

# The K Project

## Interrupt and Exception Handling

LSE Team

EPITA

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Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

- *Exception* : Synchronous with program execution  
(e.g. division by zero, accessing an invalid address)
- *Interrupt* : Asynchronous with program execution.  
Generated by devices external to the CPU

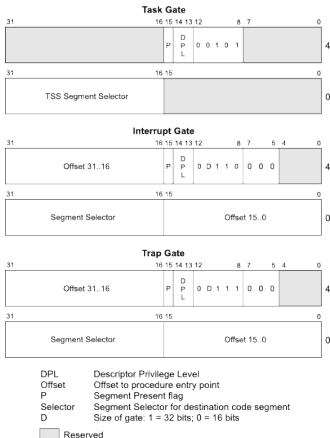


Figure: IDT

# Interrupt Descriptor Table Register

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Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

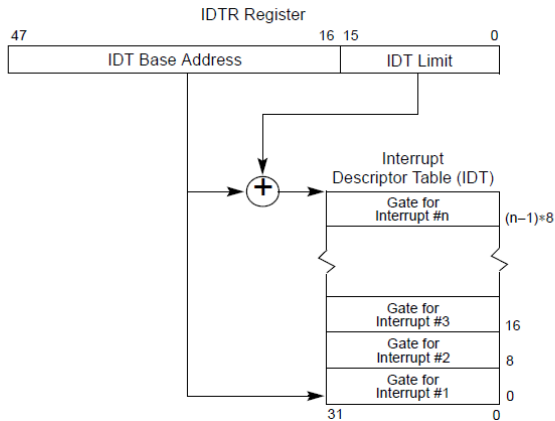


Figure: IDTR

```
idt_r idtr;
```

```
idtr.base = idt;           /* idt base address */
```

```
idtr.limit = sizeof(idt) - 1; /* idt size - 1 */
```

```
__asm__ volatile("lidt %0\n"  
                 : /* no output */  
                 : "m" (idtr)  
                 : "memory");
```

The K Project

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Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

Int.	Description
0	Divide by 0
1	Debug
2	NMI
3	Breakpoint
4	Overflow
5	Bound Range Exceeded
6	Invalid Opcode

The K Project

LSE Team

Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

Int.	Description
7	Device Not Available
8	Double Fault
9	Coprocessor
10	Invalid TSS
11	Segment not present
12	Stack Segment Fault
13	General Protection
14	Page Fault

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Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

```
int $3      ; Breakpoint  
int $0x80   ; Syscall
```

Intel's definition, Vol2a

"The INT n instruction generates a call to the interrupt or exception handler specified with the destination operand"



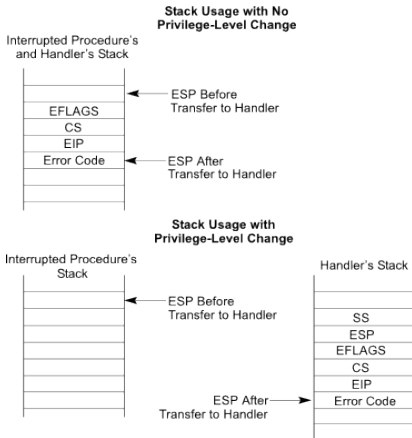


Figure: Stack Usage

```
isr:
    xchgl %eax, (%esp)
    ;<save registers>
    call *%eax
    ;<restore registers>
    iret

.global isr_keyboard
isr_keyboard:
    pushl $do_isr_keyboard
    jmp    isr
```

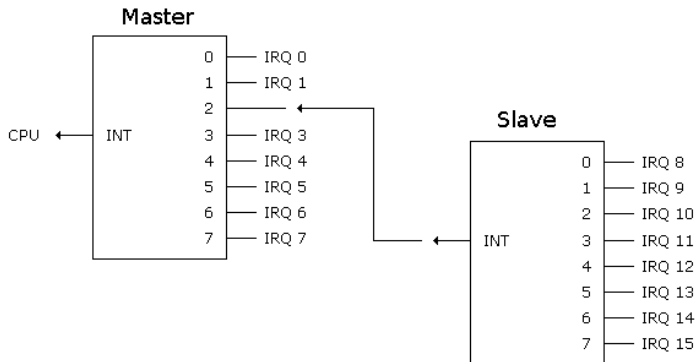


Figure: PIC

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Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

- IRQ0 - PIT
- IRQ1 - Keyboard
- IRQ2 - Not assigned in PC/XT; cascaded to slave 8256
- IRQ3 - UART (COM2 and COM4)
- IRQ4 - UART (COM1 and COM3)
- IRQ5 - Hard disk in PC/XT; Parallel port LPT2 in PC/AT
- IRQ6 - Floppy disk controller
- IRQ7 - Parallel port LPT1

The K Project

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Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

- IRQ8 - RTC
- IRQ9 -
- IRQ10 -
- IRQ11 -
- IRQ12 - PS/2 mouse controller
- IRQ13 - Math coprocessor
- IRQ14 - Hard disk controller 1
- IRQ15 - Hard disk controller 2

The K Project

LSE Team

Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

- 0x20, the master PIC's port A
- 0x21, the master PIC's port B
- 0xA0, the slave PIC's port A
- 0xA1, the slave PIC's port B

```

0 0 0 1 x 0 x x
      |   | |
      |   | | +----- (1)
      |   +----- (2)
      +----- (3)
  
```

- 1** ICW4 present (set) or not (clear)
- 2** single controller (set) or cascade mode (clear)
- 3** level triggered mode (set) or edge triggered mode (clear)

The K Project

LSE Team

Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

```

x x x x x 0 0 0
| | | | | | | |
+----- (1)

```

**1** Interrupt vector base address



## Master PIC

```

x x x x x x x x
| | | | | | | |
+----- (1)

```

## Slave PIC

```

0 0 0 0 0 x x x
          | | |
          +----- (2)

```

- 1** For each bit, indicate whether a slave PIC is connected to this pin (set) or not (clear)
- 2** Indicate to the slave his slave ID (which pin of the master it is connected to)

```

0 0 0 x x x x 1
      | --- |
      |   | +----- (1)
      | +----- (2)
      +----- (3)
  
```

- 1** Automatic (set) EOI or normal (clear) EOI
- 2** Buffering mode
- 3** Special mode fully nested (set) or not (clear)

## The K Project

LSE Team

Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

```

x x x x x x x x
| | | | | | | |
+----- (1)
  
```

- 1** For each bit, indicate whether the corresponding IRQ is masked (set) or not (clear)

## The K Project

LSE Team

Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

```

x x x 0 0 x x x
| | |     -----
| | |           |
| | |           +----- (1)
| | +----- (2)
| +----- (3)
+----- (4)
  
```

- 1** Interrupt level to be acted upon when sending a specific command
- 2** Send an EOI (end of interrupt command) (set)
- 3** Send a specific (set) or a non-specific (clear) command
- 4** Rotate priorities (set) or not (clear)

- Write IDT management functions
  - allocate/clean IDT
  - sets an interrupt gate into the IDT
- Write the context saving/restoring routines in assembly code
- Implement the exceptions and interrupts wrappers
- Write a function which builds the IDT and loads it
- Initialize the PIC
  - send ICWs to both master and slave PICs
  - mask all interrupts
- Write very simple debug handlers like:
  - printing an error message when executing a division by zero
  - printing a string when a key is pressed
- Do not forget to enable hardware interrupts using `sti`

The K Project

LSE Team

Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

- You forgot to save or restore some registers in your context
- You did not consider that gcc automatically generates the prolog/epilog for C functions
- The stack is misaligned when `iret` is executed
- PICs are not acknowledged after returning from an ISR (Interrupt SubRoutine)

The K Project

LSE Team

Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

- 0x60: I/O buffer
- 0x64: Status register

X	X	X	X	X	X	X	X		
							+	----	Output buffer full
						+	-----		Input buffer full
					+	-----			System flag
				+	-----				Command/Data
		+	-----						Keyboard inhibit
	+	-----							Auxiliary device output buffer
+	-----								General purpose time-out
+	-----								Parity error



The K Project

LSE Team

Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

```

X X X X X X X X
| -----
|           |
|           +----- Key number
|           +----- Key press (clear) or release (set)

```

- Ensure that the event manager is working
- Initialize driver
  - Add the keyboard interrupt gate to the IDT
  - Update the PIC to unmask the IRQ line 1
- Write a very simple keyboard handler:
  - Read scancodes from I/O port 0x60
  - Extra features such as modifier keys or simultaneous key strikes support are not mandatory
- Implement `getkey()`
- You might implement a queue for the keyboard buffer

The K Project

LSE Team

Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

- Execution context may be corrupted.
- Hardware interrupts may have been disabled with `cli` or may not have been enabled with `sti`
- The keyboard interrupt may be masked in the PIC

The K Project

LSE Team

Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

- Counter 0: fire an interrupt at a user-defined frequency.
- Counter 1: historically used in order to periodically refresh the RAM, but it not used anymore.
- Counter 2: linked with the PC speaker, so you can use it in order to generate sound

The K Project

LSE Team

Introduction

Interrupt  
Descriptor  
Table

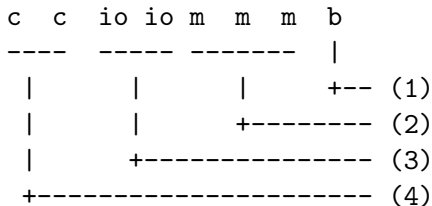
Interrupt  
Request

Keyboard

Timer

Conclusion

- Mode 0: Interrupt on terminal count
- Mode 1: hardware retriggerable one-shot
- Mode 2: rate generator
- Mode 3: square generator
- Mode 4: Software Triggered Strobe
- Mode 5: Hardware Triggered Strobe



- 1 Binary counter (unset) or BCD counter (set)
- 2 Mode to use
- 3 Registers read/write policy
- 4 Counter to setup

The K Project

LSE Team

Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

- 0x40 : Counter 0
- 0x41 : Counter 1
- 0x42 : Counter 2
- 0x43 : Control Register

The K Project

LSE Team

Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

- Write into control register
- Read/Write the value on the counter register



The K Project

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Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

- Write into control register
- Write the divider on the counter register

$$divider = \frac{internal\_frequency}{desired\_frequency}$$

- Internal frequency : 1193182

```
unsigned long gettick(void);
```

- Counter 0
- Mode 2
- Interrupt rate : 100 Hz

The K Project

LSE Team

Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

- Execution context may be corrupted.
- Hardware interrupts may have been disabled with `cli` or may not have been enabled with `sti`
- The timer interrupt may be masked in the PIC.

The K Project

LSE Team

Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

- Use X Macro

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Introduction

Interrupt  
Descriptor  
Table

Interrupt  
Request

Keyboard

Timer

Conclusion

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- [k@lse.epita.fr](mailto:k@lse.epita.fr)
- [naam@lse.epita.fr](mailto:naam@lse.epita.fr)
- [nurelin@lse.epita.fr](mailto:nurelin@lse.epita.fr)