The Weibull distribution

With i.i.d. Weibull distributed observations Z_1, \ldots, Z_n then $Y_1 = Z_1^k, \ldots, Y_n = Z_n^k$ are i.i.d. from the exponential family.

This is a generalized linear model with $\mathbf{X} = \mathbf{1}$ the $n \times 1$ matrix of ones, and

$$\eta = 1\eta$$
.

The score equation is

$$0 = U(\eta) = \sum_{i=1}^{n} \theta'(\eta) y_i - c'(\eta) = \frac{k}{\eta^{k+1}} \left(\sum_{i=1}^{n} y_i \right) - \frac{nk}{\eta}.$$

The Fisher information is

$$J(\eta) = n\theta'(\eta)^2 V(Y) = \frac{nk^2}{\eta^2}.$$

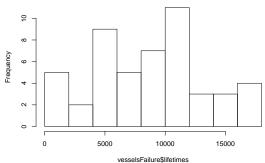


Data example

We use a small example data set on the lifetime of presure vessels.

```
vesselsFailure <- read.table(
   "http://www.math.ku.dk/~richard/courses/Regression/vessels.txt",
   header = TRUE)
hist(vesselsFailure$lifetimes)</pre>
```

Histogram of vesselsFailure\$lifetimes





Score function etc.

To implement the Newton algorithm for fitting the Weibull distribution we need to implement the functions that compute the score and the derivative of the score.

```
U <- function(eta, k, y = vesselsFailure$lifetimes)
k * sum(y^k) / (eta^(k+1)) - length(y) * k / eta

dU <- function(eta, k, y = vesselsFailure$lifetimes)
length(y) * k / eta^2 - k * (k + 1) * sum(y^k) / (eta^(k + 2))</pre>
```

We will also need the Fisher information.

```
J <- function(eta, k, n = length(vesselsFailure$lifetimes))
n * (k / eta)^2</pre>
```



The Newton algorithm

We replace the (nonlinear) score equation by the linearization around η_1

$$U(\eta_1) + U'(\eta_1)(\eta - \eta_1) = 0$$
 (1)

relying on $U(\eta) \simeq U(\eta_1) + U'(\eta_1)(\eta - \eta_1)$.

The solution to (1) is

$$\eta = \eta_1 - \frac{U(\eta_1)}{U'(\eta_1)}.$$

The Newton algorithm is obtained by iteration;

$$\eta_{m+1} = \eta_m - \frac{U(\eta_m)}{U'(\eta_m)}$$

with η_1 the initial value or start guess.



Newton and Fisher updates

Replacing $-U'(\eta)$ by its expectation $J(\eta)$ we get the Fisher scoring algorithm

$$\eta_{m+1} = \eta_m + \frac{U(\eta_m)}{J(\eta_m)}.$$

```
Newton <- function(eta, k = 2)
- U(eta, k) / dU(eta, k)
Fisher <- function(eta, k = 2)
U(eta, k) / J(eta, k)</pre>
```



Newton and Fisher algorithms

Argument update = Fisher gives Fisher scoring.

```
iterativeMLE <- function(eta = mean(vesselsFailure$lifetimes),</pre>
                         k = 2
                          nrIter = 6.
                          update = Newton) {
  ## Setting up the format of the results
 results <- matrix(0, ncol = nrIter, nrow = 6)
 row.names(results) <- c("eta", "U", "-dU", "J"," -U/dU", "U/J")
 for(m in 1:nrIter) {
    results[, m] <- c(eta,
                      U(eta, k) * 1e6.
                      -dU(eta, k) * 1e6,
                      J(eta, k) * 1e6,
                      Newton(eta, k),
                      Fisher(eta, k)
    eta <- eta + update(eta, k)
 results
```

Newton and Fisher algorithms

```
## [,1] [,2] [,3] [,4] [,5] [,6]
## eta 8805.7 9633.8 9876 9.9e+03 9.9e+03 9.9e+03
## U 2915.8 553.0 33 1.3e-01 2.3e-06 1.7e-12
## -dU 3.5 2.3 2 2.0e+00 2.0e+00 2.0e+00
## J 2.5 2.1 2 2.0e+00 2.0e+00 2.0e+00
## -U/dU 828.1 242.1 16 6.7e-02 1.1e-06 8.7e-13
## U/J 1153.5 261.9 16 6.7e-02 1.1e-06 8.7e-13
```

```
iterativeMLE(update = Fisher)
```

```
## [,1] [,2] [,3] [,4] [,5] [,6] 
## eta 8805.7 9959.2 9892.40 9.9e+03 9.9e+03 9.9e+03 
## U 2915.8 -132.0 -0.45 -5.2e-06 1.7e-12 1.7e-12 
## -dU 3.5 1.9 2.00 2.0e+00 2.0e+00 2.0e+00 
## J 2.5 2.0 2.00 2.0e+00 2.0e+00 2.0e+00 
## -U/dU 828.1 -68.2 -0.23 -2.6e-06 8.7e-13 8.7e-13 
## U/J 1153.5 -66.8 -0.23 -2.6e-06 8.7e-13 8.7e-13
```



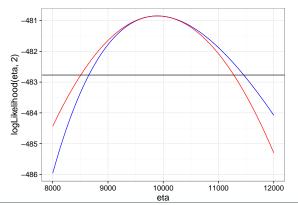
The quadratic approximation

We compare the log-likelihood with a quadratic function with maximum in $\hat{\eta}$.

```
etaHat0 <- iterativeMLE()["eta", 6]
quardApprox <- function(eta) {
   logLikelihood(etaHat0, 2) -
        (eta - etaHat0) * J(etaHat0, 2) * (eta - etaHat0) / 2
}
logLikelihood <- function(eta, k, y = vesselsFailure$lifetimes) {
   length(y)*(log(k) - k*log(eta)) +
        (k-1)*sum(log(y)) - sum(y^k)/eta^k
}</pre>
```



The quadratic approximation





Generalized linear models

The *p*-dimensional score equation for a GLM reads

$$U(\beta) = \mathbf{X}^T U(\boldsymbol{\eta}) = 0.$$

Given β_1 and corresponding $\eta_{1,i} = X_i^T \beta_1$ let

$$\mathbf{W}_1^{\mathsf{obs}} = - \left(egin{array}{ccc} U_1'(\eta_{1,1}) & \dots & 0 \ dots & \ddots & dots \ 0 & \dots & U_n'(\eta_{1,n}) \end{array}
ight).$$

The linearization of the score equation is

$$\mathbf{X}^T U(\boldsymbol{\eta}_1)^T - \mathbf{X}^T \mathbf{W}_1^{\text{obs}} \mathbf{X}(\beta - \beta_1) = 0,$$

whose solution is

$$\beta = \beta_1 + (\mathbf{X}^T \mathbf{W}_1^{\text{obs}} \mathbf{X})^{-1} \mathbf{X}^T U(\boldsymbol{\eta}_1).$$



Fisher scoring

Replacing $\mathbf{W}_{m}^{\text{obs}}$ by its expectation

$$\mathbf{W}_{m} = \frac{1}{\psi} \begin{pmatrix} \mu'(\eta_{m,1})\theta'(\eta_{m,1}) & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \mu'(\eta_{m,n})\theta'(\eta_{m,n}) \end{pmatrix}$$

we get by iteration the Fisher scoring algorithm.

$$\beta_{m+1} = \beta_m + (\mathbf{X}^T \mathbf{W}_m \mathbf{X})^{-1} \mathbf{X}^T U(\boldsymbol{\eta}_m)$$

$$= (\mathbf{X}^T \mathbf{W}_m \mathbf{X})^{-1} \mathbf{X}^T \mathbf{W}_m \left(\underbrace{\mathbf{X} \beta_m + \mathbf{W}_m^{-1} U(\boldsymbol{\eta}_m)}_{\mathbf{Z}_m} \right).$$



Iterative Weighted Least Squares

The vector \mathbf{Z}_m is known as the working response and

$$Z_{m,i} = X_i^T \beta_m + \frac{Y_i - \mu(\eta_{m,i})}{\mu'(\eta_{m,i})}$$
 (2)

In terms of the working response, the vector β_m is the minimizer of the weighted sum of squares

$$(\mathbf{Z}_m - \mathbf{X}\beta)^T \mathbf{W}_m (\mathbf{Z}_m - \mathbf{X}\beta). \tag{3}$$

This is a standard weighted least squares problem.



Iterative Weighted Least Squares

The Fisher scoring algorithm for GLMs is known as IWLS due to the iterative solution of a weighted least squares problem. Given β_1 we iterate until convergence:

- Compute the working response vector \mathbf{Z}_m based on β_m using (2).
- Compute the weights

$$w_{m,ii} = \frac{(\mu'_{m,i})^2}{\mathcal{V}(\mu_{m,i})} = \frac{\mu'(\eta_{m,i})^2}{\mathcal{V}(\mu(\eta_{m,i}))}.$$

• Minimize the weighted sum of squares (3).

Computations rely only on the mean value function μ , its derivative μ' and the variance function \mathcal{V} .



Estimation of the nuisance parameter

Implementation of the profile log-likelihood.

```
etaHat <- function(k = 2,
                    y = vesselsFailure$lifetimes,
                    update = Newton) {
  eta <- mean(v)
  maxIter <- 20
  convCrit <- 1e-6
  m < -1
  for(m in 2:maxIter) {
    up <- update(eta, k)
    eta <- eta + up
    if(abs(up) < convCrit)</pre>
      break
  return(eta)
```



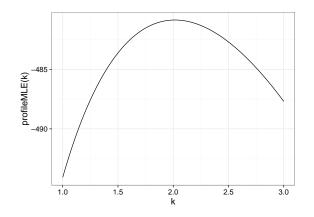
Profile log-likelihood

The use of Vectorize below makes the function work for vector arguments.



Profile log-likelihood

```
k \leftarrow seq(1, 3, 0.01); qplot(k, profileMLE(k), geom = "line")
```





Score function with canonical link

With the canonical link function $\theta'(\eta) = 1$ and the score function is

$$U(\beta) = \sum_{i=1}^{n} (Y_i - \mu(\eta_i)) X_i = t - \tau(\beta)$$

whose second derivative equals the negative Fisher information

$$-D_{\beta}U(\beta) = \mathcal{J}(\beta) = \mathbf{X}^{T}\mathbf{W}\mathbf{X}$$

with $\mathbf{W}_{ii} = \mu'(\eta_i) = \mathcal{V}(\mu(\eta_i))$. Recall that $\mu'(\eta) > 0$ for all η , thus the weights are always strictly positive for the canonical link.

Define

$$au(eta) = \sum_{i=1}^n \mu(\eta_i) X_i$$
 and $t = \sum_{i=1}^n Y_i X_i$



The score equation

The score equation is

$$\tau(\beta) = t. \tag{4}$$

Theorem (Thm. 6.9)

If **X** has full rank p the map $\tau : \mathbb{R}^p \to \mathbb{R}^p$ is one-to-one. With $C := \tau(\mathbb{R}^p)$ there is a unique solution to (4) if and only if $t \in C$.

Lemma (Lemma 6.10)

If $t_0 = \sum_{i=1}^n \mu_i X_i$ with $\mu_i \in J := \mu(\mathbb{R})$ there is a solution to the equation $\tau(\beta) = t_0$.



Existence of the MLE

Corollary (Cor. 6.11)

The set $C = \tau(\mathbb{R}^p)$ has the representation

$$C = \left\{ \sum_{i=1}^{n} \mu_i X_i \mid \mu_i \in J \right\}$$
 (5)

and is convex. If X has full rank p then C is open.

To check if the MLE exists we need to check if $t \in C$. This is trivially the case if

$$P(Y \in J) = 1$$

but less trivial to check if $P(Y \in \partial J) > 0$.

The solution, if it exists, is unique if X has full rank p.

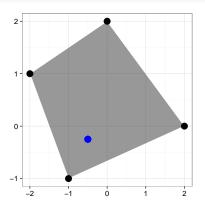


```
X \leftarrow data.frame(x1 = c(-2, -1, 2, 0), x2 = c(1, -1, 0, 2))
y \leftarrow c(1, 2, 1, 0); Xy \leftarrow cbind(y, X)
t <- c(y %*% X$x1, y %*% X$x2) / sum(y)
summary(glm(y ~ x1 + x2, family = poisson, data = Xy))
## Coefficients:
##
              Estimate Std. Error z value Pr(>|z|)
## (Intercept) 0.0267 0.5461 0.05 0.96
## x1 -0.1237 0.3742 -0.33 0.74
## x2 -0.6550 0.5157 -1.27 0.20
##
   (Dispersion parameter for poisson family taken to be 1)
##
      Null deviance: 2.77259 on 3 degrees of freedom
##
## Residual deviance: 0.75402 on 1 degrees of freedom
## ATC: 13.37
##
## Number of Fisher Scoring iterations: 5
```



In the example the average t was in the interior of the convex hull, and we could fit the Poisson model using glm.

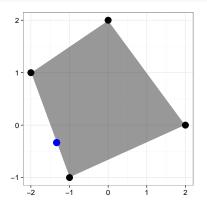
```
p <- qplot(x1, x2, data = X, geom = "polygon", alpha = I(0.5)) +
    geom_point(size = 5, alpha = 1) + xlab("") + ylab("")
p + geom_point(aes(t[1], t[2]), size = 5, color = "blue")</pre>
```





Then we consider an example where the average t ends up on the boundary of the convex hull.

```
y <- c(1, 2, 0, 0); Xy <- cbind(y, X)
t <- c(y %*% X$x1, y %*% X$x2) / sum(y)
p + geom_point(aes(t[1], t[2]), size = 5, color = "blue")
```





```
summary(glm(y ~ x1 + x2, family = poisson, data = Xy))
## Coefficients:
##
             Estimate Std. Error z value Pr(>|z|)
## (Intercept) -12.84 25534.58
## x1
              -8.79 17023.05
## x2
              -4.74 8511.53
##
## (Dispersion parameter for poisson family taken to be 1)
##
      Null deviance: 4.4987e+00 on 3 degrees of freedom
##
## Residual deviance: 4.0610e-10 on 1 degrees of freedom
## AIC: 10.61
##
## Number of Fisher Scoring iterations: 21
```



Binary response

If the response is binary, $I = \mathbb{R}$, J = (0,1) and the canonical link is the logit function

$$(0,1) \ni p \mapsto \operatorname{logit}(p) = \operatorname{log}\left(\frac{p}{1-p}\right).$$

The response variables all take values on the boundary of J = (0, 1)!

We have that

$$t = \sum_{i:Y_i=1} X_i \in \overline{C}$$

and we need to find conditions in terms of the X_i that ensure that $t \in C$.



Separation

The responses $Y_1, \ldots, Y_n \in \{0, 1\}$ are binary.

Definition

We say that $X_1, \ldots, X_n \in \mathbb{R}^p$ are separated by Y_1, \ldots, Y_n if there exists a nonzero vector $\beta \in \mathbb{R}^p$ such that for all $i = 1, \ldots, n$

$$X_i^T \beta \geq 0$$
 if $Y_i = 1$,

and

$$X_i^T \beta \leq 0$$
 if $Y_i = 0$.

Observe that if **X** has full rank p, and the rows are separated according to the definition above, the at least one of the n inequalities above is sharp because β is assumed nonzero. The vector β is called the separating vector.



Existence of the MLE in logistic regression

We consider binary responses $Y_1, \ldots, Y_n \in \{0, 1\}$ and the logistic regression model.

Theorem (Th, 6.16)

Assume that **X** has full rank p. The MLE exists if and only if the rows of **X** are not separated by Y_1, \ldots, Y_n .



Being explicit about the intercept

If the model contains an intercept in addition to the predictors $X_i \in \mathbb{R}^p$, it is

$$\tilde{X}_i = (1, X_i^T)^T$$

for $i=1,\ldots,n$ that must be checked for separability. This is equivalent to the existence of $\beta\in\mathbb{R}^p$ and $\beta_0\in\mathbb{R}$ such that for all $i=1,\ldots,n$

$$X_i^T \beta \ge \beta_0$$
 if $Y_i = 1$,

and

$$X_i^T \beta \leq \beta_0$$
 if $Y_i = 0$.



Checking for linear separability

Corollary (Cor. 6.17)

Assume that X has full rank p. The maximization problem

maximize
$$\sum_{i=1}^{n} s_i$$

subject to $(2Y_i - 1)X_i^T \beta \ge s_i$, $s_i \ge 0$, $i = 1, ..., n$,
 $-1 \le \beta_j \le 1$, $j = 1, ..., p$

in the variables $(\beta^T, s^T)^T \in \mathbb{R}^{n+p}$ has a solution with $\sum_{i=1}^n s_i > 0$ if and only if X_1, \ldots, X_n are separated by Y_1, \ldots, Y_n .

The constraints on the β_j 's force the s_i 's to be bounded, and the constraints are fulfilled for $\beta = \mathbf{0}_p$ and $s = \mathbf{0}_n$. Thus we maximize a linear function over a compact set, and there is always a finite solution bounded below by 0.



Poisson responses

For Poisson distributed responses we have $I = \mathbb{R}$, $J = (0, \infty)$ and canonical link

$$(0,\infty)\ni \mu\mapsto \log(\mu).$$

The nonexistence of the MLE is clearly related to observations being 0.



Existence of the MLE in Poisson regression

We consider positive responses $Y_i \ge 0$ and the Poisson regression model with log-link. We let

$$t_0 = \sum_{i=1}^n Y_i X_i = \mathbf{X}^T \mathbf{Y}.$$

Corollary (Cor. 6.13)

Assume that \mathbf{X} has full rank p. The MLE exists if and only if the following linear program

maximize
$$s$$
 subject to $\mathbf{X}^T \mu = t_0, \ \mu_i - s \ge 0, \ s \ge 0.$

in the variables $(\mu^T, s)^T \in \mathbb{R}^{n+1}$ has a feasible point with s > 0.

Note that $(\mathbf{Y}^T, 0)^T$ is a feasible point.



Specifying the linear program in practice

The linear program is specified in practice in terms of a vector $c \in \mathbb{R}^{n+1}$ of objective coefficients and an $(n+p) \times (n+1)$ constraint matrix A. They are given as

$$c=(0,\ldots,0,1)^T$$

and

$$A = \left(\begin{array}{cc} \mathbf{I}_n & -\mathbf{1}_n \\ \mathbf{X}^T & \mathbf{0}_p \end{array}\right)$$

where \mathbf{I}_n is the $n \times n$ identity matrix, $\mathbf{1}_n$ is the n-dimensional vector of ones and $\mathbf{0}_p$ is the p-dimensional vector of zeroes.

The constraint matrix specifies the left hand side of the n+p constraints in the n+1 variables. The first n are inequality constraints and the last p are equality constraints. The right hand side of the constraints is the (n+p)-dimensional vector

$$\begin{pmatrix} \mathbf{0}_n \\ t_0 \end{pmatrix}$$
.



```
## Coefficient vector
c \leftarrow c(0, 0, 0, 0, 1)
## Constraint matrix
A <- matrix(
  c(1. 0, 0, 0, -1,
    0, 1, 0, 0, -1,
    0, 0, 1, 0, -1,
    0, 0, 0, 1, -1,
   1, 1, 1, 1, 0,
   -2, -1, 2, 0, 0,
    1, -1, 0, 2, 0),
 nrow = 7,
 ncol = 5,
  byrow = TRUE)
## Right hand side
t \leftarrow A[5:7, 1:4] \% \% c(1, 2, 1, 0)
rhs \leftarrow c(0, 0, 0, 0, t)
## Directions of the (in)equalities
dir \leftarrow c(rep(">=", 4), rep("=", 3))
```



```
lp(direction = "max",
   objective.in = c,
   const.mat = A,
   const.dir = dir,
   const.rhs = rhs
)

### Success: the objective function is 0.47
```



```
## Changing the right hand side
t <- A[5:7, 1:4] %*% c(1, 2, 0, 0)
rhs <- c(0, 0, 0, 0, t)
## Solving the linear program
lp(direction = "max",
   objective.in = c,
   const.mat = A,
   const.dir = dir,
   const.rhs = rhs
)
## Success: the objective function is 0</pre>
```

