TECHNCIAL UNIVERSITY OF DENMARK



02504 Computer Vision F24

Visual Solutions

To Exercises

Preface

This file contains visual solutions to the programming exercises. It is intended to be a way of checking, whether your code outputs the correct results. If your code does not produce the shown result, check whether the settings are the same (e.g. same camera matrix \mathbf{K} , same rotation matrix \mathbf{R} , same translation vector \mathbf{t}) or something else. If you are stuck you are always more than welcome to write to us on Piazza:-)

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1 Week1

In this exercise the vision1.png was used.



Figure 1: Solution to Exercise 1.10

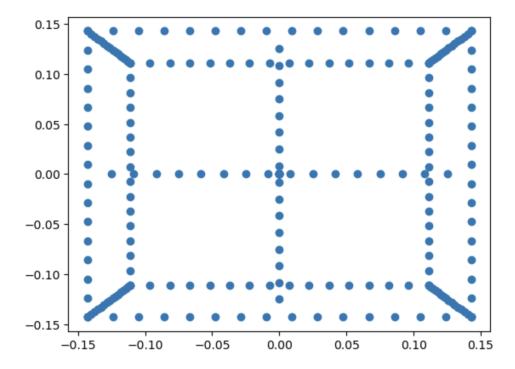


Figure 2: Solution to Exercise 1.13

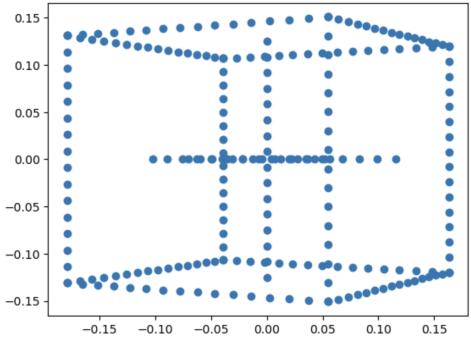


Figure 3: Solution to Exercise 1.14

Note in Exercise 1.15, the translation vector $t = [0, 2, 4]^T$ and the rotation matrix (around the Y-axis) R with -30° was used.

