## Exercise

## In groups of UP TO FOUR:

- 1. Implement a MAB:
  - Let each arm give rewards from a Gaussian of variance 1, and means drawn from a Gaussian of mean 0, variance 3 when they are created.
  - You should be able to "pull" an arm (select an action) and receive a random reward.
- 2. Implement the  $\epsilon$ -greedy, greedy with optimistic initialisation, and UCB algorithms.
- 3. Run the three algorithms with different parameter settings on a 10-arm bandit.

## By next week's lecture, submit on Moodle:

- 1. A plot of reward over time (averaged over 100 runs each) on the same axes, for  $\epsilon$ -greedy with  $\epsilon = 0.1$ , greedy with  $Q_1 = 5$ , and UCB with  $Q_2 = 5$
- 2. A summary comparison plot of rewards over first 1000 steps for the three algorithms with different values of the hyperparameters
- 3. Your code