

Fluctuation data analysis in Fusion Relevant Plasmas

N. Vianello

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Diagnostics provides information with different time and spatial resolution

1. Measurements coming from a single point
2. Spatially distributed arrays of measurements (resolving portion of the plasma or entire torus)
3. line integrated measurements (single Line Of Sight (LoS))
4. Arrays of LoS (examples are tomographic reconstruction)
5. We will focus on analysis technique suitable for single-point/multi point measurements, extracting information on spatial/temporal dynamics

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- ▶ Some remarks on basic Fourier Transform and its discrete counterpart the Discrete Fourier Transform are mandatory

- ▶ The **Direct** and **Inverse** fourier transform of a generic function of time $x(t)$ is defined as :

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- ▶ In the case of discrete signals $x_n = x(n\Delta t)$ with $0 \leq n \leq N - 1$, sampled at frequency $f_c = \frac{1}{\Delta t}$ we have the corresponding **Direct** and **Inverse** Discrete Fourier transform, then defined as

$$X_n = \frac{1}{N} \sum_{k=0}^{N-1} x_k e^{-2\pi i k n / N}$$

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- ▶ The **Sampling Theorem** (Bracewell 1999) ensure that A function whose Fourier transform is zero for $f > f_c$ is fully specified by values spaced at equal intervals not exceeding $\frac{1}{2} f_c^{-1}$

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- ▶ The **Nyquist Frequency** $f_N = \frac{1}{2\Delta t}$, defines the maximum frequency which can be properly resolved, or equivalently given the frequency of the system we would like to investigate, we had to sample at least at twice the values of this frequency.

- ▶ Various theorems may be applied to FT (Bracewell [1999](#)) among which we cite:

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Theorem

Convolution theorem: If $x(t)$ and $g(t)$ have FT respectively equal to $X(f)$ and $G(f)$ the convolution of the two function $h(t) = \int_{-\infty}^{+\infty} x(t')g(t-t')dt'$ is equal to $X(f)G(f)$

- ▶ The importance of the convolution equation resides on the fact that it allows treatment of non-linearities as the term $\mathbf{v} \cdot \nabla \mathbf{v}$ in the Navier-Stokes equations

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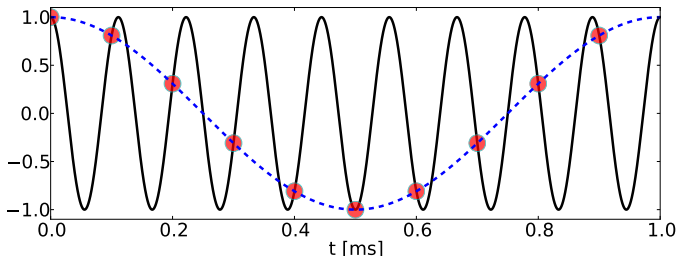
Theorem

Rayleigh's Theorem *The integral of squared modulus of a function is equal to the integral of the squared modulus of its spectrum, i.e:*

$$\int_{-\infty}^{+\infty} |f(t)|^2 dt = \int_{-\infty}^{+\infty} |F(f)|^2 df$$

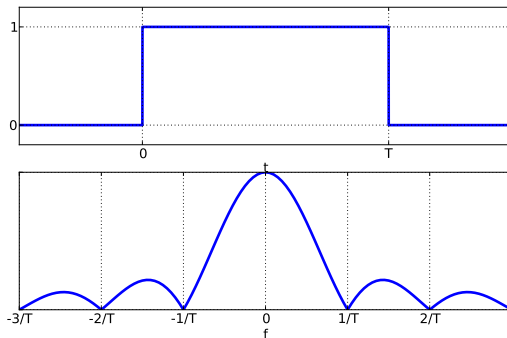
- ▶ This is equivalent to an energy conservation law for the time or frequency domain representation of the signal

- ▶ The presence of frequency higher than the Nyquist frequency may lead to the presence of spurious frequency



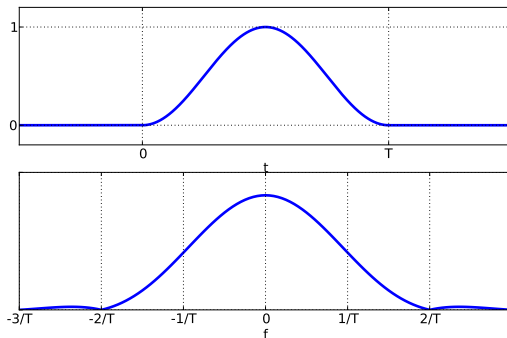
- ▶ A 9 kHz cosine if sampled at 10 kHz exhibits a spurious 1 kHz oscillation

- ▶ Actually signals are acquired for a given period $T \rightarrow$ equivalent to the convolution with a box function $G(t)$ with domain $0 \leq t \leq T$, i.e. $G(t) = 1$ if $0 \leq t \leq T$ 0 otherwise
- ▶ In the Fourier space equivalent to the multiplication with the Fourier representation of a box function $\rightarrow \text{sinc}(x) = \sin(x)/x$ function as shown, which **leaking** some power from one frequency bin to the adjacents ones.



- Solution to the leakage: multiplication with an appropriate window function which reduces the lobes as the *Hanning window*:

$$u_h(t) = \frac{1}{2}(1 - \cos(2\pi t/T)) \text{ for } 0 \leq t \leq T \text{ and } 0 \text{ otherwise.}$$



- ▶ A random process $x(t)$ is completely described by its moments, which are the average over the probability distribution function

$$E[x(t)] \quad E[x(t_1)x(t_2)] \quad E[x(t_1)x(t_2)x(t_3)] \quad \dots$$

- ▶ We define **Auto-correlation function**, i.e. the second order momentum of the distribution, or the **autocovariance function**

$$R(\tau) = E[x(t)x(t-\tau)]$$

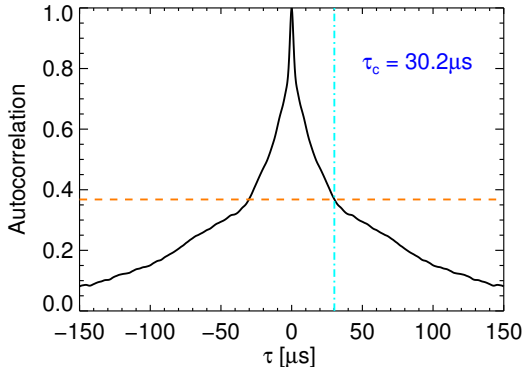
$$C(\tau) = E[(x(t) - m)(x(t-\tau) - m)]$$

being m the average of $x(t)$

- ▶ The **Auto-correlation coefficient factor** is defined as $\rho(\tau) = C(\tau)/C(0)$
- ▶ For digitized signals with N samples the estimator of $C(\tau)$ is defined as

$$C_j = \frac{1}{N} \sum_{i=j}^{N-1} (x_i - \bar{x})(x_{i-j} - \bar{x}) \quad \bar{x} = \frac{1}{N} \sum_{i=0}^{N-1} x_i$$

- Define the **Auto-correlation time** of a turbulent field such as the potential: $R(\tau_c) = \frac{\max(R(\tau))}{e}$



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- ▶ Practically, we divide signals into M slices, assumed as independent realization of the same stochastic process and we compute

$$\hat{S}(f) = \frac{1}{M} \sum_{k=1}^M S^{(k)}(f); \quad S^{(k)}(f) = \frac{1}{T} |X_T^{(k)}(f)|^2$$

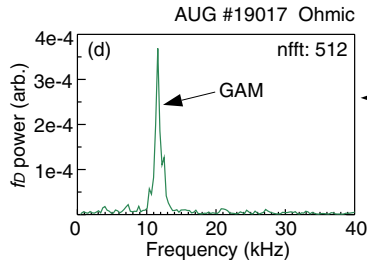
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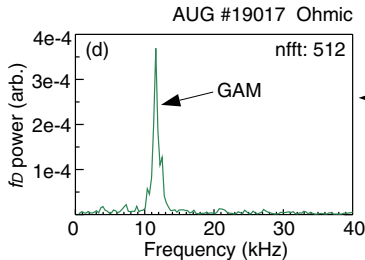
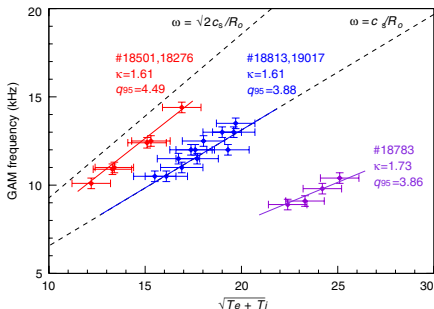
- ▶ With digitized signal, the power spectral estimator \hat{S}_n is related to the real power spectrum $S(f_n)$ as

$$\hat{S}_n = \frac{1}{M} \sum_{k=1}^M |X_n^{(k)}|^2; \quad \hat{S}_n \simeq S(f_n) \Delta f$$

- ▶ Mode identification at a given frequency (Conway et al. 2005)

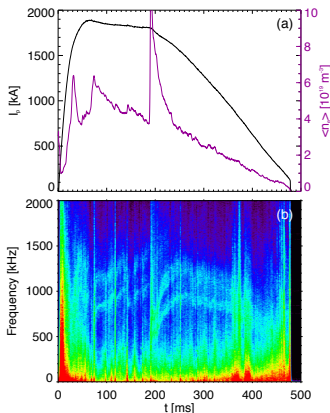


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- ▶ Information must be completed. In the example scaling of identified mode as a function of ion sound velocities

- ▶ The same information can be also analyzed in time applying the **spectrogram** technique which shows how the spectral density of the signal varying in time/frequency space (Spagnolo et al. [2011](#))



- ▶ Alfvénic nature revealed by the comparison with the plasma density

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- ▶ The minimum set includes two measurements $x(t)$ and $y(t)$. We can define the **Cross-correlation function**, **The cross-covariance function** and the **cross-correlation coefficient function**

$$R_{xt}(\tau) = E[y(t)x(t - \tau)]$$

$$C_{xy}(\tau) = E[(y(t) - \bar{y})(x(t - \tau) - \bar{x})]$$

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- ▶ In the discrete counterpart of the cross-covariance is defined as

$$C_{yx,j} = \frac{1}{N} \sum_{i=j}^{N-1} (y_i - \bar{y})(x_{i-j} - \bar{x})$$

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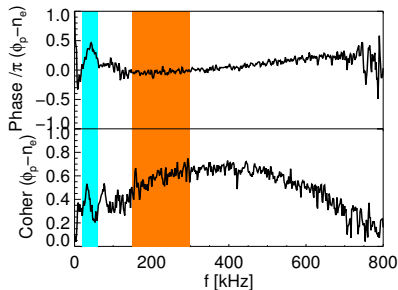
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- ▶ In the case of discrete signals with finite temporal length the following definitions hold (in analogy to single point case)

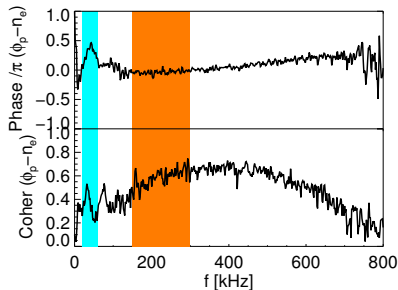
$$\hat{S}_{Y,X,n} = \frac{1}{M} \sum_{k=1}^M Y_n^{(k)} X_n^{*(k)} \quad \hat{S}_{Y,X,n} \simeq S_{YX}(f_n) \Delta f$$

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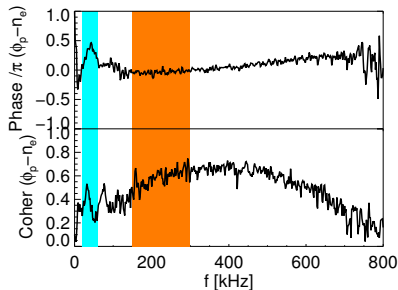


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- ▶ This allows the possibility to distinguish the frequency where turbulence is **Interchange-dominated** from that where turbulence is **Drift-dominated**
- ▶ Other possibility is the determination of the polarization of magnetic fluctuations frequency resolved

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- ▶ The probe distance d must be less than aa wave length, less than a correlation lenght, but far enough the detect a measurable phase difference

- ▶ Fluctuations induced particle flux is defined as
$$\Gamma = E[\tilde{n}(t)\tilde{v}(t)] = E[\tilde{n}(t)\tilde{E}(t)]/B$$
- ▶ According to previous definitions and properties

$$\Gamma = \frac{1}{B} R_{nE}(\tau = 0) = \frac{1}{B} \int_{-\infty}^{+\infty} S_{nE}(f) e^{i2\pi f\tau} df = \frac{2}{B} \int_0^{+\infty} \Re[S_{nE}(f)] df$$

- ▶ In quasi-static approximation $\tilde{E} = -\nabla\tilde{\phi}$, and considering the finiteness of the measurements we end up with the formula

$$\Gamma(f) = \frac{2}{BT} \Im\{E[k(f)N(f)\Phi^*(f)]\}$$
$$\Gamma(f) = \frac{2k(f)}{B} \Im\{S_{n\phi}(f)\} \text{ if } k(f) \text{ is deterministic}$$

- In practice, considering digitized signals we have (see for example (Antoni et al. [2000](#)))

$$\Gamma(f) = \frac{1}{M} \sum_{k=1}^M \Gamma^k(f)$$

$$\Gamma^{(k)}(f) = \frac{2}{B} \Im \{ k^{(k)}(f) N^{(k)}(f) \Phi^{*(k)}(f) \} \quad 0 < f < N/2 - 1$$

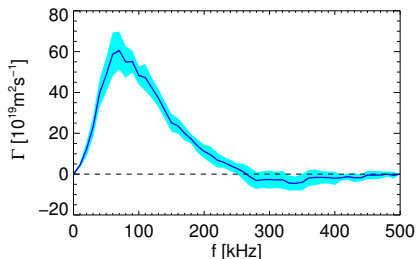
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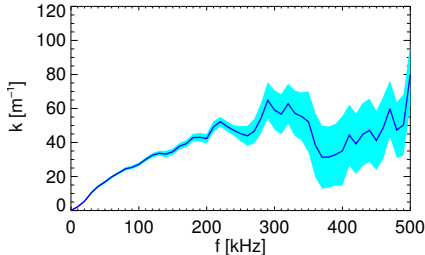


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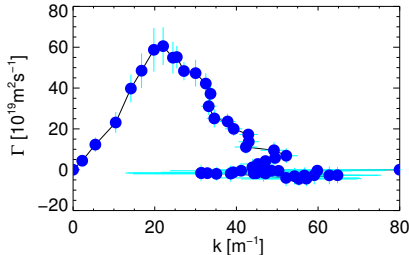


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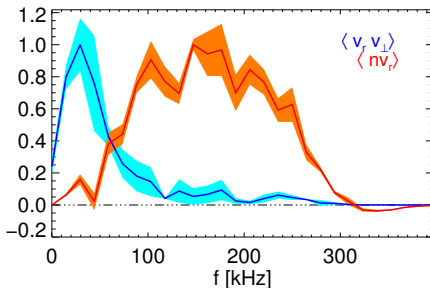
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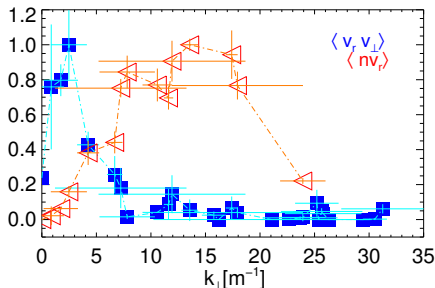


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Ricerca Formazione Innovazione

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- ▶ Again for finite time length T and finite space L we have an estimate

$$\hat{S}(k, \omega) = \frac{1}{LT} E[G_{LT}(k, \omega) G_{LT}^*(k, \omega)]$$
$$\lim_{L, T \rightarrow \infty} \hat{S}(k, \omega) = S(k, \omega)$$

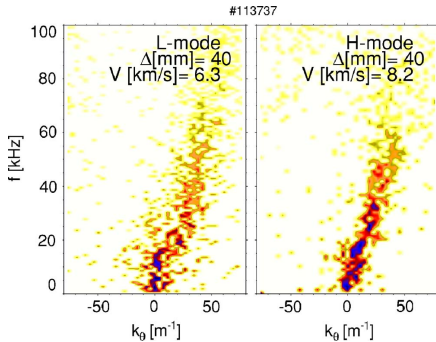
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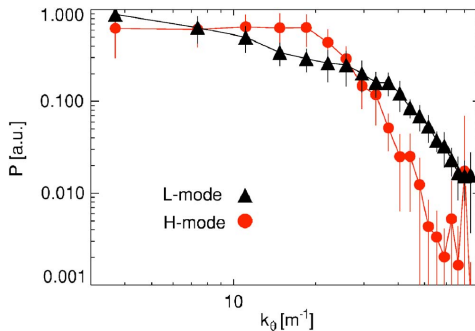
- ▶ If, as usual, only 2 points are available, the spectrum is reconstructed on a statistical basis:

$$\hat{S}_L(k, \omega) = \hat{S}_L(p\delta k, 2\pi n\Delta f) = \frac{1}{M} \sum_{j=1}^M S_n^{(j)} I_p[k_n^j]$$
$$I_p[k_n^j] = \begin{cases} 1 & \text{for } (p - 1/2)\Delta k < k_n^{(j)} < (p + 1/2)\Delta k \\ 0 & \text{elsewhere} \end{cases}$$

- Spectral power density from GPI LoS on NSTX (Agostini et al. [2007](#))



- ▶ We can consequently compute $S(k) = \int_{-\infty}^{+\infty} S(k, \omega) \frac{d\omega}{2\pi}$



- ▶ The Fourier decomposition uses trigonometric functions as orthogonal basis
- ▶ These functions oscillates forever, i.e. the information content of a generic function is spread over all the spectral component
- ▶ Thus Fourier decomposition is not suitable for processes highly localized in time/space. We can use **Wavelet Transform**(Farge 1992)
- ▶ A Wavelet is a function $\psi \in L^2(\mathbb{R})$ which satisfies the admissibility condition $C_\psi = \int_{-\infty}^{+\infty} \frac{|\hat{\psi}(\omega)|^2}{|\omega|} d\omega < \infty$, i.e. ψ is a zero mean function $\int_{-\infty}^{+\infty} \psi(t) dt = 0$
- ▶ Defining time-frequency atoms as $\psi_{s,\tau} = \frac{1}{\sqrt{\tau}} \psi\left(\frac{t-s}{\tau}\right)$ the **Continuous Wavelet Transform** is defined as

$$w(s, \tau) = \frac{1}{\sqrt{\tau}} \int_{-\infty}^{+\infty} f(t) \psi^* \left(\frac{t-s}{\tau} \right) dt$$

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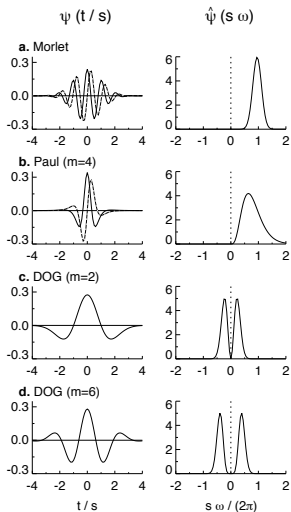
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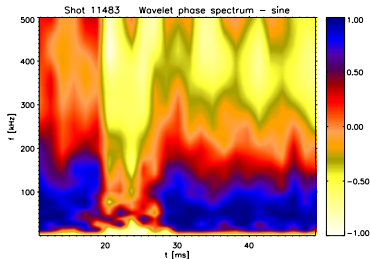
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- ▶ Example of different types of wavelet (Mallat 1999)



- ▶ In analogy to Fourier we can define Wavelet Cross power spectrum and Corresponding phase spectrum (well localized in time/frequency)



- ▶ Phase spectrum between density and potential varies because of variation of the shear \rightarrow responsible for transport reduction (Antoni et al. [2000](#))

- ▶ Wavelet coefficient exhibits similar scaling properties as the fluctuations of the signals at the same

$$\delta_{\tau} f = f(t + \tau) - f(t) \sim \tau^h \Rightarrow |w(t, \tau)| \sim \tau^{h+1/2}$$

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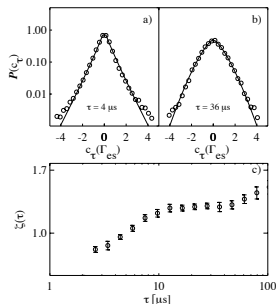
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- ▶ Easy way to compute the **Probability Distribution Function** of normalized fluctuations $C(t, \tau) = \frac{w(t, \tau) - \langle w(t, \tau) \rangle}{\sigma_{\tau}}$. For **self-similar** fluctuations, these should collapse to a single form

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- ▶ **Revealing non self-similarity i.e. Intermittency**



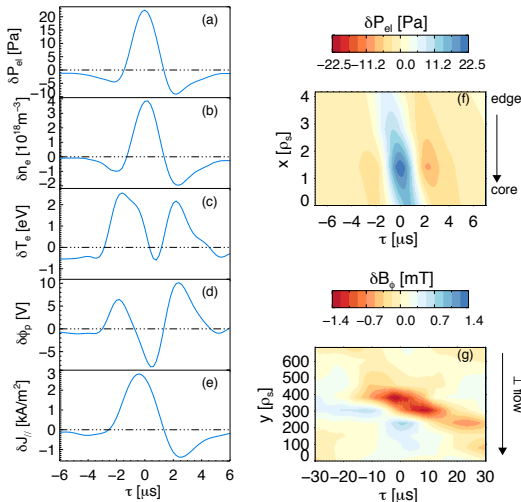
- ▶ Intermittency is due to the presence of strong, sporadic fluctuations
- ▶ The **Local Intermittency Measurements** is a method, based on wavelet, which identifies in time and scales these fluctuations (Antoni et al. 2001)
- ▶ The method is based on the following:

$$\{w(t, \tau)\} = \{w_e(t, \tau)\} \oplus \{w_g(t, \tau)\} \quad \text{with } F(\tau) = \frac{\langle w_g(t, \tau)^4 \rangle}{[\langle w_g(t, \tau)^2 \rangle]^2} = 3$$

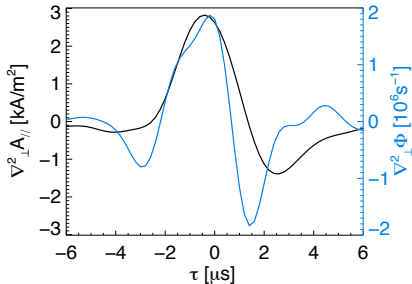
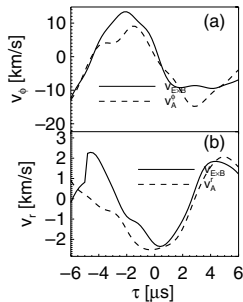
- ▶ The typical fluctuations may be derived using **Conditional Average Procedure**, i.e. averaging different time windows of the signal, each centered around the occurrence of an **Intermittent Events** or **blobs**

Example of structures

- Conditional average may be applied to different signals using the same trigger

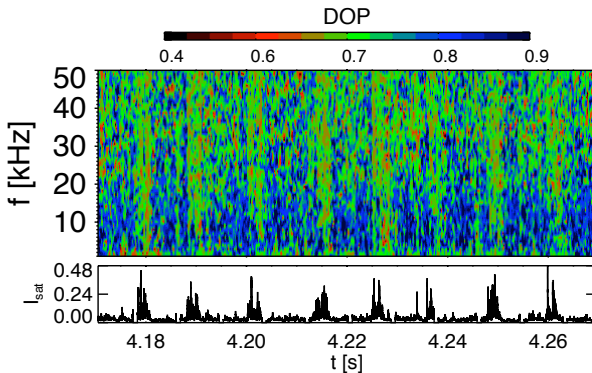


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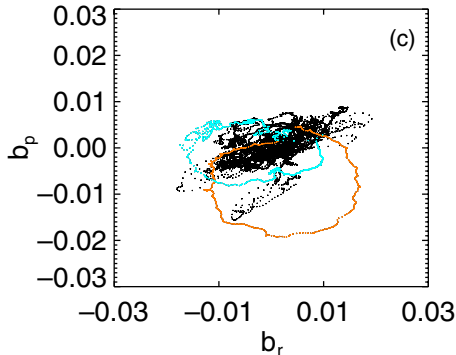


- ▶ Example of **Drift-Kinetic Alfvén vortices** (Martines et al. 2009; Vianello et al. 2010)

- **Degree of Polarization**, which tests, frequency by frequency by frequency, the plane wave ansatz (Vianello et al. [2011](#))



- ▶ The **hodogram**, which follows the trajectory of fluctuating fields, highlighting the state of polarization (Vianello et al. [2011](#))



- ▶ High temporal and spatial resolution are needed for better characterization of the plasma. But two points still gives a bunch of information
- ▶ Fourier transform allows estimate of quantities directly comparable with theories
- ▶ Often localized events (in space or time) require more sophisticated tools which maintain the locality of the information
- ▶ As much as possible correlation between different diagnostics are generally needed for an adeguated comprehension

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