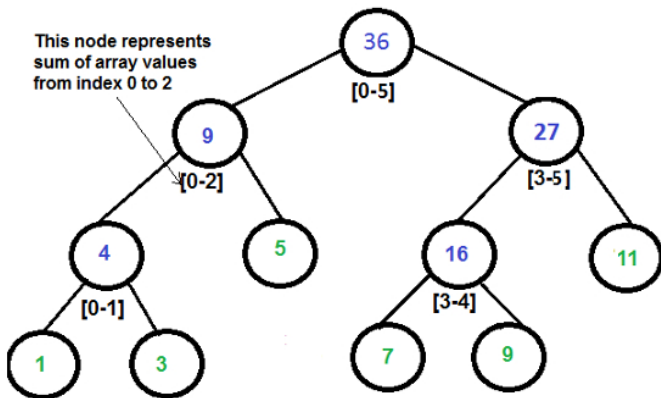
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Segment Tree for input array {1, 3, 5, 7, 9, 11}

# Operations

## Building a tree

- $(n \log n)$  storage
- but only  $(2*n - 1)$  actual nodes

## Query - range search

- $O(\log n)$

## Updating a tree

- $O(\log n)$
- can modify any  $[l:r]$  section, than it will propagate updating dependencies

# Building a Segtree

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## Operations

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```
void
buildtree(int (*f)(int l_num, int r_num), int *v, int *tree,
          int *t_size, int node, int min, int max)
{
    int mid;

    if(min == max)
        tree[node] = v[min];

    else
    {
        mid = (min+max)/2;

        buildtree((*f), v, tree, t_size, 2*node + 1, min , mid);
        buildtree((*f), v, tree, t_size, 2*node + 2, mid + 1 , max);
        tree[node] = (*f)(tree[2*node + 1], tree[2*node + 2]);
    }
}
```

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```
int
query(int (*f)(int l_num, int r_num), int *tree,
      int node, int min, int max, int l, int r)
{
    if(r < min || max < l)
        return 0;

    if(l <= min && max <= r)
        return tree[node];

    int mid, l_bipod, r_bipod;
    mid = (min+max)/2;

    l_bipod = query((*f), tree, 2*node + 1, min , mid, l , r);
    r_bipod = query((*f), tree, 2*node + 2, mid + 1 , max, l, r);
    return ((*f)(l_bipod, r_bipod));
}
```



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```
void
updatetree(int (*f)(int l_num, int r_num), int *tree,
           int node, int min, int max, int l, int r, int val)
{
    int mid;
    if(min > max || min > r || max < l)
        return ;

    if(min == max)
    {
        tree[node] = val;
        return;
    }

    mid = (min+max)/2;

    updatetree((*f), tree, 2*node + 1, min , mid, l, r, val);
    updatetree((*f), tree, 2*node + 2, mid + 1 , max, l, r, val);

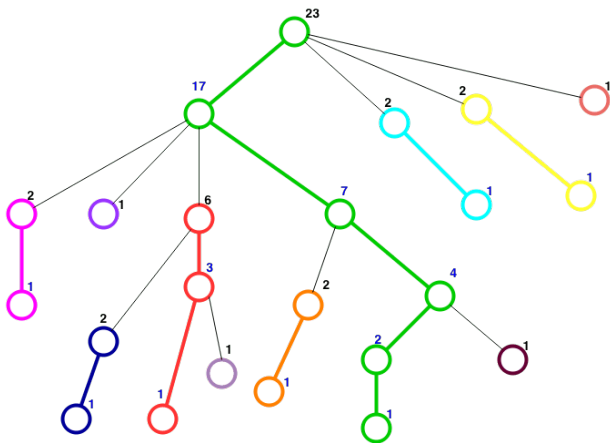
    tree[node] = (*f)(tree[2*node +1], tree[2*node + 2]);
}
```

# Segtree as a base for advanced algorithms

As seen, segtree is a flexible algorithm, such power can be used as a base for even more advanced algorithms, such as Heavy Light Decomposition

- HLD takes segtree to another new level, transforming linear paths of the graph into multiple segtrees

# Heavy Light Decomposition - a Segtree in graph



Each Chain is represented with different color.  
Thin Black lines represent the connecting edges. They connect 2 chains.

# Conclusion

the algorithm is better suited to solve problems of:

- analysis of big chunks of data
- reorganization and update of said data

And these properties are highly applicable in fields of stock market, weather analysis and competitive programming alike