

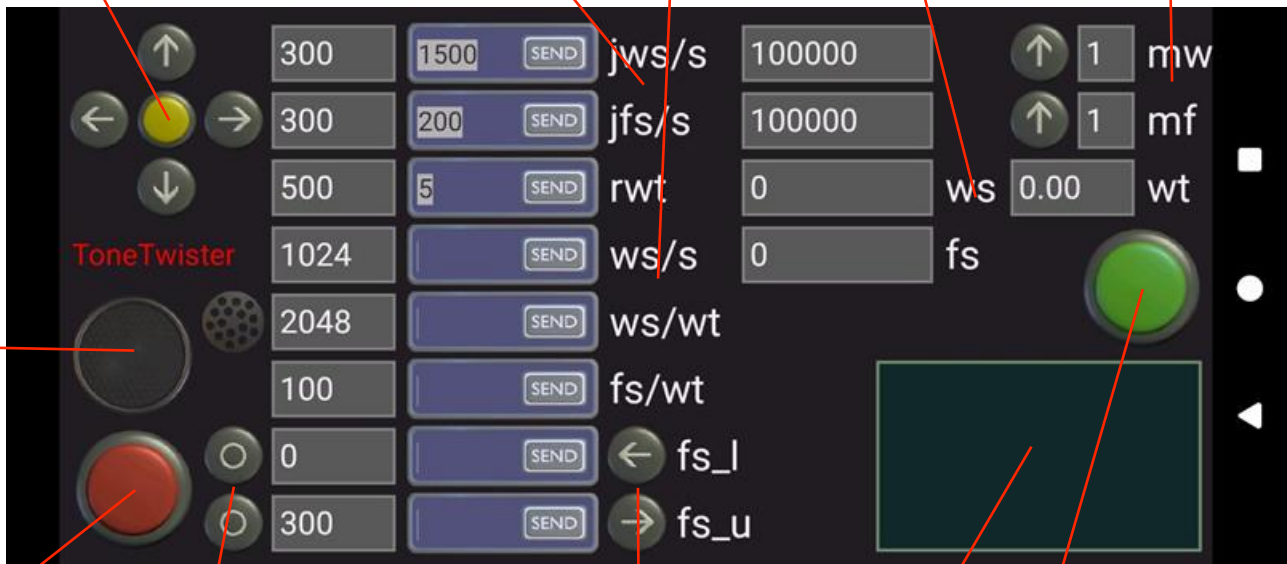
jws/s - winder steps per second for jog
jfs/s - feed steps per second for job

mw - winder microstepping fraction (1/x)
mf - feed microstepping fraction (1/x)

rwt - required number of winder turns
ws/s - winder steps per second
ws/wt - winder steps per winder turn
fs/wt - feed steps per winder turn
fs_l - lower limit for feed steps
fs_u - upper limit for feed steps

Jog motors
Up/down - winder
Left/right - feed
Speed set by jws/s and jf/s
Middle button - set "home" reference position

ws - winder steps from reference
fs - feed steps from reference
wt - winder turns from start



Flashes when connected

Kill

Set feed lower/upper limits to current fs value

Move feed (fs) to lower/upper limit

Terminal

Wind