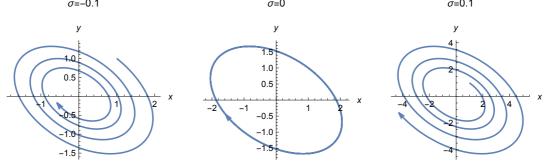
```
(*1.4a*)
(*Analytically compute the eigenvalues, \lambda 1 and \lambda 2,
of M\sigma and confirm that they constitute a complex conjugate pair*)
f[x, y, \sigma] = (\sigma + 1) * x[t] + 3 * y[t];
g[x, y, \sigma] = -2 * x[t] + (\sigma - 1) * y[t];
M = \{ \{ \sigma + 1, 3 \}, \{ -2, \sigma - 1 \} \}; (*from the eqs above*)
eigenVal = Eigenvalues[M]
\{-i \sqrt{5} + \sigma, i \sqrt{5} + \sigma\}
(*1.4b*)
(*Solve the dynamical system
    analytically for the initial values x(0) = u and y(0) = v*
x1[t_] = \{x[t], y[t]\};
dynS = x1'[t] = M.x1[t];
solution = DSolve[dynS, {x, y}, t];
x1[t_-, x0_-, y0_-, \sigma_-] = \{x[t], y[t]\} /. solution[1] /. \{C[1] \rightarrow u, C[2] \rightarrow v\}
\left\{\frac{3 e^{\mathsf{t} \, \sigma} \, \mathsf{v} \, \mathsf{Sin} \big[\, \sqrt{5} \, \, \mathsf{t} \, \big]}{\sqrt{5}} + \frac{1}{5} e^{\mathsf{t} \, \sigma} \, \mathsf{u} \, \left(5 \, \mathsf{Cos} \big[\, \sqrt{5} \, \, \mathsf{t} \, \big] + \sqrt{5} \, \, \mathsf{Sin} \big[\, \sqrt{5} \, \, \mathsf{t} \, \big] \right),
   -\frac{2 e^{\mathsf{t} \, \sigma} \, \mathsf{u} \, \mathsf{Sin} \big[ \, \sqrt{\mathsf{5}} \, \, \mathsf{t} \, \big]}{\sqrt{\mathsf{5}}} \, + \frac{\mathsf{1}}{\mathsf{5}} \, e^{\mathsf{t} \, \sigma} \, \mathsf{v} \, \left( \mathsf{5} \, \mathsf{Cos} \big[ \, \sqrt{\mathsf{5}} \, \, \mathsf{t} \, \big] \, - \, \sqrt{\mathsf{5}} \, \, \mathsf{Sin} \big[ \, \sqrt{\mathsf{5}} \, \, \mathsf{t} \, \big] \, \right) \Big\}
(*1.4c*)
(*Plot in three figures representative trajectories for \sigma=-1/10,
\sigma=0 and \sigma=1/10*)
f1 = x1[t, 1, 1, -0.1];
f1[[1]];
p1 = ParametricPlot[x1[t, 1, 1, -0.1] /. u \rightarrow 1 /. v \rightarrow 1, {t, 0, 10},
        AxesLabel \rightarrow {x, y}, PlotLabel \rightarrow "\sigma=-0.1"] /. Line \rightarrow Arrow;
p2 = ParametricPlot[x1[t, 1, 1, 0] /. u \rightarrow 1 /. v \rightarrow 1,
         \{t, 0, 10\}, AxesLabel \rightarrow \{x, y\}, PlotLabel \rightarrow "\sigma=0"] /. Line \rightarrow Arrow;
p3 = ParametricPlot[x1[t, 1, 1, 0.1] /. u \rightarrow 1/. v \rightarrow 1, {t, 0, 10},
        AxesLabel \rightarrow {x, y}, PlotLabel \rightarrow "\sigma=0.1"] /. Line \rightarrow Arrow;
GraphicsRow[{p1, p2, p3}]
                     \sigma = -0.1
                                                                        \sigma=0
                                                                                                                      \sigma=0.1
```



```
(*1.4d*)
(*When \sigma=0 the system has an invariant orbit in the form of
   an ellipse. Analytically compute the period of the ellips0∗)
Solve[x1[0, u, v, 0] = x1[t, u, v, 0], t]
\left\{ \left\{ t \to \left| \begin{array}{c} 2 \; \pi \; \mathbb{c}_1 \\ \hline \sqrt{5} \end{array} \right. \; \text{if} \; \; \mathbb{c}_1 \in \mathbb{Z} \; \right\} \right\}
(*e) Analytically calculate the length ratio
 between the major and minor axes of the ellipse*)
xyVal = x1[t, 1, 1, 0] /. u \rightarrow 1 /. v \rightarrow 1;
(*Circle equation r^2=x^2+y^2*)
radius = Sqrt[(xyVal[1])^2 + (xyVal[2])^2];
a = FindMaximum[radius, {t, t0}];
b = FindMinimum[radius, {t, t0}];
ratio = a/b;
ratio[1, 1](*The ratio is equivalent with (1+sqrt(5))/2*)
1.39095
(*1.4f*)
(*Analytically calculate the direction
 of the major ellipse axis in the (x,y) plane*)
(*As in the previous task where \sigma=
 0. We get t-position from the major ellipse and normalize.*)
dirMajor = xyVal /. {u \rightarrow 1, v \rightarrow 1, \sigma \rightarrow 0, a[2][1]};
Normalize[dirMajor]
\{0.850651, -0.525731\}
```