



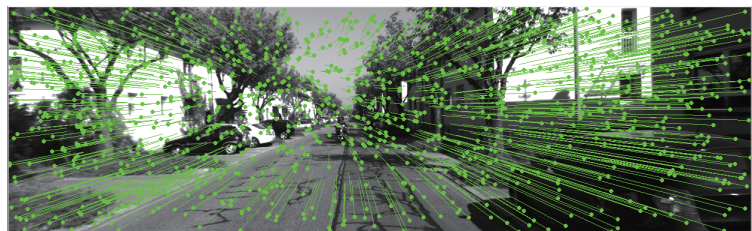
Reference image



Disparity map of the reference



Image to track



The tracked points by direct method