

## 2. Probability Theory

### - Conditional and Unconditional Probability

When we observe the probability that an event ( $A$ ) occurs without taking into account whether it is necessarily preceded by any other specific events, it is known as an **unconditional probability**.

- ▶ Also known as a **marginal probability**.
- ▶ Notation:  $\mathbb{P}(A)$

When we observe the probability of a given event after taking into account that another event has already occurred ( $A$  occurs given that  $B$  has occurred), it is known as a **conditional probability**.

- ▶ Notation:  $\mathbb{P}(A|B)$  "probability of  $A$  given  $B$ "
- ▶ Example: Event  $A$ : *the stock return of the company ABC falls below  $-10\%$*   
Event  $B$ : *the market return falls below  $-10\%$*   
 $A|B$ : *the stock return of the company ABC falls below  $-10\%$  given that the market return falls below  $-10\%$*

**Marginal Probability** - probability of any single event occurring unconditioned on any other events. Whenever someone asks you whether the weather is going to be rainy or sunny today, you are computing a marginal probability.

**Joint Probability** - probability of more than one event occurring simultaneously. If I ask you whether the weather is going to be rainy and the temperature is going to be above a certain number, you are computing a joint probability.

**Conditional probability** - probability of an event occurring given some events that you have already observed. When I ask you what's the probability that today is rainy or sunny given that I noticed the temperature is going to be above 80 degrees, you are computing a conditional probability.

**Conditional probability:**

$$\mathbb{P}(A|B) = \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)}, \mathbb{P}(B) \neq 0$$

**Multiplication rule:** the joint probability of  $A$  and  $B$  is

$$\mathbb{P}(A \cap B) = \mathbb{P}(A|B)\mathbb{P}(B) = \mathbb{P}(B|A)\mathbb{P}(A)$$

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## - Independent Events

When events are **independent**, the occurrence of one does not affect the probability of the other. In other words,  $\mathbb{P}(A|B) = \mathbb{P}(A)$  and  $\mathbb{P}(B|A) = \mathbb{P}(B)$ .

Then **the multiplication rule**:  $\mathbb{P}(A \cap B) = \mathbb{P}(A)\mathbb{P}(B)$ .

More generally, if  $A_1, A_2, \dots, A_n$  are independent, then

$$\mathbb{P}(A_1 \cap A_2 \cap \dots \cap A_n) = \mathbb{P}(A_1)\mathbb{P}(A_2) \dots \mathbb{P}(A_n)$$

$$[ E(A) * E(B) = E(A * B) ]$$

## - Bayes' Rule

**Bayes' Rule** is used to determine how a subjective belief should change given new evidence.

$$\mathbb{P}(Event|Information) = \left( \frac{\mathbb{P}(Information|Event)}{\mathbb{P}(Information)} \right) \mathbb{P}(Event)$$

- Updated probability given new information (posterior probability)
- Ratio of probability of the new information given the event and unconditional probability of the new information
- Prior probability of the event

**Bayes' Rule:**

$$\mathbb{P}(E|A) = \frac{\mathbb{P}(A|E)\mathbb{P}(E)}{\mathbb{P}(A|E)\mathbb{P}(E) + \mathbb{P}(A|E^c)\mathbb{P}(E^c)}$$

More generally,

$$\mathbb{P}(E_j|A) = \frac{\mathbb{P}(A|E_j)\mathbb{P}(E_j)}{\sum_{i=1}^n \mathbb{P}(A|E_i)\mathbb{P}(E_i)} = P(A)$$

where  $E_1, E_2, \dots, E_n$  are mutually exclusive and exhaustive events.

## - Covariance and Correlation

Covariance and correlation are measures of **linear dependence** between random variables.

**Covariance** of two random variables  $X$  and  $Y$  is

$$\underline{Cov(X, Y) = \sigma_{X,Y} = \mathbb{E}([X - \mathbb{E}(X)][Y - \mathbb{E}(Y)])}$$

**Correlation** is covariance scaled by standard deviations of random variables:

$$\rho(X, Y) = \rho_{X,Y} = \frac{Cov(X, Y)}{\sqrt{\sigma^2(X)\sigma^2(Y)}} = \frac{\sigma_{X,Y}}{\sigma_X\sigma_Y}$$

$$\blacktriangleright -1 \leq \rho_{X,Y} \leq 1$$

## - Properties of Expected Value and Variance

$\mathbb{E}(aX + bY) = a\mathbb{E}(X) + b\mathbb{E}(Y)$ , where  $a$  and  $b$  are deterministic.

$\mathbb{E}(aX + c) = a\mathbb{E}(X) + c$ , where  $a$  and  $c$  are deterministic.

$$\sigma^2(X) = \mathbb{E}(X^2) - (\mathbb{E}(X))^2$$

$\sigma^2(aX + bY) = a^2\sigma^2(X) + b^2\sigma^2(Y) + 2ab Cov(X, Y)$ , where  $a$  and  $b$  are deterministic.

$\sigma^2(aX + c) = a^2\sigma^2(X)$ , where  $a$  and  $c$  are deterministic.

$$Cov(X, Y) = Cov(Y, X), \rho(X, Y) = \rho(Y, X),$$

$$Cov(X, X) = \sigma^2(X)$$

$$Cov(X, Y) = \mathbb{E}(XY) - \mathbb{E}(X)\mathbb{E}(Y)$$

If  $X_1, X_2, \dots, X_n$  are independent, then

$$\sigma^2\left(\sum_{i=1}^n X_i\right) = \sum_{i=1}^n \sigma^2(X_i)$$

## - Conditional Expectations

**Conditional distribution** that  $X = x_i$  given that  $Y = y_i$  is described by a set of conditional probabilities:

$$\mathbb{P}(X = x_i | Y = y_i) = \frac{\mathbb{P}(X = x_i, Y = y_i)}{\mathbb{P}(Y = y_i)}$$

Notation:  $p_{X|Y}(x|y)$



The **conditional expectation** of  $X$  given  $Y = y$  is

$$E(X|Y = y) = \sum_x xp_{X|Y}(x|y)$$

### The Total Probability Rule for Expected Value

$$\begin{aligned}\mathbb{E}(X) &= \mathbb{E}(X|E)\mathbb{P}(E) + \mathbb{E}(X|E^C)\mathbb{P}(E^C) \\ &= \mathbb{E}(X|E_1)\mathbb{P}(E_1) + \mathbb{E}(X|E_2)\mathbb{P}(E_2) + \cdots + \mathbb{E}(X|E_n)\mathbb{P}(E_n),\end{aligned}$$

where  $E_1, E_2, \dots, E_n$  are mutually exclusive and exhaustive events.

## - Prediction

Predict  $Y$  by means of a constant value  $c$

Minimize the **mean squared error**  $MSE = \mathbb{E}((Y - c)^2)$

Optimal  $c = \mathbb{E}(Y)$

Predict  $Y$  by some function of  $h(X)$ , that is minimize

$$MSE = \mathbb{E}((Y - h(X))^2)$$

Optimal in the mean squared sense  $h(X) = \mathbb{E}(Y|X)$

If  $h(X)$  is a linear function, the conditional expectation represent the linear regression of  $Y$  on  $X$ .