

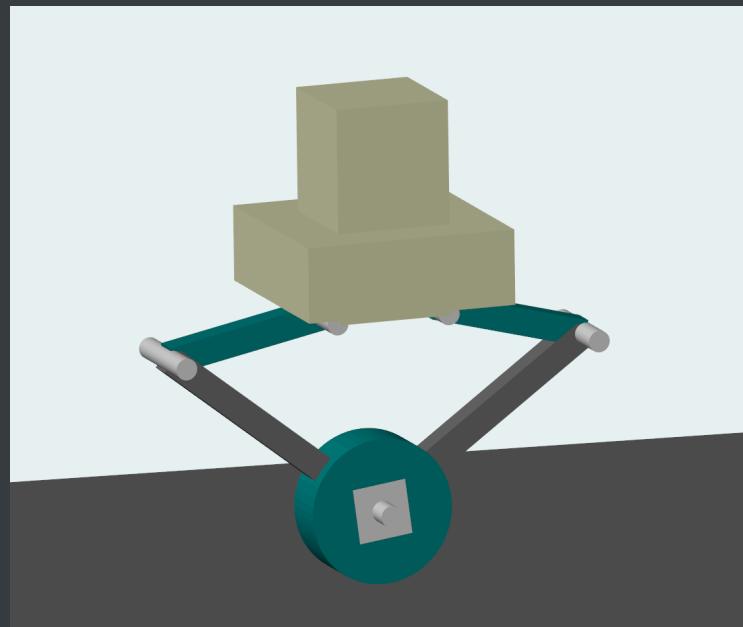
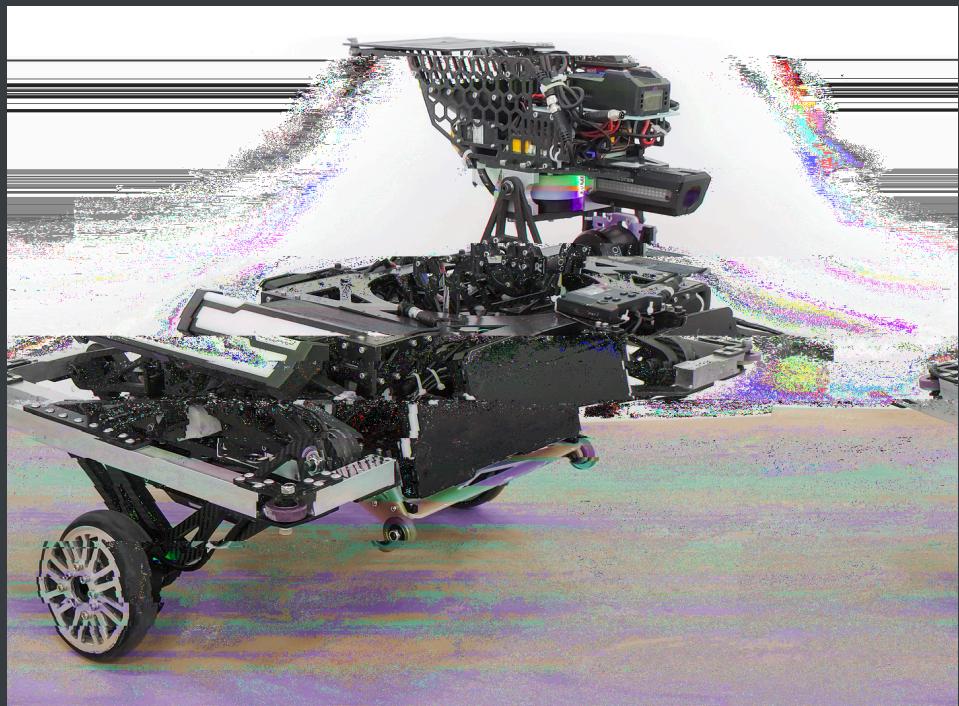


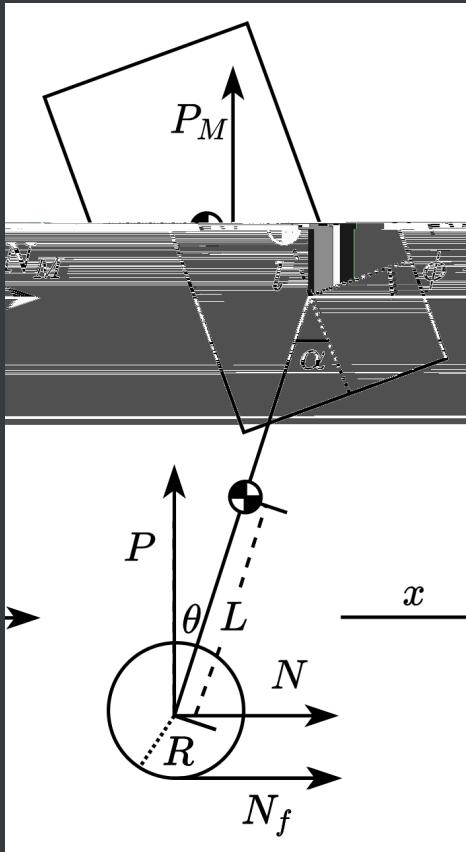
—

$$m \quad d \\ \xi_{(t)} \quad \phi_{(t)}$$

x

$$m \frac{d^2 x_{(t)}}{dt^2} = F_{x_{(t)}} \quad (3.3.1)$$







数据流通

观测器

K

雅可比矩阵

站起与巡航

倒地



