

# Frequency-resolved structural sensitivity

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We look at how uncertainty in interactions (structure) changes recovery trajectories.

Consider a stable linear system around equilibrium.

$$T\dot{x} = Ax$$

where  $T$  is diagonal with positive entries (time scales), and  $A$  is the interaction matrix with  $A_{ii} = -1$ . The generalized resolvent is

$$R(\omega) = (i\omega T - A)^{-1}$$

We also choose a weighting matrix  $C$ , which in the biomass-weighted version is

$$C = \text{diag}(u^2)$$

which relates to treating deviations in species with larger equilibrium biomasses as more important in the quadratic energy.

## 1. The distance-to-equilibrium object

Given an initial displacement  $x_0$ , the trajectory is  $x(t) = e^{Jt}x_0$  where  $J = T^{-1}A$ .

The weighted trajectory energy is

$$E(t) = x(t)^\top C x(t)$$

To remove dependence on the particular direction of  $x_0$ , we consider an ensemble of initial conditions with covariance  $\mathbb{E}[x_0 x_0^\top] = C$ .

$$\mathbb{E}[E(t)] = \text{tr}(e^{Jt} C e^{J^\top t})$$

This gives us a normalized "remaining fraction":

$$y(t) = \frac{\text{tr}(e^{Jt} C e^{J^\top t})}{\text{tr}(C)}$$

This is exactly what the biomass-weighted median return rate is, the log-slope summary of this remaining fraction:

$$r_{med}(t) = -\frac{1}{2t} \left( \log y(t) \right) = -\frac{1}{2t} \left( \log \text{tr}(e^{Jt} C e^{J^\top t}) - \log \text{tr}(C) \right)$$

Now, we define the recovery time  $t_{95}$  implicitly from  $y(t)$  by

$$y(t_{95}) = 0.05$$

We can also use normalized time  $\tau = t/t_{95}$  when we want comparability across systems.

## 2. The effective return rate

Instead of  $r_{med}(t)$ , let's now look at the distance-to-equilibrium object itself. We can call it  $R_{eff}$  and it equals the total integrated trajectory energy:

$$\int_0^\infty y(t) dt$$

This gives us a single number, that we'll call "effective return rate" and is defined by

$$\frac{1}{R_{eff}} = 2 \int_0^\infty y(t) dt, \quad \text{so that} \quad R_{eff} = \frac{1}{2 \int_0^\infty y(t) dt}$$

I believe this means that if the whole decay was a single exponential  $y(t) = e^{-2rt}$ , then

$$2 \int_0^\infty e^{-2rt} dt = \frac{1}{r}$$

so  $R_{eff} = r$ .

Thus,  $R_{eff}$  is a scalar summary of the entire decay curve that does not retain the full time dependence like  $r_{med}(t)$ .

## 3. The generalized resolvent

The main benefit of moving to frequency is that integrals of squared trajectory magnitude can be written as integrals of squared transfer magnitude (Parseval's theorem)

If we write the system as a forced linear system,

$$T\dot{x} = Ax + \xi(t)$$

its Fourier transform satisfies

$$\hat{x}(\omega) = R(\omega)\hat{\xi}(\omega)$$

If  $\xi$  matches the same  $C$  we used in time, then we get an identity of the form

$$\int_0^\infty \mathbb{E}[x(t)^\top C x(t)] dt \propto \int_{-\infty}^\infty \text{tr}(R(\omega) C_\xi R(\omega)^\dagger) d\omega$$

where  $\dagger$  is conjugate transpose and  $C_\xi$  is the forcing covariance in frequency.

This is why the generalized resolvent matters. It converts an integrated time-domain energy statement into an integrated frequency-domain magnitude statement.

## 4. Structural uncertainty and the role of $R(\omega)$ and $R(\omega)PR(\omega)$

We model interaction uncertainty as

$$A \mapsto A + \varepsilon P$$

where  $P$  is a direction (uncertainty pattern) and  $\varepsilon$  sets its magnitude.

A first-order expansion gives us

$$R_\varepsilon(\omega) - R(\omega) \approx \varepsilon R(\omega) P R(\omega)$$

Thus, the frequency-resolved sensitivity to uncertainty direction  $P$  is naturally based on the operator  $RPR$ . Because we're also considering the biomass-weighted  $C$ , sensitivity at a certain  $\omega$  can be defined as

$$S(\omega; P) = \varepsilon^2 \frac{\|R(\omega)PR(\omega)U\|_F^2}{\text{tr}(C)}, \quad \text{with} \quad UU^\top = C$$

If  $C = \text{diag}(u^2)$  as it has been so far, then  $U = \text{diag}(u)$ .

Given  $S(\omega; P)$ , can now define two sensitivities

- Typical sensitivity: average  $S(\omega; P)$  over an ensemble of  $P$  (noise uncertainty).
- Worst-case sensitivity: maximize over  $P$ , which yields a worst-case bound that will be controlled by the singular values of  $R(\omega)$  and  $R(\omega)U$ .

## 5. The cutoff frequency $\omega_c$

Let's consider a cutoff frequency linked to the minimal time to get divergence. Or in other words, the minimal time at which structural information may matter.

We can define it in two different ways

### 5.1 Picking $\omega_c$ from $\rho(A_\omega)$ (better)

The more mechanistic way to define the cutoff is to identify when indirect interaction pathways become important.

We can factor the resolvent as

$$R(\omega) = (i\omega T - A)^{-1} = (I - A_\omega)^{-1}(i\omega T + I)^{-1}$$

with

$$A_\omega = A(i\omega T + I)^{-1}$$

The term  $(i\omega T + I)^{-1}$  behaves like a classic low-pass filter.

And the term  $(I - A_\omega)^{-1}$  expands as a Neumann series when  $\rho(A_\omega) < 1$ :

$$(I - A_\omega)^{-1} = I + A_\omega + A_\omega^2 + \dots$$

This means:

- $I$  is the direct (no-interaction) response.
- $A_\omega$  is one-step interaction (direct effects).
- $A_\omega^2, A_\omega^3, \dots$  are the indirect effects.

A frequency cutoff can therefore be defined from a “collectivity” index such that  $K(\omega) = \rho(A_\omega)$ . The cutoff  $\omega_c$  is where indirect effects stop being negligible (for example, when  $K(\omega)$  crosses 1), and then  $t_c = 1/\omega_c$  is the earliest time at which indirect pathways can matter.

## 5.2 Picking $\omega_c$ from $S(\omega)$ (old idea)

We can also do the following:

- Define a relevant frequency threshold  $\omega_{95} = 1/t_{95}$ .
- Look at how sensitivity accumulates over frequencies above  $\omega_{95}$ .
- Define  $\omega_q$  such that a fraction  $q$  of the relevant sensitivity is accumulated by  $\omega_q$ :

$$\frac{\int_{\omega_{95}}^{\omega_q} S(\omega) d\omega}{\int_{\omega_{95}}^{\infty} S(\omega) d\omega} = q$$

Then bring it back to time-domain by  $t_q = 1/\omega_q$  and  $\tau_q = t_q/t_{95}$ .

Why is this useful? If most sensitivity sits at high frequencies, then  $\omega_q$  is large and  $t_q$  is small, meaning trajectories are expected to separate early (in normalized time). If sensitivity sits at lower frequencies, separation is expected later, maybe in slow, not-so-relevant times.

## 6. Formal link between $r_{med}(t)$ and $R_{eff}$

Here I give an exact mathematical relation between  $r_{med}(t)$  and  $R_{eff}$ .

### 6.1 Common backbone: weighted energy $y(t)$

Let  $J$  be the stable Jacobian,  $E(t) = e^{tJ}$  and a positive diagonal weight matrix  $C$ . The normalised weighted trajectory energy is

$$y(t) = \frac{\text{tr}(E(t) C E(t)^\top)}{\text{tr}(C)}$$

Then  $y(0) = 1$ ,  $y(t) > 0$ , and for stable  $J$ ,  $y(t) \rightarrow 0$  as  $t \rightarrow \infty$ .

Thus, our biomass-weighted median return rate is exactly

$$r_{med}(t) = -\frac{1}{2t} \log(y(t))$$

### 6.2 Instantaneous energy decay rate

The instantaneous energy decay rate is

$$r_{inst}(t) = -\frac{1}{2} \frac{d}{dt} \log(y(t))$$

Because  $y(0) = 1$ , we can integrate  $d \log y / dt$  from 0 to  $t$  to obtain

$$\log y(t) = -2 \int_0^t r_{inst}(s) ds$$

Substituting into the definition of  $r_{med}(t)$  yields an exact identity:

$$r_{med}(t) = \frac{1}{t} \int_0^t r_{inst}(s) ds$$

Thus,  $r_{med}(t)$  is the uniform in time average of the instantaneous decay rate over the interval  $[0, t]$ .

### 3.3 Defining $R_{eff}$ from the same $y(t)$

In Section 2, I already showed that

$$R_{eff} = \frac{1}{2 \int_0^\infty y(t) dt}$$

### 6.4 Exact relation

Using  $r_{inst}(t) = -(1/2) d \log y(t)/dt$ , we have

$$\frac{d}{dt} y(t) = -2 r_{inst}(t) y(t)$$

Integrating both sides from 0 to  $\infty$  gives

$$\int_0^\infty r_{inst}(t) y(t) dt = -\frac{1}{2} \int_0^\infty y'(t) dt = \frac{1}{2} (y(0) - y(\infty)) = \frac{1}{2}$$

Therefore,

$$R_{eff} = \frac{1}{2 \int_0^\infty y(t) dt} = \frac{\int_0^\infty r_{inst}(t) y(t) dt}{\int_0^\infty y(t) dt}$$

Thus,  $R_{eff}$  is a single scalar that averages across all times, with weights proportional to  $y(t)$  whereas  $r_{med}(t)$  is a function of time and depends on a finite averaging horizon  $[0, t]$

### 6.5 When are they approximately equal?

If  $y(t)$  is approximately a single exponential,

$$y(t) \approx e^{-2rt}$$

then  $r_{inst}(t) = r$  is constant, and

$$r_{med}(t) = r \quad \text{for all } t, \quad R_{eff} = \frac{1}{2 \int_0^\infty e^{-2rt} dt} = r$$

Hence, exact equality between  $R_{eff}$  and  $r_{med}(t)$  will only occur when the energy decay is effectively a single rate.