2 Overview of Supervised Learning

 $X \in \mathbb{R}^p$: Random vector input

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Y \in \mathbb{R}: Random variable to predict
f(X): function we seek to predict Y
L(Y, f(X)): Loss function to penalize error in prediction
EPE(f) = \mathbb{E}[L(Y, f(X))]: Expected Prediction Error
Square error loss (or L_2 loss function): L(Y, f(X)) = (Y - f(X))^2
In this case, the sol is f(x) = \mathbb{E}[Y|X=x]: regression function
Curse of dimension: if p \uparrow, local methods fail because density O(N^{1/p})
Mean Squared Error of the estimator \hat{f} at x_0: MSE(\hat{y}_0) := \mathbb{E}_{\tau}[(y_0 - \hat{y}_0)^2]
\tau (training set) is random, so is \hat{y}_0 := \hat{f}(x_0). True y_0 := f(x_0) is fixed
bias-variance decomposition: MSE(\hat{y}_0) = Var_{\tau}(\hat{y}_0) + Bias(\hat{y}_0)^2
Additive error model: Y = f(X) + \epsilon with \mathbb{E}[\epsilon] = 0 and X \perp \epsilon
We model f with parameters \theta and try to determine f_{\theta}
In least squares method, \theta chosen to minimize Residual Sum of Squares
In teast squares method, \theta chosen to infinite RSS(\theta) := \sum_{i=1}^{N} (y_i - f_{\theta}(x_i))^2
Maximum \ likelihood \ estimation: \ \text{maximize} \ \mathbb{P} \ \text{to have those observations}
\theta = argmax_{\theta} L(\theta) := \sum_{i=1}^{N} \log \mathbb{P}_{\theta}(Y = y_i | X = x_i)
Least square=Max likelihood if Y = f_{\theta}(X) + \epsilon with \epsilon \backsim \mathcal{N}(0, \sigma^2)
Penalized RSS: PRSS(f, \lambda) := RSS(f) + \lambda J(f), J roughness penalty
If output is a categorical variable G \in \mathcal{G}, L is a card(\mathcal{G})-square matrix
zero-one loss function: L(G, \hat{G}(X)) = 1_{G = \hat{G}(X)}: (f \text{ noted } \hat{G})
In this case, \hat{G}(x) = argmax_{q \in \mathcal{G}} \mathbb{P}(G = g|X = x), called bayes classifier
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3 Linear Methods for Regression

3.2 Linear Regression and Least Squares

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\begin{split} f(X) &= \beta_0 + \sum_{j=1}^p X_j \beta_j \\ RSS(\beta) &= \sum_{i=1}^N (y_i - (\beta_0 + \sum_{j=1}^p X_j \beta_j))^2 = (y - X\beta)^T (y - X\beta) \\ \text{it's convex, solving } \frac{\partial RSS}{\partial \beta} &= 0 \text{, we get } \hat{\beta} = (X^TX)^{-1}X^Ty \\ X \text{ generate a p-dim subspace of } \mathbb{R}^N, \ \hat{y} &= X\hat{\beta} \text{ is the $\bot$-projection of } y \\ \text{If true model is } Y &= X\beta + \epsilon \text{ with } \epsilon \backsim \mathcal{N}(0, \sigma^2) \colon \hat{\beta} \backsim \mathcal{N}(\beta, (X^TX)^{-1}\sigma^2) \\ (X \text{ considered deterministic, randomness comes from $\epsilon$ and $Y$)} \end{split}
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3.3 Subset Selection