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(*2.3a*)
(*What is  $\omega$  for the two systems (1) and (2), respectively?*)
(*System (1)*)
x1[x, y] =  $\mu x - 6y - 2x^3$ ;
y1[x, y] =  $6x + \mu y + 4y^3$ ;
(*System (2)*)
x2[x, y] =  $\mu x + y - x^2$ ;
y2[x, y] =  $-x + \mu y + 2x^2$ ;
(*Hopf bif. at origin for  $\mu=0$  with  $\dot{y} = \omega x$ ,  $\dot{x} = -\omega y$  :*)
Eqs = {{x1[x, y], y1[x, y]}, {x2[x, y], y2[x, y]}} /.  $\mu \rightarrow 0$ ;
Eqs[[1]]
{-2 x^3 - 6 y, 6 x + 4 y^3}
(*For system one we can see that  $-6y = -\omega y$  and  $6x = \omega x \rightarrow \omega_1 = 6$ ;*)

Eqs[[2]]
{-x^2 + y, -x + 2 x^2}
(*For system two we get  $y = -\omega y$  and  $-x = \omega x$ , thus  $\omega_2 = -1$ ;*)

(*2.3b) Determine f and g for the systems (1) and (2)*)
(*  $x = -\omega y + f(x, y)$ ,  $y = \omega x + g(x, y)$ ;
and the computed equations(Eqs) we get f(x,y) and g(x,y) by comparison;
From system one  $\rightarrow f_1(x, y) = -2x^3$  and  $g_1(x, y) = 4y^3$ ;
From system two  $\rightarrow f_2(x, y) = -x^2$  and  $g_2(x, y) = 2x^2$ ;*)

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(*2.3c) Determine a for the two systems (1) and (2)*)
(*System one*)
Clear["Global`*"]
 $\omega = \{6, -1\};$ 
fx = D[{-2 x^3, -x^2}, x];
fxx = D[fx, x];
fxxx = D[fxx, x];
fxy = D[fx, y];
fxyy = D[fxy, y];
fy = D[{-2 x^3, -x^2}, y];
fyy = D[fy, y];
gx = D[{4 y^3, 2 x^2}, x];
gxx = D[gx, x];
gxy = D[gx, y];
gy = D[{4 y^3, 2 x^2}, y];
gyy = D[gy, y];
gyyy = D[gyy, y];
Solve[
  16 a == fxxx[[1]] + fxyy[[1]] + gxyy[[1]] + gyyy[[1]] + 1 /  $\omega$ [[1]] * (fxy[[1]] * (fxx[[1]] + fyy[[1]]) -
    gxy[[1]] * (gxx[[1]] + gyy[[1]]) - fxx[[1]] * gxx[[1]] + fyy[[1]] * gyy[[1]]), a]
Solve[
  16 a == fxxx[[2]] + fxyy[[2]] + gxyy[[2]] + gyyy[[2]] + 1 /  $\omega$ [[2]] * (fxy[[2]] * (fxx[[2]] + fyy[[2]]) -
    gxy[[2]] * (gxx[[2]] + gyy[[2]]) - fxx[[2]] * gxx[[2]] + fyy[[2]] * gyy[[2]]), a]
{{a ->  $\frac{3}{4}$ }}
{{a ->  $-\frac{1}{2}$ }}

(*2.3d*)
(*Draw phase portraits of the global dynamics for positive and
negative  $\mu$  for each of the systems (1) and (2). Make sure that
these phase portraits verify the criteria you found in subtask*)

(*From 2.3c we see that system (1) is subcritical ( $a < 0$ );
and system (2) is supercritical ( $a < 0$ *)
(*subcritical ( $a < 0$ *)
(*First case where  $\mu < 0$  *)
xDot[x_, y_,  $\mu$ _] :=  $\mu x - 6 y - 2 x^3$ ;
yDot[x_, y_,  $\mu$ _] :=  $6 x + \mu y + 4 y^3$ ;
mu1 = {-1, 1};
Eqs1 = Transpose[{x1[x, y], y1[x, y]} /.  $\mu \rightarrow \mu 1$ ];
p1 =
  StreamPlot[Eqs1[[1]], {x, -1, 1}, {y, -1, 1}, PlotLabel -> " $\mu < 0$ \nSystem (1)"];
minx = -0.3; maxx = 0.3; miny = -0.3; maxy = 0.3;
s[x0_, y0_] = NDSolve[{x'[t] == xDot[x[t], y[t],  $\mu$ ], y'[t] == yDot[x[t], y[t],  $\mu$ ]},

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x[0] = x0, y[0] = y0 /.  $\mu \rightarrow -1$ , {x, y}, {t, -1, 1}];
initialCondition = Join[Table[{0, y}, {y, miny, maxy, 0.1}],
  Table[{minx, y}, {y, miny, maxy, 0.1}], Table[{maxx, y}, {y, miny, maxy, 0.1}],
  Table[{x, miny}, {x, minx, maxx, 0.1}], Table[{x, maxy}, {x, minx, maxx, 0.1}]];
p12 =
  Show[Table[ParametricPlot[Evaluate[{x[t], y[t]} /. s[initialCondition[[i, 1]],
    initialCondition[[i, 2]]], {t, -1, 1}, PlotRange  $\rightarrow$ 
    {{minx, maxx}, {miny, maxy}}], {i, Length[initialCondition]}] /.
    Line[x_]  $\rightarrow$  {Arrowheads[{0., 0.05, 0.05, 0.05, 0.}], Arrow[x]},
    PlotLabel  $\rightarrow$  "Subcritical stable spiral"];

(*Second case where  $\mu > 0$  *)
p2 =
  StreamPlot[Eqs1[[2]], {x, -1, 1}, {y, -1, 1}, PlotLabel  $\rightarrow$  " $\mu > 0$ \nSystem (1)"];
s[x0_, y0_] = NDSolve[{x'[t] == xDot[x[t], y[t],  $\mu$ ], y'[t] == yDot[x[t], y[t],  $\mu$ ],
  x[0] == x0, y[0] == y0} /.  $\mu \rightarrow 1$ , {x, y}, {t, -1, 1}];
initialCondition = Join[Table[{0, y}, {y, miny, maxy, 0.1}],
  Table[{minx, y}, {y, miny, maxy, 0.1}], Table[{maxx, y}, {y, miny, maxy, 0.1}],
  Table[{x, miny}, {x, minx, maxx, 0.1}], Table[{x, maxy}, {x, minx, maxx, 0.1}]];
p22 =
  Show[Table[ParametricPlot[Evaluate[{x[t], y[t]} /. s[initialCondition[[i, 1]],
    initialCondition[[i, 2]]], {t, -1, 1}, PlotRange  $\rightarrow$ 
    {{minx, maxx}, {miny, maxy}}], {i, Length[initialCondition]}] /.
    Line[x_]  $\rightarrow$  {Arrowheads[{0., 0.05, 0.05, 0.05, 0.}], Arrow[x]},
    PlotLabel  $\rightarrow$  "Subcritical unstable spiral"];

(*System (2): supercritical case*)
(*First case where  $\mu < 0$  *)
xDot2[x_, y_,  $\mu$ ] :=  $\mu x + y - x^2$ ;
yDot2[x_, y_,  $\mu$ ] :=  $-x + \mu y + 2x^2$ ;

mu2 = {-0.1, 0.1};
Eqs2 = Transpose[{x2[x, y], y2[x, y]} /.  $\mu \rightarrow \mu 2$ ];
p3 = StreamPlot[Eqs2[[1]], {x, -1, 1}, {y, -1, 1}, PlotLabel  $\rightarrow$  " $\mu < 0$ \nSystem (2)"];
s[x0_, y0_] = NDSolve[{x'[t] == xDot[x[t], y[t],  $\mu$ ],
  y'[t] == yDot[x[t], y[t],  $\mu$ ], x[0] == x0, y[0] == y0} /.  $\mu \rightarrow -1$ ,
  {x, y}, {t, -1.5, 1.5}];
initialCondition = Join[Table[{0, y}, {y, miny, maxy, 0.1}],
  Table[{minx, y}, {y, miny, maxy, 0.1}], Table[{maxx, y}, {y, miny, maxy, 0.1}],
  Table[{x, miny}, {x, minx, maxx, 0.1}], Table[{x, maxy}, {x, minx, maxx, 0.1}]];
p32 =
  Show[Table[ParametricPlot[Evaluate[{x[t], y[t]} /. s[initialCondition[[i, 1]],
    initialCondition[[i, 2]]], {t, -1.5, 1.5}, PlotRange  $\rightarrow$ 
    {{minx, maxx}, {miny, maxy}}], {i, Length[initialCondition]}] /.
    Line[x_]  $\rightarrow$  {Arrowheads[{0., 0.05, 0.05, 0.05, 0.}], Arrow[x]},
    PlotLabel  $\rightarrow$  "Supercritical stable spiral"];
(*Second case where  $\mu > 0$  *)

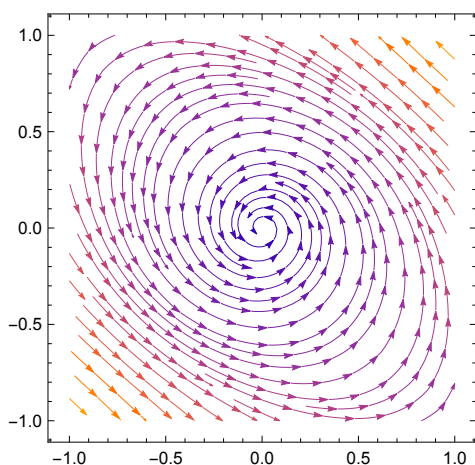
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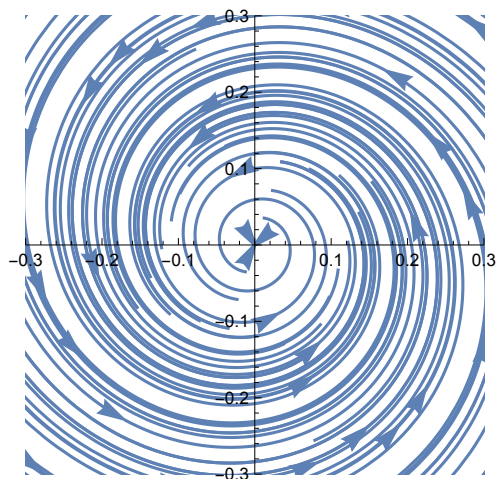
p4 =
  StreamPlot[Eqs2[[2]], {x, -1, 1}, {y, -1, 1}, PlotLabel → "μ > 0\nSystem (2)"];
s[x0_, y0_] = NDSolve[{x'[t] == xDot[x[t], y[t], μ],
  y'[t] == yDot[x[t], y[t], μ], x[0] == x0, y[0] == y0} /. μ → 1,
  {x, y}, {t, -1.5, 1.5}];
initialCondition = Join[Table[{0, y}, {y, miny, maxy, 0.1}],
  Table[{minx, y}, {y, miny, maxy, 0.1}], Table[{maxx, y}, {y, miny, maxy, 0.1}],
  Table[{x, miny}, {x, minx, maxx, 0.1}], Table[{x, maxy}, {x, minx, maxx, 0.1}]];
p42 =
  Show[Table[ParametricPlot[Evaluate[{x[t], y[t]} /. s[initialCondition[[i, 1]],
    initialCondition[[i, 2]]], {t, -1.5, 1.5}, PlotRange →
    {{minx, maxx}, {miny, maxy}}], {i, Length[initialCondition]}] /.
    Line[x_] → {Arrowheads[{0., 0.05, 0.05, 0.05, 0.}], Arrow[x]},
  PlotLabel → "Supercritical unstable spiral"];
GraphicsRow[{p1, p12}]
GraphicsRow[{p2, p22}]
GraphicsRow[{p3, p32}]
GraphicsRow[{p4, p42}]
(*From the plots we can draw the conclusion that they agree with
  what we predicted thus verifying our criteria in 2.3c (see page 254-
  255 in the book,fig 8.2.3 and 8.2.5).*)

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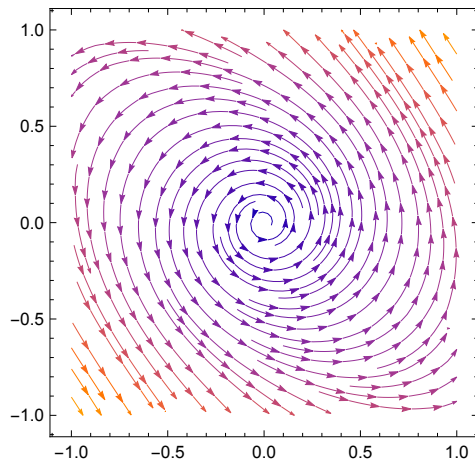
$\mu < 0$
System (1)



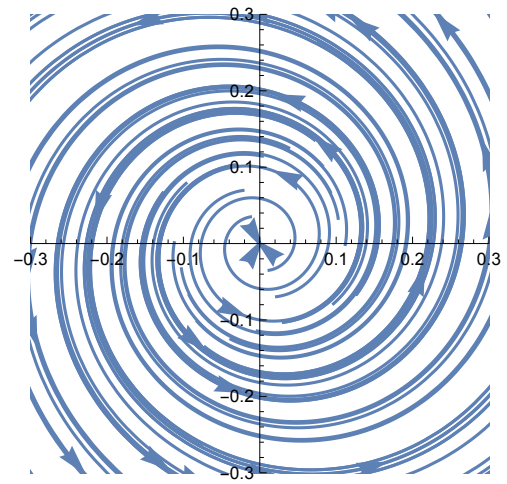
Subcritical stable spiral



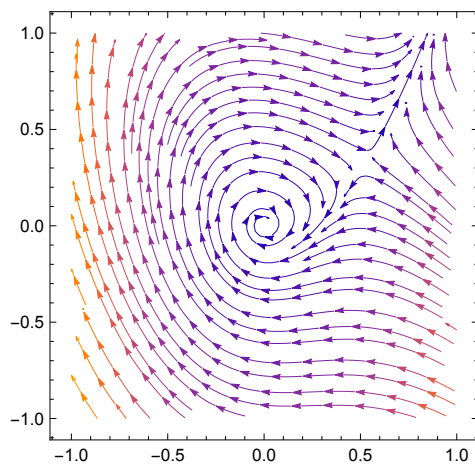
$\mu > 0$
System (1)



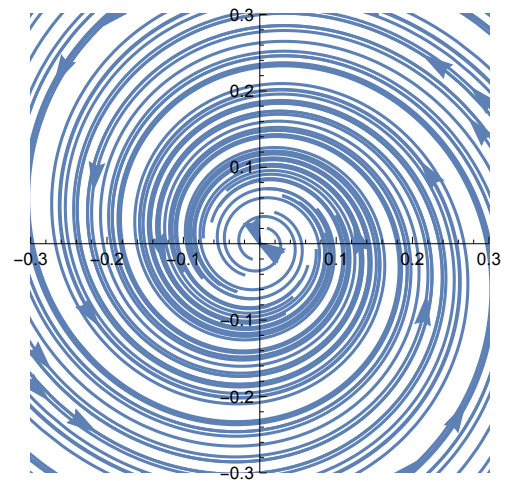
Subcritical unstable spiral



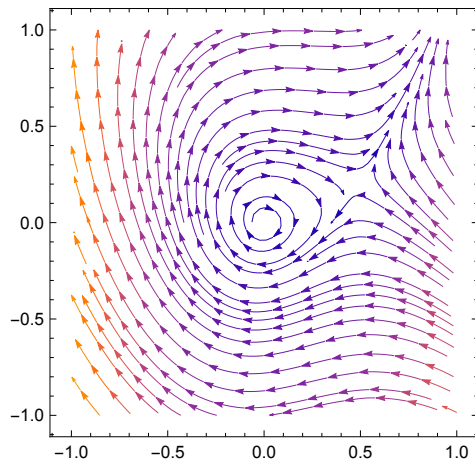
$\mu < 0$
System (2)



Supercritical stable spiral



$\mu > 0$
System (2)



Supercritical unstable spiral

