# Prosilica GiGE PvAPI SDK Documentation

# Jeren Suzuki

# Last Edited 29th October 2012

# ${\bf Contents}$

		Setting Started Setting up the Proper Tools		
2	Dov	vnloading Tools		
3	Installing Tools			
	3.1	Compiling ListCameras for §4.1		
	3.2	Compiling Other Executables		
4	Networking			
	4.1	Steps to Connect to Camera		
	4.2	Connecting to Camera		
		MTU		

# 1 Getting Started

### 1.1 Setting up the Proper Tools

Currently, Ubuntu is the primary supported Linux  $OS^1$  and if possible, should be used. While this guide is centered around Ubuntu, similar commands can be used to get the SDK to work on other platforms. Furthermore, make sure that the GCC version is greater than 4.1. You will also need:

```
1. GTK+ \geq 2.0
2. glib-2.0 \geq 2.12.0
3. atk \geq 1.9.0
4. pango \geq 1.12.0
```

### 5. cairo $\geq 1.2.0$

# 2 Downloading Tools

#### Download:

```
http://www.alliedvisiontec.com/fileadmin/content/PDF/Software/Prosilica_software/Prosilica_SDK/AVT_GigE_SDK_Linux.tgz and wxGTK with a version number of at least 2.6 from:
http://www.wxwidgets.org/downloads/2
```

## 3 Installing Tools

cd into the folder where you have downloaded the two previous files and untar them with:

```
tar xvf AVT_GigE_SDK_Linux.tgz

tar xvf wxGTK-2.8.12.tar.gz

cd into the wxGTK-2.8.12<sup>3</sup> folder you untar'ed and enter in Terminal:

mkdir static

cd static

../configure --enable-shared=no --enable-static=yes --enable-unicode=yes --prefix=$PWD

make

cd out of the wxGTK-2.8.12 folder and cd into the AVT GigE SDK directory.

cd examples

nano ARCH<sup>4</sup>
```

<sup>&</sup>lt;sup>1</sup>http://www.alliedvisiontec.com/us/products/software/windows/avt-pvapi-sdk.html

<sup>&</sup>lt;sup>2</sup>This is needed for the SampleViewer program later on. While this program is not necessary in order to use the camera, it does help to see what your pictures will look like so you can focus the lens appropriately and ensure that the camera is pointed in the right direction.

<sup>&</sup>lt;sup>3</sup>The version number at the time of writing is 2.8.12, mileage may vary.

<sup>&</sup>lt;sup>4</sup>Or use whatever text editor you prefer, vi, emacs, gedit, etc.

```
Edit the following lines:

CC = g++-{CVER}

into

CC = g++
```

Save the file and cd into the SampleViewer folder nano Makefile

Change the WX\_DIR to the location of the static folder in wxGTK-2.8.12

e.g.

WX\_DIR=/mydisks/home/jsuzuki/wxGTK-2.8.12/static

Once this has been changed,
make sample
and it should make a working executable called SampleViewer.
make install

to install the executable and it should move the file into ../../bin-pc/x64 if you are running on a 64-bit OS or ../../bin-pc/x86 if you are running on a 32-bit OS.

## 3.1 Compiling ListCameras for §4.1

Starting from the AVT GigE SDK folder, cd into examples/ListCameras and enter make sample make install

This will be needed later.

### 3.2 Compiling Other Executables

Compiling any of the other executables is as easy as cd'ing into that directory and: make sample make install

### 4 Networking

Once you have the tools to access the camera, you'll need to find the camera on the network. The camera comes with it's own built-in IP that cannot be changed (As far as I know). You will have to change your network preferences to match that of the camera.

If you are interested in setting the camera up with the network, see §4.2. If you are interested in the steps leading up to connecting the camera, see §4.1.

### 4.1 Steps to Connect to Camera

Compile ListCameras as per the instructions above and cd into a directory with a working ListCameras executable. Then:

1. sudo ifconfig eth0 192.168.123.1 netmask 255.255.255.0

- 2. sudo if config tcpdump -n src port 3956 -i  $eth0^5$
- 3. ./ListCameras

You will be prompted for your password, enter it normally. Step 1 sets the computer to manually have an IP of 192.168.123.1 on the netmask 255.255.255.0. An important note is that the netmask and IP must correlate to each other<sup>6</sup>. Step 2 monitors data on the network and sees where information is being used through which addresses. Step 3 is a program supplied by the PvAPI SDK and which looks on the network for any cameras. It basically pings each address on the subnet and sees if any cameras respond. After running Step 2, an IP should appear on the terminal line. e.g., 169.254.66.255

### 4.2 Connecting to Camera

run:

sudo ifconfig eth0 169.254.66.99 netmask 255.255.0.0

This sets the eth0 interface to the above settings. The first three numbers of the IP address (169, 254, 66) must be the same for both the camera and the computer. The last number is just the identifier on the network and requires that no two numbers are being used simultaneously.

#### 4.3 MTU

The original PvAPI documentation recommends having an ethernet card capable of Jumbo Frames, which correspond to an MTU value of 9000 or higher. Typically 9000. While our ethernet card is incapable of having an MTU higher than 1500, we see no image quality degradation or loss of data with our current setup. While we may explore more frames/second in the future and run into problems with MTU throttling, that does not concern us at this time.

 $<sup>^5</sup>$ Replace eth0 with your network interface adapter name from ifconfig -a

<sup>&</sup>lt;sup>6</sup>http://en.wikipedia.org/wiki/Subnetwork