



Politecnico  
di Torino



# Multimodal Egocentric Action Recognition

Advanced Machine Learning / Data Analysis and Artificial Intelligence

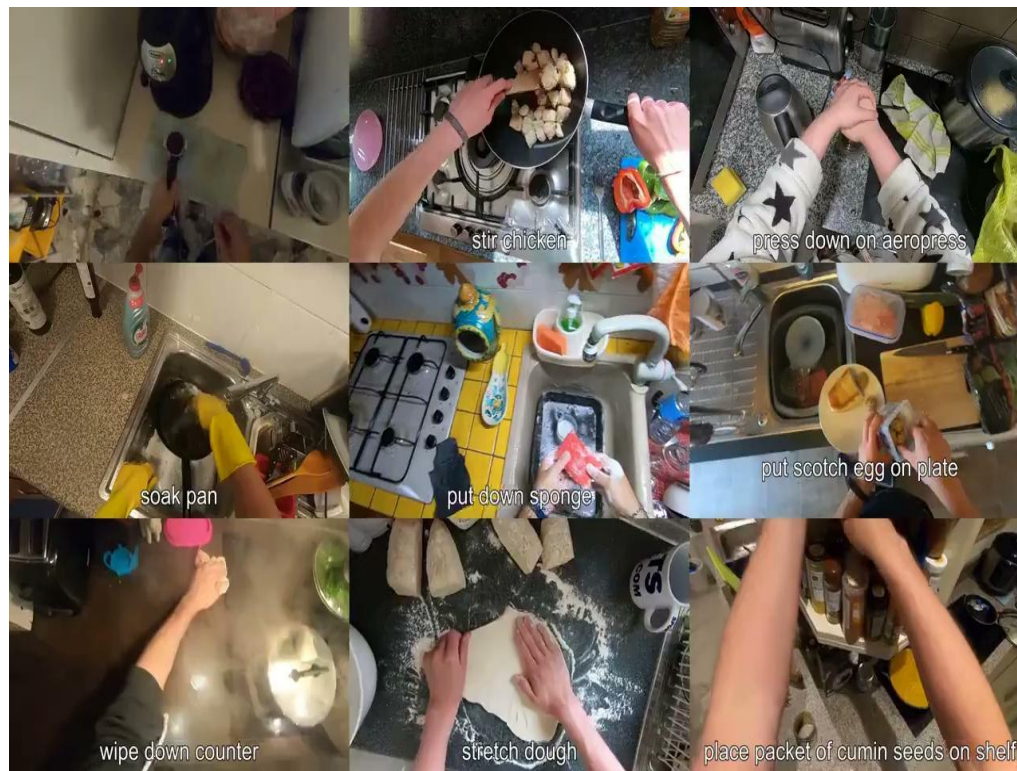
2023/2024

Teaching Assistant:

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# Egocentric Vision



# Why Egocentric Action Recognition?

Learn **how humans interact with world** and improve human-robot cooperation



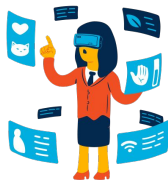
Assistive robotics



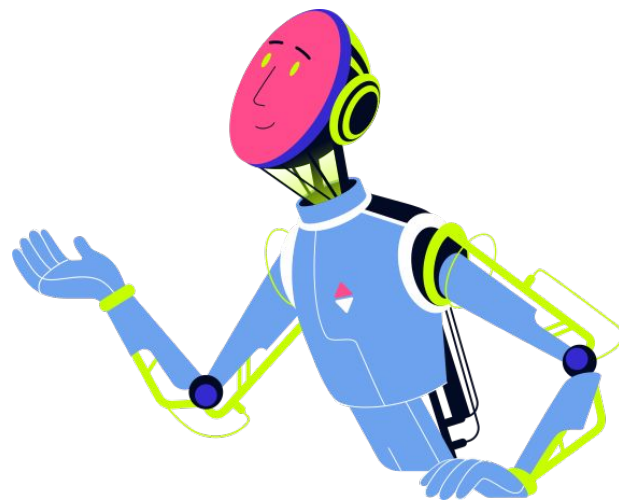
Autonomous driving



Industrial applications

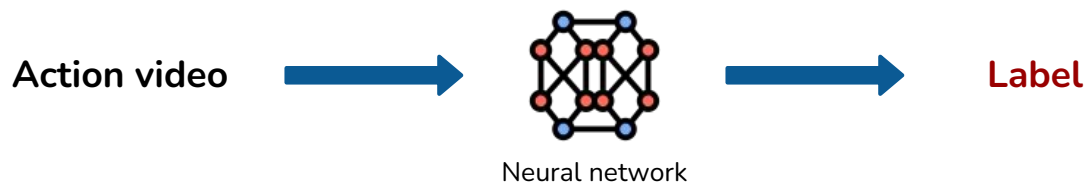


Augmented reality

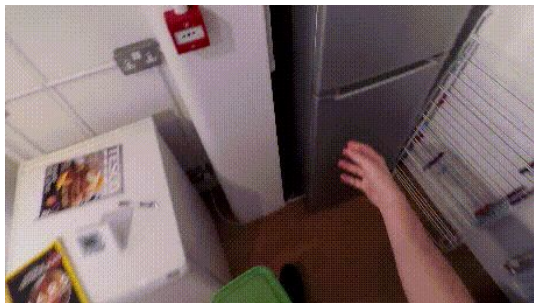


# Egocentric Action Recognition (EAR)

A classification problem that aims to assign **labels** to **videos**



## Examples



*Open fridge*



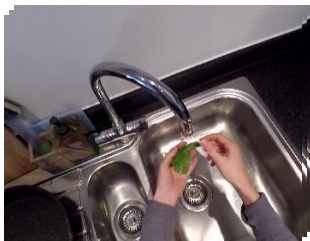
*Close oil*



*Place pan on hob*

# Egocentric Action Recognition (EAR)

Videos provide **multiple sources of information** (a.k.a *modalities*) that we can use for action recognition



RGB frames



Visual appearance  
(objects and scenes)



Suffers from  
occlusions and blur



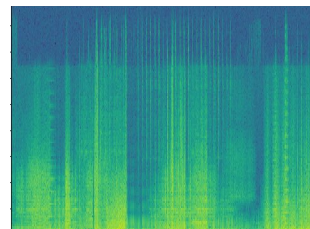
Optical flow



Focused on motion



Computationally  
expensive



Audio



Lightweight



Not all activities are  
recognizable from  
audio only

Each modality has its own **strengths** and **weaknesses**

# Egocentric vision + wearable sensors

Combine **egocentric vision** with **wearable sensors**

## EMG sensors

measures the electrical activity of the muscles

**Body and finger tracking**  
senses the acceleration and velocity of your body



## Eye tracking

detects where the eyes are looking at

## Tactile sensors

measure the force exerted on the fingers through touch



# The EPIC-Kitchens dataset (2018)

<https://epic-kitchens.github.io>



32  
participants



55+ recorded  
hours



39k action  
segments in a  
kitchen



# The Action-Net dataset (2022)

<https://action-net.csail.mit.edu>



10 subjects



12+ recorded  
hours



20 unique  
activities



Eye tracking



RGB/RGB-D cameras



Microphones



Tactile sensors

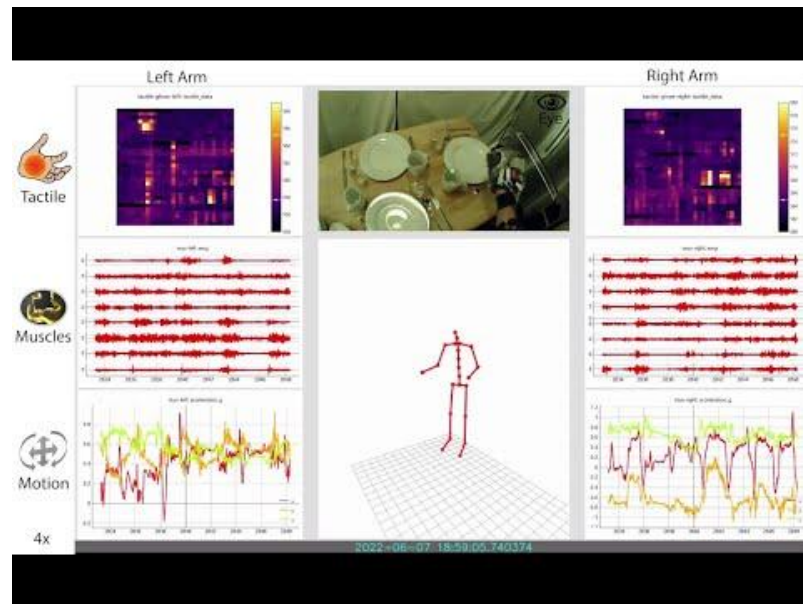


Body tracking



EMG sensors

A large number of **cameras** (head-mounted and external) and **wearable sensors**





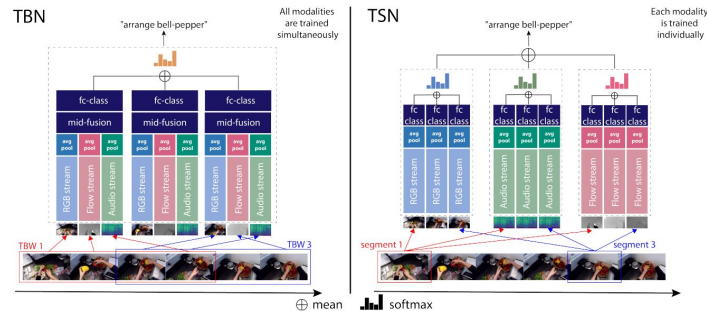
# Project steps

1. **Get familiar with egocentric vision and multimodal learning**
2. Implement common baselines using RGB and optical flow on the EK-55 dataset.
3. Implement one of the following variations:
  - a. Multimodal training with RGB and EMG on Action-Net.
  - b. A variational autoencoder to translate from RGB to EMG and viceversa on Action-Net. Reconstruct the missing EMG signal in EK and use it to implement a classifier.

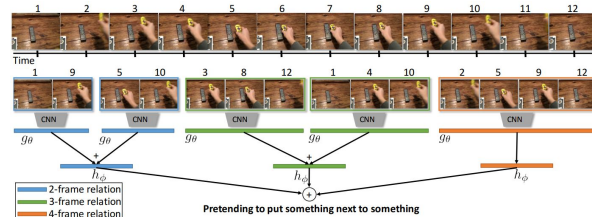


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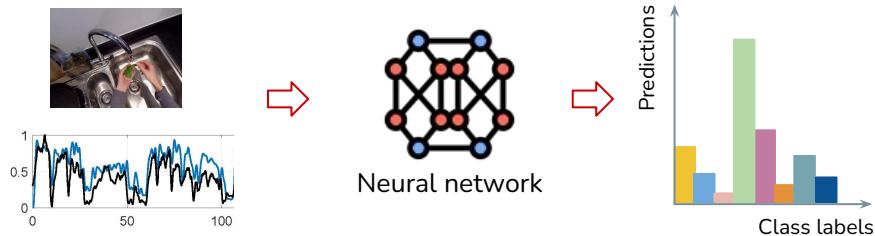
Temporal Binding Network [3] and Temporal Segment Network [4]



Temporal Relational Reasoning in Videos [5]

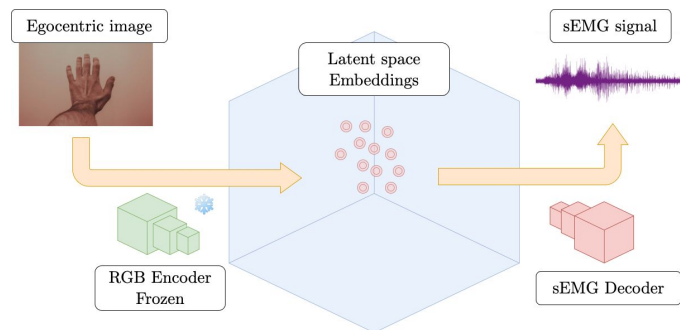
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# Bibliography

[1] Damen, Dima, et al. "Rescaling egocentric vision: Collection, pipeline and challenges for epic-kitchens-100." International Journal of Computer Vision (2022): 1-23.

[1] Núñez-Marcos, Adrián, Gorka Azkune, and Ignacio Arganda-Carreras. "Egocentric vision-based action recognition: a survey." Neurocomputing 472 (2022): 175-197.

[2] DelPreto, Joseph, et al. "ActionNet: A Multimodal Dataset for Human Activities Using Wearable Sensors in a Kitchen Environment." Thirty-sixth Conference on Neural Information Processing Systems Datasets and Benchmarks Track.

[3] Kazakos, Evangelos, et al. "Epic-fusion: Audio-visual temporal binding for egocentric action recognition." Proceedings of the IEEE/CVF International Conference on Computer Vision. 2019.

[4] Wang, Limin, et al. "Temporal segment networks for action recognition in videos." IEEE transactions on pattern analysis and machine intelligence 41.11 (2018): 2740-2755.

[5] Zhou, Bolei, et al. "Temporal relational reasoning in videos." Proceedings of the European conference on computer vision (ECCV). 2018.



# Multimodal Egocentric Action Recognition

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The objective of this project is to explore multimodal **Egocentric Action Recognition (EAR)**, starting from traditional approaches based on RGB, optical flow and audio and moving towards new modalities enabled by wearable sensors. The student should understand typical approaches used in egocentric vision and how multiple modalities can be combined together to perform action recognition or to compensate for the absence of other modalities.

## The project is organized in the following steps:

1. Get familiar with egocentric vision and multimodal learning, the task of egocentric action recognition and the most common datasets in the field.
2. Implement EAR models using RGB and optical flow on the EPIC-KITCHENS dataset.
3. Implement one of the following variations:
  - a. **Train a multimodal model** on the Action-Net [1] dataset using RGB frames and EMG signals measuring the wearer's muscle activity.
  - b. **Train a variational autoencoder** on the Action-Net dataset to translate from RGB to EMG and viceversa. Reconstruct the missing EMG signal on EPIC-KITCHENS [2] and use it to implement a classifier.



[Link to project details](#)

[1] DelPreto, Joseph, et al. "ActionNet: A Multimodal Dataset for Human Activities Using Wearable Sensors in a Kitchen Environment." NeurIPS22

[2] Damen, Dima, et al. "Scaling egocentric vision: The epic-kitchens dataset." ECCV 2018.