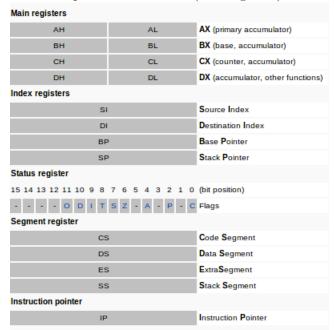
## Chapter 1

# Assembly

### 1.1 Registers

What are registers for?

- Store instructions
- Store result of operations
- Manipulate data in them (shift registers)



Why EAX,EBX,ECX? Registers AL,AH,BL,BH,CL,CH,DL,DH are of 16 bits each and can be used in pairs: AX, BX, CX, DX

#### 1.2 Hello world

```
section .data
        hello:
                    db 'Hello world!',10
        helloLen: equ \$-hello
                                              ; Length of the 'Hello world'
                                             ; (I'll explain soon)
section .text
        global _start
_start:
                             ; The system call for write (sys_write)
        mov eax,4
        mov ebx,1
                             ; File descriptor 1 - standard output
        mov ecx,hello ; Put the offset of hello in ecx
mov edx,helloLen ; helloLen is a constant, so we don't need to say
                               ; mov edx, [helloLen] to get it's actual value
        int 80h
                               ; Call the kernel
                              ; The system call for exit (sys_exit)
        mov eax,1
                              ; Exit with return code of 0 (no error)
        mov ebx,0
        int 80h
```

Then in the terminal:

```
nasm -f elf hello.asm
ld -m elf_i386 -s -o hello hello.o
```

Note that the elf\_i386 is necessary as we are writing 32 bit assembly code in a 64 bit architecture.

1.3. REFERENCES 3

### 1.3 References

- $1.\ \mathtt{https://www.quora.com/What-is-an-intuitive-explanation-of-how-CPU-registers-work}$
- $2. \ \texttt{http://stackoverflow.com/questions/2545192/what-does-x-mean-in-eax-ebx-ecx-in-assembly}$
- 3. http://docs.cs.up.ac.za/programming/asm/derick\_tut/