

```
Clear[aux, t, x, a1, a2, a3, a4, a5, b1, b2, c1, c2, q1,
      q2, q3, q4, q5, V1, V12, V22, u, x1, x2, y2, y3, z2, z3, m, n, in];
```

```
R = 1.3036;  $\theta_0 = 4 / 7$ ;  $\theta_1 = \frac{4}{7}$ ;
```

```
G0[aux_, t_, in_, k_] = -  $\frac{(-t)^{k-1}}{(k-2)!}$  Integrate[ $e^{-aux * u * t * \theta_1} u^{k-2} (1-u)^{in} t^{in}$ , {u, 0, 1}];
```

```
G1[aux_, t_, in_, k_] =
```

```
Which[k == 2, -2 *  $t^{in}$ , k == 3, -  $\frac{3 (-t)^{3-2}}{(3-3)!}$  Integrate[ $e^{-aux * u * t * \theta_1} u^{3-3} (1-u)^{in} t^{in}$ , {u, 0, 1}]];
```

```
G2[aux_, t_, in_, k_] = Which[k == 2, aux *  $\theta_1 * t^{in} + in * t^{in-1}$ , k == 3, -3 *  $t^{in}$ ];
```

```
G3[aux_, t_, in_, k_] = Which[k == 2, 0, k == 3, aux *  $\theta_1 * t^{in} + in * t^{in-1}$ ];
```

```
I2[aux_, t_, in_, k_] = Which[k == 0, G0[aux, t, in, 2], k == 1,
```

```
      G1[aux, t, in, 2], k == 2, G2[aux, t, in, 2], k == 3, G3[aux, t, in, 2]];
```

```
I3[aux_, t_, in_, k_] = Which[k == 0, G0[aux, t, in, 3], k == 1,
```

```
      G1[aux, t, in, 3], k == 2, G2[aux, t, in, 3], k == 3, G3[aux, t, in, 3]];
```

```
P1[aux_, t_, in_] = aux *  $\theta_0 * t^{in} + in * t^{in-1}$ ;
```

```
PC = Compile[{{m, _Integer}, {n, _Integer}},
```

```
      Sum[ $\frac{m! * n!}{1! * (m-1)! * (n-1)! * (m+n)!}$ , {1, 0, Min[m, n]}]];
```

```
P00[x_] = x + p02 x (1 - x) + p03 x (1 - x)2 + p04 x (1 - x)3 + p05 x (1 - x)4;
```

```
P01[x_] = p11 x + p12 x2 + p13 x3;
```

```
P02[x_] = p21 x + p22 x2 + p23 x3;
```

```
Q[x_] = q0 + q1 (1 - 2 x) + q2 (1 - 2 x)3 + (1 - q0 - q1 - q2) (1 - 2 x)5;
```

```
{p1[0], p1[1], p1[2], p1[3], p1[4], p1[5]} = CoefficientList[P00[x], x];
```

```
{p2[0], p2[1], p2[2], p2[3]} = CoefficientList[P01[x], x];
```

```
{p3[0], p3[1], p3[2], p3[3]} = CoefficientList[P02[x], x];
```

```
{q[0], q[1], q[2], q[3], q[4], q[5]} = CoefficientList[Q[x], x];
```

```

i = 1; cc = 0;
While[i < 6, j = 1;
  While[j < 6, k = 0;
    While[k < 6, l = 0;
      While[l < 6, concon[a_, b_, x_] = P1[a, 1 - x, i] * P1[b, 1 - x, j];

      concons[a_, b_, x_] = 
$$\frac{\text{concon}[a, b, x] - e^{-a-b} \text{concon}[-b, -a, x]}{a + b};$$


      conconq := Derivative[l, k, 0][concons];

      cc = cc + p1[i] * p1[j] * q[k] * q[l] * 
$$\frac{(-1)^{1+k}}{\theta_0} *
      \text{Re}[NIntegrate[conconq[-R, -R, x], \{x, 0, 1\}, Method \rightarrow \{"GlobalAdaptive",
        "MaxErrorIncreases" \rightarrow 10000, Method \rightarrow "GaussKronrodRule"\}]]];

      l = l + 1];
      k = k + 1];
      j = j + 1];
      i = i + 1];
TimeUsed[]
8.389

Clear[i, j, k, l, r, cf2];$$

```

```

i = 1; cf2 = 0;
While[i < 6, j = 1;
  While[j < 4, k = 0;
    While[k < 6, l = 0;
      While[l < 6, r = 0;
        While[r < 3,
          confen02[a_, b_, x_] = xr * P1[a, 1 - x  $\frac{\theta_1}{\theta_0}$ , i] * I2[b, 1 - x, j, r];

          confens02[a_, b_, x_] =  $\frac{1}{a + b}$  (confen02[a, b, x] - e-a-b confen02[-b, -a, x]);
          confenq02 := Derivative[l, k, 0][confens02];
          cf2 = cf2 + p1[i] * p2[j] * q[k] * q[l] *  $\frac{(-1)^{1+k}}{r! * \theta_0}$  *
            Re[NIntegrate[confenq02[-R, -R, x], {x, 0, 1}, Method → {"GlobalAdaptive",
              "MaxErrorIncreases" → 10 000, Method → "GaussKronrodRule"}]];
          r++];
        l = l + 1];
      k = k + 1];
    j = j + 1];
  i = i + 1]
TimeUsed[]
19.92

```

```

Clear[i, j, k, l, r, cf3];
i = 1; cf3 = 0;
While[i < 6, j = 1;
  While[j < 4, k = 0;
    While[k < 6, l = 0;
      While[l < 6, r = 0;
        While[r < 4,
          confen03[a_, b_, x_] =  $x^r * P1\left[a, 1 - x \frac{\theta_1}{\theta_0}, i\right] * I3[b, 1 - x, j, r];$ 

          confens03[a_, b_, x_] =  $\frac{1}{a + b} \left( \text{confen03}[a, b, x] - e^{-a-b} \text{confen03}[-b, -a, x] \right);$ 
          confenq03 := Derivative[1, k, 0][confens03];
          cf3 = cf3 + p1[i] * p3[j] * q[k] * q[l] *  $\frac{(-1)^{1+k}}{r! * \theta_0} * \text{Re}[NIntegrate[\text{confenq03}[-R, -R, x], \{x, 0, 1\}, \text{Method} \rightarrow \{"GlobalAdaptive",$ 
            "MaxErrorIncreases"  $\rightarrow 10000, \text{Method} \rightarrow \text{"GaussKronrodRule"}]]];$ 
          r++;
        l = l + 1];
      k = k + 1];
    j = j + 1];
  i = i + 1];
TimeUsed[]
216.764

```

```

Clear[i, j, k, l, r, s, ff22];
i = 1; ff22 = 0;
While[i < 4, j = 1;
  While[j < 4, k = 0;
    While[k < 6, l = 0;
      While[l < 6, r = 0;
        While[r < 3, s = 0;
          While[s < 3,
            fenfen22[a_, b_, x_] = xr+s * I2[a, 1 - x, i, s] * I2[b, 1 - x, j, r];

            fenfens22[a_, b_, x_] =  $\frac{1}{a+b}$  (fenfen22[a, b, x] - e-a-b fenfen22[-b, -a, x]);
            fenfenq22 := Derivative[l, k, 0][fenfens22];

            ff22 = ff22 + p2[i] * p2[j] * q[k] * q[l] *  $\frac{(-1)^{1+k}}{\theta_1}$  * PC[r, s] *

            Re[NIntegrate[fenfenq22[-R, -R, x], {x, 0, 1}, Method → {"GlobalAdaptive",
              "MaxErrorIncreases" → 10000, Method → "GaussKronrodRule"}]];

            s++];
          r++];
        l = l + 1];
      k = k + 1];
    j = j + 1];
  i = i + 1];
TimeUsed[]
265.264

```

```

Clear[i, j, k, l, r, s, ff23];
i = 1; ff23 = 0;
While[i < 4, j = 1;
  While[j < 4, k = 0;
    While[k < 6, l = 0;
      While[l < 6, r = 0;
        While[r < 4, s = 0;
          While[s < 3,
            fenfen23[a_, b_, x_] = xr+s * I2[a, 1 - x, i, s] * I3[b, 1 - x, j, r];

            fenfens23[a_, b_, x_] =  $\frac{1}{a+b}$  (fenfen23[a, b, x] - e-a-b fenfen23[-b, -a, x]);
            fenfenq23 := Derivative[1, k, 0][fenfens23];

            ff23 = ff23 + p2[i] * p3[j] * q[k] * q[l] *  $\frac{(-1)^{1+k}}{\Theta_1}$  * PC[r, s] *

            Re[NIntegrate[fenfenq23[-R, -R, x], {x, 0, 1}, Method → {"GlobalAdaptive",
              "MaxErrorIncreases" → 10000, Method → "GaussKronrodRule"}]];

            s++;
          ];
          r++;
        ];
        l = l + 1;
      ];
      k = k + 1;
    ];
    j = j + 1;
  ];
  i = i + 1;
];
TimeUsed[]
696.764

```

```

Clear[i, j, k, l, r, s, ff33];
i = 1; ff33 = 0;
While[i < 4, j = 1;
  While[j < 4, k = 0;
    While[k < 6, l = 0;
      While[l < 6, r = 0;
        While[r < 4, s = 0;
          While[s < 4,
            fenfen33[a_, b_, x_] = xr+s * I3[a, 1 - x, i, s] * I3[b, 1 - x, j, r];

            fenfens33[a_, b_, x_] =  $\frac{1}{a+b}$  (fenfen33[a, b, x] - e-a-b fenfen33[-b, -a, x]);
            fenfenq33 := Derivative[l, k, 0][fenfens33];

            ff33 = ff33 + p3[i] * p3[j] * q[k] * q[l] *  $\frac{(-1)^{1+k}}{\theta_1}$  * PC[r, s] *

            Re[NIntegrate[fenfenq33[-R, -R, x], {x, 0, 1}, Method → {"GlobalAdaptive",
              "MaxErrorIncreases" → 10000, Method → "GaussKronrodRule"}]];

            s++;
          ];
          r++;
        ];
        l = l + 1;
      ];
      k = k + 1;
    ];
    j = j + 1;
  ];
  i = i + 1;
];
TimeUsed[]
1708.2

Minimize[cc + 2 (cf2 + cf3 + ff23) + ff22 + ff33,
  {p02, p03, p04, p05, p11, p12, p13, p21, p22, p23, q0, q1, q2, q3}]
{2.13745, {p02 → 0.261077, p03 → -1.07101, p04 → -0.23684, p05 → 0.260234,
  p11 → 1.04827, p12 → 1.31991, p13 → -0.940058, p21 → 0.522812, p22 → -0.68651,
  p23 → -0.0499239, q0 → 0.490464, q1 → 0.636852, q2 → -0.159327, q3 → -0.0452241}}

1 -  $\frac{\text{Log}[2.1374544061177065]}{R}$ 
0.417294

1 - 0.49104466722644263 - 0.6323866423049164` - (-0.15444126926636118`)
0.03101

```

```

P00[x_] = x + 0.26107655428766874` x (1 - x) - 1.0710070584688371` x (1 - x)^2 -
0.2368403810100388` x (1 - x)^3 + 0.26023389454818024` x (1 - x)^4 ;
P01[x_] = 1.0482749626606975` x + 1.3199126585889513` x^2 - 0.9400584473859237` x^3;
P02[x_] = 0.5228119879990683` x - 0.6865103565474571` x^2 - 0.0499239413756441` x^3;
Q[x_] = 0.4904641213705433` + 0.6368518935202375` (1 - 2 x) +
-0.15932727726618862` (1 - 2 x)^3 + 0.032011262375407856` (1 - 2 x)^5;

P00[1]
1.

P00[0]
0.

Q[0]
1.

FullSimplify[Q[x] + Q[1 - x]]
0.980928

Solve[0.9679887376245921` + A == 1]
{{A -> 0.0320113}}

Q[1]
0.0581636

0.41729396200519175`

```