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In [3]: import cv2
import numpy as np

background = None
accumulated_weight = 0.5

ROI_top = 100
ROI_bottom = 300
ROI_right = 150
ROI_left = 350

def cal_accum_avg(frame, accumulated_weight):

    global background

    if background is None:
        background = frame.copy().astype("float")
        return None

    cv2.accumulateWeighted(frame, background, accumulated_weight)

def segment_hand(frame, threshold=25):
    global background

    diff = cv2.absdiff(background.astype("uint8"), frame)

    _, thresholded = cv2.threshold(diff, threshold, 255, cv2.THRESH_BINARY)

    # Grab the external contours for the image
    contours, hierarchy = cv2.findContours(thresholded.copy(), cv2.RETR_EXT

    if len(contours) == 0:
        return None
    else:

        hand_segment_max_cont = max(contours, key=cv2.contourArea)

        return (thresholded, hand_segment_max_cont)

cam = cv2.VideoCapture(0)

num_frames = 0
element = 10
num_imgs_taken = 0

while True:
    ret, frame = cam.read()

    # flipping the frame to prevent inverted image of captured frame...
    frame = cv2.flip(frame, 1)

    frame_copy = frame.copy()

    roi = frame[ROI_top:ROI_bottom, ROI_right:ROI_left]

    gray_frame = cv2.cvtColor(roi, cv2.COLOR_BGR2GRAY)
    gray_frame = cv2.GaussianBlur(gray_frame, (9, 9), 0)

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if num_frames < 60:
    cal_accum_avg(gray_frame, accumulated_weight)
    if num_frames <= 59:

        cv2.putText(frame_copy, "FETCHING BACKGROUND...PLEASE WAIT", (8
            #cv2.imshow("Sign Detection", frame_copy)

#Time to configure the hand specifically into the ROI...
elif num_frames <= 300:

    hand = segment_hand(gray_frame)

    cv2.putText(frame_copy, "Adjust hand...Gesture for" + str(element),

    # Checking if hand is actually detected by counting number of contours
    if hand is not None:

        thresholded, hand_segment = hand

        # Draw contours around hand segment
        cv2.drawContours(frame_copy, [hand_segment + (ROI_right, ROI_top),

        cv2.putText(frame_copy, str(num_frames)+"For" + str(element), (

        # Also display the thresholded image
        cv2.imshow("Thresholded Hand Image", thresholded)

    else:

        # Segmenting the hand region...
        hand = segment_hand(gray_frame)

        # Checking if we are able to detect the hand...
        if hand is not None:

            # unpack the thresholded img and the max_contour...
            thresholded, hand_segment = hand

            # Drawing contours around hand segment
            cv2.drawContours(frame_copy, [hand_segment + (ROI_right, ROI_top),

            cv2.putText(frame_copy, str(num_frames), (70, 45), cv2.FONT_HERSHEY_SIMPLEX, 1)
            #cv2.putText(frame_copy, str(num_frames)+"For" + str(element),
            cv2.putText(frame_copy, str(num_imgs_taken) + 'images' + "For" +

            # Displaying the thresholded image
            cv2.imshow("Thresholded Hand Image", thresholded)
            if num_imgs_taken <= 300:
                #cv2.imwrite(r"D:\gesture\train\\" + str(element) + ".jpg")
                #cv2.imwrite(r"C:\Users\vishwanth\Downloads\gesture\x"+str(element)+".jpg")
                cv2.imwrite(r"D:\gesture\train\\" + str(num_imgs_taken) + ".jpg")

            else:
                break
            num_imgs_taken +=1
        else:
            cv2.putText(frame_copy, 'No hand detected...', (200, 400), cv2.FONT_HERSHEY_SIMPLEX, 1)

# Drawing ROI on frame copy
cv2.rectangle(frame_copy, (ROI_left, ROI_top), (ROI_right, ROI_bottom),

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cv2.putText(frame_copy, "DataFlair hand sign recognition_ _ _", (10, 200), cv2.FONT_HERSHEY_SIMPLEX, 1, (0, 0, 255), 2, True)

# increment the number of frames for tracking
num_frames += 1


# Display the frame with segmented hand
cv2.imshow("Sign Detection", frame_copy)

# Closing windows with Esc key...(any other key with ord can be used to
k = cv2.waitKey(1) & 0xFF

if k == 27:
    break

# Releasing camera & destroying all the windows...

cv2.destroyAllWindows()
cam.release()
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In []:

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