

# Prosilica GiGE PvAPI SDK Documentation

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# 1 Getting Started

## 1.1 Setting up the Proper Tools

Currently, Ubuntu is the primary supported Linux OS<sup>1</sup> and if possible, should be used. While this guide is centered around Ubuntu, similar commands can be used to get the SDK to work on other platforms. Furthermore, make sure that the GCC version is greater than 4.1. You will also need:

1.  $\text{GTK+} \geq 2.0$
2.  $\text{glib-2.0} \geq 2.12.0$
3.  $\text{atk} \geq 1.9.0$
4.  $\text{pango} \geq 1.12.0$
5.  $\text{cairo} \geq 1.2.0$

## 2 Downloading Tools

Download:

[http://www.alliedvisiontec.com/fileadmin/content/PDF/Software/Prosilica\\_software/Prosilica\\_SDK/AVT\\_GigE\\_SDK\\_Linux.tgz](http://www.alliedvisiontec.com/fileadmin/content/PDF/Software/Prosilica_software/Prosilica_SDK/AVT_GigE_SDK_Linux.tgz)  
and wxGTK with a version number of at least 2.6 from:  
<http://www.wxwidgets.org/downloads/><sup>2</sup>

## 3 Installing Tools

cd into the folder where you have downloaded the two previous files and untar them with:

```
tar xvf AVT_GigE_SDK_Linux.tgz
tar xvf wxGTK-2.8.12.tar.gz
```

cd into the wxGTK-2.8.12<sup>3</sup> folder you untar'ed and enter in Terminal:

```
mkdir static
cd static
../configure --enable-shared=no --enable-static=yes --enable-unicode=yes --prefix=$PWD
make
cd out of the wxGTK-2.8.12 folder and cd into the AVT GigE SDK directory.
cd examples
nano ARCH4
```

---

<sup>1</sup><http://www.alliedvisiontec.com/us/products/software/windows/avt-pvapi-sdk.html>

<sup>2</sup>This is needed for the SampleViewer program later on. While this program is not necessary in order to use the camera, it does help to see what your pictures will look like so you can focus the lens appropriately and ensure that the camera is pointed in the right direction.

<sup>3</sup>The version number at the time of writing is 2.8.12, mileage may vary.

<sup>4</sup>Or use whatever text editor you prefer, vi, emacs, gedit, etc.

Edit the following lines:

```
CC = g++-{CVER}  
into  
CC = g++
```

Save the file and `cd` into the `SampleViewer` folder

```
nano Makefile
```

Change the `WX_DIR` to the location of the static folder in `wxGTK-2.8.12`

e.g.,

```
WX_DIR=/mydisks/home/jsuzuki/wxGTK-2.8.12/static
```

Once this has been changed,

```
make sample
```

and it should make a working executable called `SampleViewer`.

```
make install
```

to install the executable and it should move the file into `../bin-pc/x64` if you are running on a 64-bit OS or `../bin-pc/x86` if you are running on a 32-bit OS.

### 3.1 Compiling ListCameras for §4.1

Starting from the AVT GigE SDK folder, `cd` into `examples/ListCameras` and enter

```
make sample
```

```
make install
```

This will be needed later.

### 3.2 Compiling Other Executables

Compiling any of the other executables is as easy as `cd`'ing into that directory and:

```
make sample
```

```
make install
```

## 4 Networking

Once you have the tools to access the camera, you'll need to find the camera on the network. The camera comes with its own built-in IP that cannot be changed (As far as I know). You will have to change your network preferences to match that of the camera.

If you are interested in setting the camera up with the network, see §4.2.

If you are interested in the steps leading up to connecting the camera, see §4.1.

### 4.1 Steps to Connect to Camera

Compile `ListCameras` as per the instructions above and `cd` into a directory with a working `ListCameras` executable. Then:

1. `sudo ifconfig eth0 192.168.123.1 netmask 255.255.255.0`
2. `sudo ifconfig tcpdump -n src port 3956 -i eth05`
3. `./ListCameras`

You will be prompted for your password, enter it normally. Step 1 sets the computer to manually have an IP of 192.168.123.1 on the netmask 255.255.255.0. An important note is that the netmask and IP must correlate to each other<sup>6</sup>. Step 2 monitors data on the network and sees where information is being used through which addresses.

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<sup>5</sup>Replace `eth0` with your network interface adapter name from `ifconfig -a`

<sup>6</sup><http://en.wikipedia.org/wiki/Subnetwork>

Step 3 is a program supplied by the PvAPI SDK and which looks on the network for any cameras. It basically pings each address on the subnet and sees if any cameras respond. After running Step 2, an IP should appear on the terminal line. e.g., 169.254.66.255

## 4.2 Connecting to Camera

run:

```
sudo ifconfig eth0 169.254.66.99 netmask 255.255.0.0
```

This sets the eth0 interface to the above settings. The first three numbers of the IP address (169, 254, 66) must be the same for both the camera and the computer. The last number is just the identifier on the network and requires that no two numbers are being used simultaneously.

## 4.3 MTU

The original PvAPI documentation recommends having an ethernet card capable of Jumbo Frames, which correspond to an MTU value of 9000 or higher. Typically 9000. While our ethernet card is incapable of having an MTU higher than 1500, we see no image quality degradation or loss of data with our current setup. While we may explore more frames/second in the future and run into problems with MTU throttling, that does not concern us at this time.