# Nihal Dhamani

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## **EDUCATION**

#### **UT AUSTIN**

B.S. COMPUTER SCIENCE B.S.A. ASTRONOMY

MIDDLE EASTERN STUDIES MINOR Expected Dec 2019 | Austin, TX

## **JOHN FOSTER DULLES HS**

Grad. May 2015 Sugar Land, TX

## SKILLS

## **PROGRAMMING**

Proficient: Python • Java

Working Knowledge:

 $\mathsf{C} \bullet \mathsf{Go} \bullet \mathsf{MATLAB} \bullet \mathsf{SQL} \bullet \mathsf{CSS}$ 

Bash • HTML • PHP • JavaScript

#### **TECHNOLOGIES**

Git • TensorFlow • Android Studio OpenCV • Amazon Web Services Docker

## **INTERPERSONAL**

Project Management

## COURSEWORK

Computer Vision
Artificial Intelligence
Software Engineering
Data Structures
Algorithms
Operating Systems
Computer Architecture
Mobile Computing
Statistics and Probability
Linear Algebra

# **ACTIVITIES**

## **TEXAS BLAZERS**

VICE CHAIR OF COMMUNITY
SERVICE | SEPT. 2016 - PRESENT
Service organization devoted to
serve UT Austin and the
surrounding community

## **EXPERIENCE**

## NASA JET PROPULSION LABORATORY

## SOFTWARE ENGINEERING INTERN

May 2018 - August 2018 | Pasadena, CA

- Improved efficiency of cloud operations for the Mars 2020 Ground Data Systems team
- Established endpoint health monitoring system hosted on AWS making use of various technologies including Docker and ElasticSearch
- Wrote scripts to efficiently manage LDAP security groups
- Employed use of Go to automate the process of GitHub issue labeling for project management

## TEXAS SPACECRAFT LABORATORY

#### SEEKER1 ML/CV LEAD

September 2017 – Present | Austin, TX

- Designed, implemented, and tested machine learning and computer vision algorithms for NASA's JSC Seeker Mission
- Trained a convolutional neural network (CNN) to detect target spacecraft in orbit using Python and TensorFlow
- Developed multi-threaded auto-capturing software to process and save spacecraft images using various computer vision techniques to extract orbital information
- Organized and led weekly team meetings to brief on progress and delegate tasks

## **METECS**

## **ENGINEERING INTERN**

May 2017 - August 2017 | Houston, TX

- Part of the RFID-Enabled Autonomous Logistics Management (REALM) team at NASA's Johnson Space Center
- Designed, implemented, and tested a voice user interface system for an inventory tracking system that is deployed on the International Space Station
- Created a real-time inventory tracking website using data from RFID sensors
- Deployed a server to interact with data from inventory tracking website, RESTful API's, and AWS

## **PROJECTS**

## **OBJECT DETECTOR**

Android application integrated with an object detection model. Allows for saving and retrieval of detected objects

## **AUTONOMOUS RC CAR**

Employed use of Arduino, Raspberry PI, OpenCV, and TensorFlow to create a self-driving car

#### **NBA WEBSITE**

Full-stack website organizing information about NBA players, coaches, and teams

#### **PONG**

Interactive web game developed in JavaScript with Al implementation