

$$|R^i\rangle = \frac{iZ}{k_0} |G|j^i\rangle$$

$$\langle j^i | |G|j^i \rangle$$

obj: $0.5 \cdot \text{Im}\{\langle R^i | T \rangle\} + \mathcal{L}_{\text{vac}}$ only take the real part

constraints: $\text{Re}\{\langle R^i | P | T \rangle\} - \langle T | [P(X^{-1\dagger} - G_0^+)]^S | T \rangle = 0$

$\text{Im}\{\langle R^i | P | T \rangle\} - \langle T | [P(X^{-1\dagger} - G_0^+)]^A | T \rangle = 0$

$$\mathcal{L} = \text{Im}\{\langle R^i | T \rangle\} + \mathcal{L}_{\text{vac}} + \lambda_1 [\text{Re}\{\langle R^i | P | T \rangle\} - \langle T | [P(X^{-1\dagger} - G_0^+)]^S | T \rangle] + \lambda_2 [\text{Im}\{\langle R^i | P | T \rangle\} - \langle T | [P(X^{-1\dagger} - G_0^+)]^A | T \rangle]$$

$$= \frac{\langle R^i | T \rangle - \langle T | R^i \rangle}{2j} + \mathcal{L}_{\text{vac}} + \lambda_1 \left[\frac{\langle R^i | P | T \rangle + \langle T | P | R^i \rangle}{2} - 2 \langle T | [P(X^{-1\dagger} - G_0^+)]^S | T \rangle \right] + \lambda_2 \left[\frac{\langle R^i | P | T \rangle - \langle T | P | R^i \rangle}{2j} - 2 \langle T | [P(X^{-1\dagger} - G_0^+)]^A | T \rangle \right]$$

$$\frac{\partial \mathcal{L}}{\partial T} = -\frac{|R^i\rangle}{2j} + \lambda_1 \left[\frac{P|R^i\rangle}{2} - 2(P(X^{-1\dagger} - G_0^+))^S |T\rangle \right] + \lambda_2 \left[\frac{P|R^i\rangle}{2j} - 2(P(X^{-1\dagger} - G_0^+))^A |T\rangle \right] = 0$$

$$\underbrace{\left[(P(X^{-1\dagger} - G_0^+))^S + (P(X^{-1\dagger} - G_0^+))^A \right] |T\rangle}_A = -\underbrace{\frac{|R^i\rangle}{4j} + \lambda_1 \frac{P|R^i\rangle}{4} + \lambda_2 \frac{P|R^i\rangle}{4j}}_B$$