2 Overview of Supervised Learning

framework

 $X \in \mathbb{R}^p$: Random vector input

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Y \in \mathbb{R}: Random variable to predict
f(X): function we seek to predict Y
L(Y, f(X)): Loss function to penalize error in prediction
EPE(f) = \mathbb{E}[L(Y, f(X))]: Expected Prediction Error
Square error loss (or L_2 loss function): L(Y, f(X)) = (Y - f(X))^2
In this case, the sol is f(x) = \mathbb{E}[Y|X = x]: regression function
Curse of dimension: if p \uparrow, local methods fail because density O(N^{1/p})
Mean Squared Error of the estimator \hat{f} at x_0: MSE(\hat{y}_0) := \mathbb{E}_{\tau}[(y_0 - \hat{y}_0)^2]
\tau (training set) is random, so is \hat{y}_0 := \hat{f}(x_0). True y_0 := f(x_0) is fixed
bias-variance decomposition: MSE(\hat{y}_0) = Var_{\tau}(\hat{y}_0) + Bias(\hat{y}_0)^2
Additive error model: Y = f(X) + \epsilon with \mathbb{E}[\epsilon] = 0 and X \perp \epsilon
We model f with parameters \theta and try to determine f_{\theta}
In least squares method, \theta chosen to minimize Residual Sum of Squares
RSS(\theta) := \sum_{i=1}^{N} (y_i - f_{\theta}(x_i))^2
Maximum likelihood estimation: maximize \mathbb{P} to have those observations \theta = argmax_{\theta}L(\theta) := \sum_{i=1}^{N} \log \mathbb{P}_{\theta}(Y = y_i | X = x_i)
Least square=Max likelihood if Y = f_{\theta}(X) + \epsilon with \theta \backsim \mathcal{N}(0, \sigma^2)
Penalized RSS: PRSS(f, \lambda) := RSS(f) + \lambda J(f), J roughness penalty
If output is a categorical variable G \in \mathcal{G}, L is a card(\mathcal{G})-square matrix
zero-one loss function: L(G, \hat{G}(X)) = 1_{G = \hat{G}(X)}: (f \text{ noted } \hat{G})
In this case, \hat{G}(x) = argmax_{g \in \mathcal{G}} \mathbb{P}(G = g|X = x), called bayes classifier
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1 3 Linear Methods for Regression