### Project 5: Due next Wed, April 26

http://www.mathcs.emory.edu/~eugene/cs325/p5/

Questions?

More:

http://yann.lecun.com/exdb/mnist/

• Even more on image classification:

www.image-net.org/

## Extra Credit (Optional) Project: AlGym

- https://gym.openai.com/envs/Pong-v0
- https://gym.openai.com/docs
- Mission: "solve" Pong (on average, play with positive score): +10
  - Win consistently at least 5 games: +5
  - Win on average 3 games: +3
- Starting files: p5aigym.zip (in resources on Piazza)

# Final: Monday, May 1, 8am

5/1/2017, Monday

8:00AM - 10:30AM

**MCS W301** 

- Closed book, closed notes.
- + 1 Sheet of Notes
- + Calculator (optional)

### **Optional Review Session**

Tuesday, April 25, 11:30AM-12:45pm.

Room: TBA

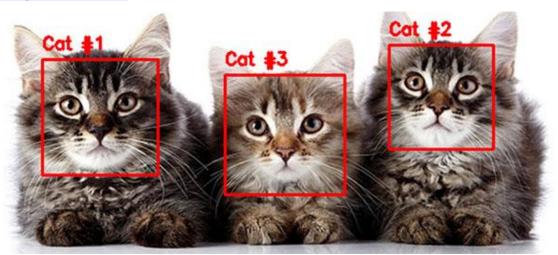
Al: What is possible? (2017)

### Al 2017: Object Recognition

https://cloud.google.com/vision/

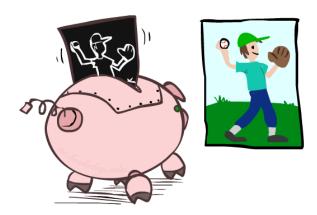
You can has it, too:

http://www.pyimagesearch.com/2016/06/20/detecting-cats-in-images-with-opency/



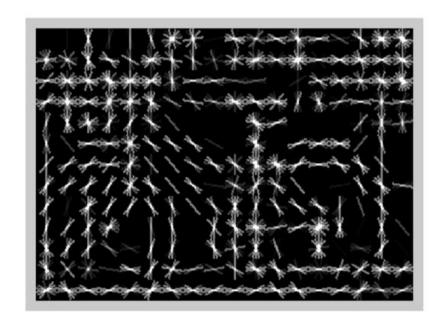
# Object Detection Approach 1: HOG + SVM







### Features and Generalization



### Features and Generalization



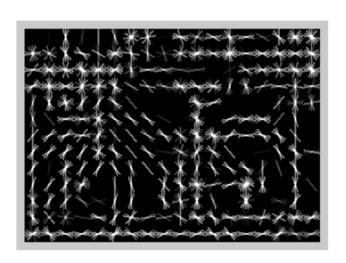


Image HoG

# **Training**

- Round 1
  - Training set =
    - Positive examples: from labeling
    - Negative examples: random patches
  - → preliminary SVM
- Round 2 ("bootstrapping" or "mining hard negatives")
  - Training set =
    - Positive examples: from labeling
    - Negative examples: patches that have score >= -1

### State-of-the-art Results

sofa sofa bottle bottle cat cat

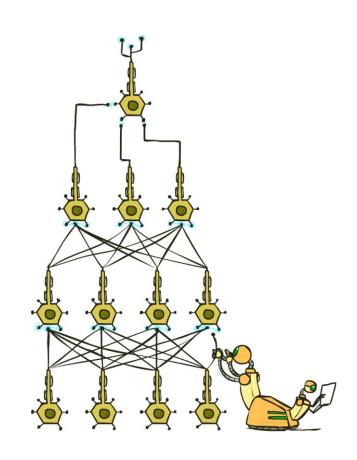
[Girschik, Felzenszwalb, McAll

### State-of-the-art Results

person person car car horse horse

[Girschik, Felzenszwalb, McAll

# Object Detection Approach 2: Deep Learning

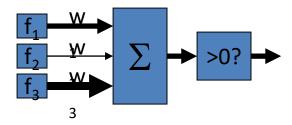


# How Many Computers to Identify a Cat?

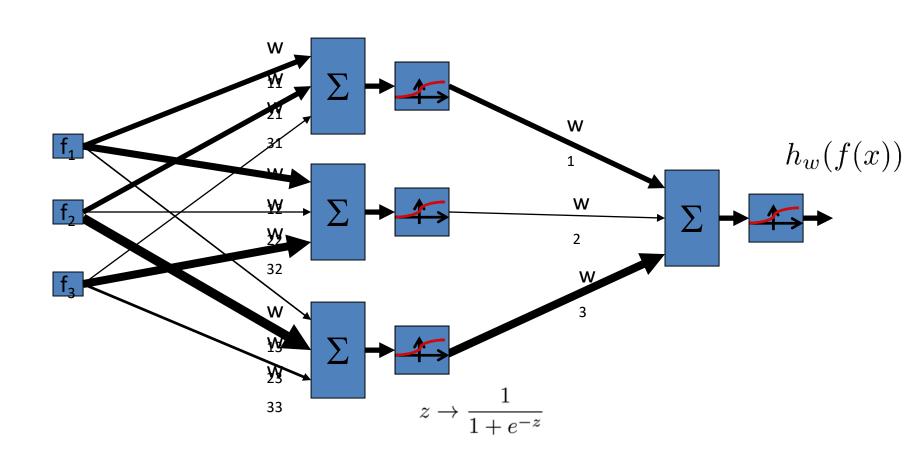


"Google Brain"
[Le, Ng, Dean, et al,

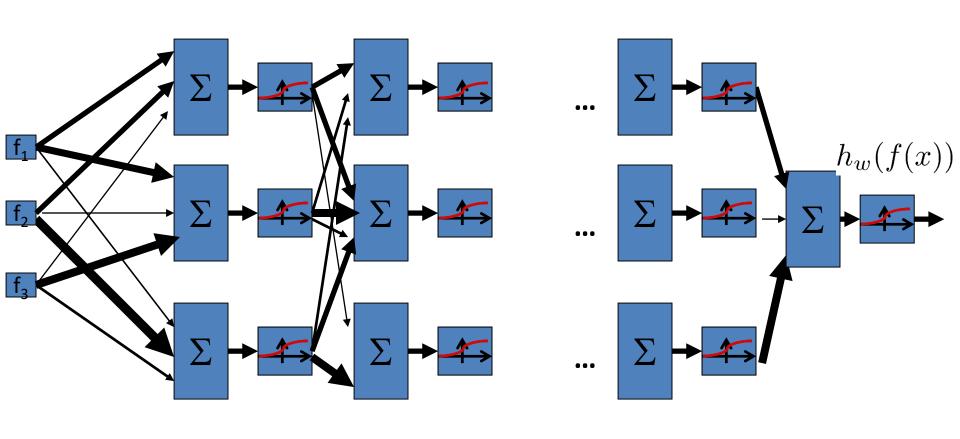
# Perceptron



# Two-Layer Neural Network



# N-Layer Neural Network



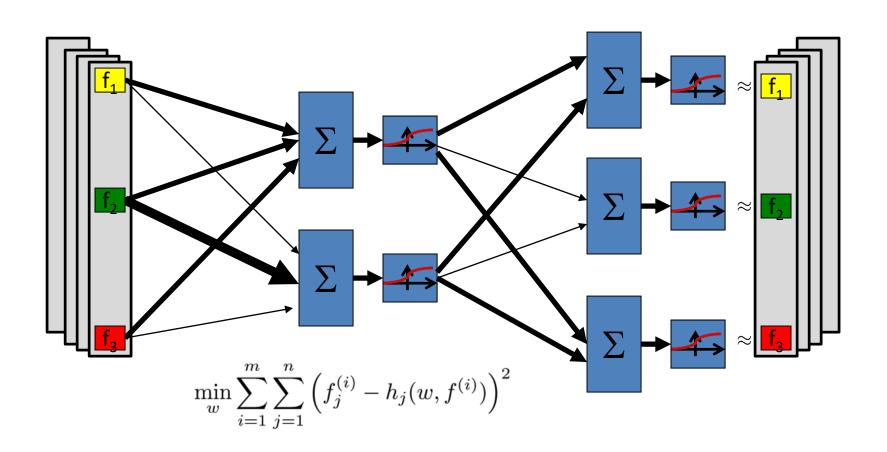
# Hill Climbing

- Simple, general idea:
  - Start wherever
  - Repeat: move to the best n∈
  - If no neighbors better than (
  - Neighbors = small perturbat
- Property
  - Many local optima



--> How to find a good local optimum?

# Auto-Encoder (Crude Idea Sketch)



# Training Procedure: Stacked Auto-Encoder

#### Auto-encoder

– Layer 1 = "compressed" version of input layer

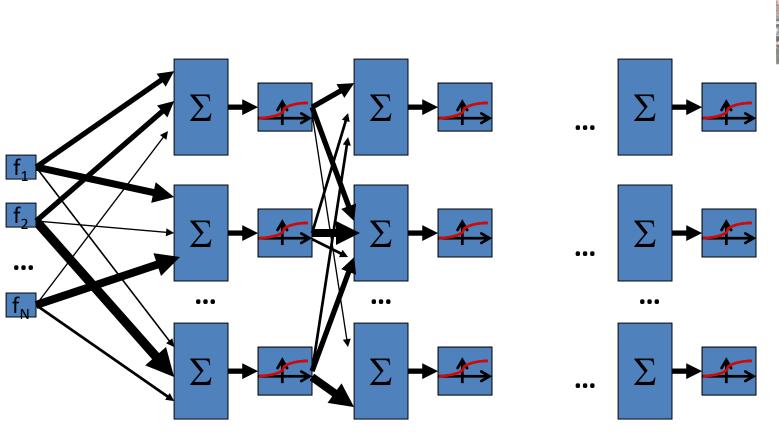
#### Stacked Auto-encoder

- For every image, make a compressed image (= layer 1 response to image)
- Learn Layer 2 by using compressed images as input, and as output to be predicted
- Repeat similarly for Layer 3, 4, etc.

#### Some details left out

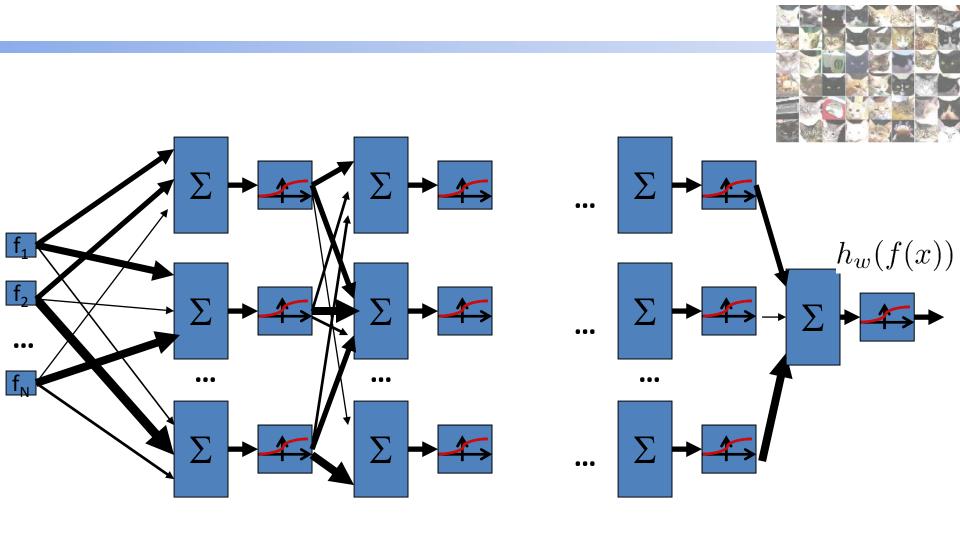
 Typically in between layers responses get agglomerated from several neurons ("pooling" / "complex cells")

### Final Result: Trained Neural Network





### Final Result: Trained Neural Network



## Al 2017: "data" Understanding

Watson Health, Law:

https://www.youtube.com/watch?v=yV 6sd32oW0

• JPMorgan: loan agreements:

https://www.bloomberg.com/news/articles/2017-02-28/jpmorgan-marshals-an-army-of-developers-to-automate-high-finance

Music?
 https://www.youtube.com/watch?v=LSHZ b05W7o

### Al 2017: Robotics 1

Uber self-driving car:

https://www.youtube.com/watch?v=OKJK3 XIGD4

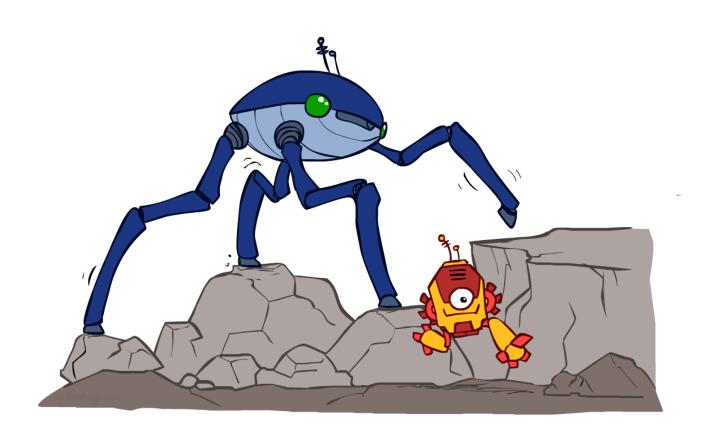


https://www.youtube.com/results?q=self+driving+car+crash&sp=Egl IBA%253D%253D

Hotel receptionist:

https://www.youtube.com/watch?v=GuXRyUiew88

# **Legged Locomotion**



# Quadruped



- Low-level control problem: moving a foot into a new location → search with successor function ~ moving the motors
- High-level control problem: where should we place the feet?

[Kolter, Abbeel & Ng, 2008]

## Experimental setup

Demonstrate path across the "training terrain"

- Run appr e reward function
- Receive "testing terrain"---height map.

# Apprenticeship Learning

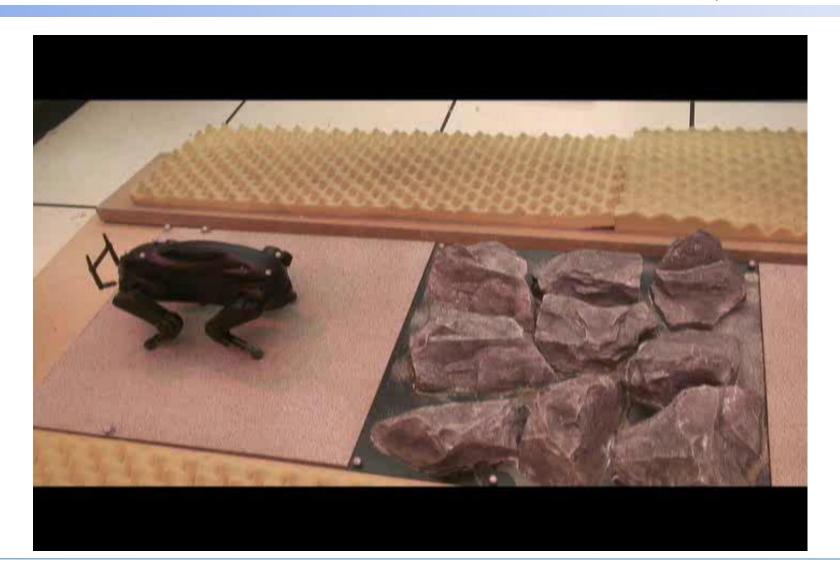
- Goal: learn reward function from expert demonstration
- Assume  $R(s) = w \cdot f(s)$
- Get expert demonstrations  $\mathbf{s} = (s_0, s_1, \dots s_n)$
- Guess initial policy $\pi_0$
- Repeat:
  - Find w which make the expert better the  $\{\pi_0, \pi_1, \dots, \pi_{i-1}\}$   $w_i \leftarrow \operatorname{distinguish}(\pi^*, \{\pi_0, \pi_1, \dots, \pi_{i-1}\})$
  - Solve MDP for new weights w:

$$\pi_i \leftarrow \text{solve}\left(MDP(w_i)\right)$$

### [VIDEO: quad initial.wmv]



### [VIDEO: quad initial.wmv]

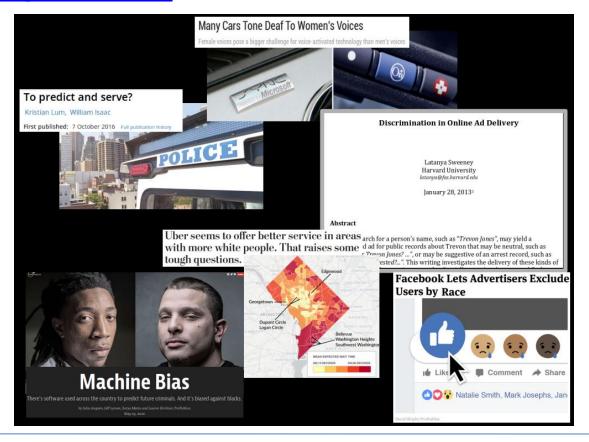


### Al 2017: Humanoid Robots

- Boston Dynamics: <a href="https://www.youtube.com/watch?v=rVlhMGQgDkY">https://www.youtube.com/watch?v=rVlhMGQgDkY</a>
- Fedor 1: <a href="https://www.youtube.com/watch?v=oke01g1-H0s">https://www.youtube.com/watch?v=oke01g1-H0s</a>
- Fedor 2: https://www.youtube.com/watch?v=gZauGhfv-1w

# What can go wrong

 https://nlpers.blogspot.com/2016/11/bias-in-mland-teaching-ai.html



### What to Study Next

### Applications:

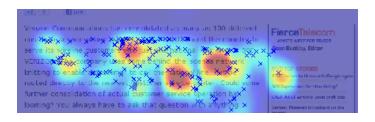
- Robotics: ?
- Natural Language Processing: CS571
- Information Retrieval and Web Search: CS572

### Techniques:

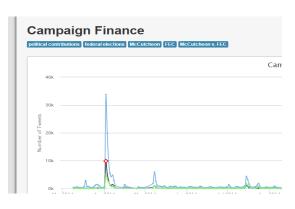
- Machine Learning (CS534): Every semester
- "Deep" Learning: Spring 2018? (requires ML + AI)

### Summer 2017 -

- Openings in IR Lab for internships in:
  - Automated (Web) Question Answering
- Web search ranking, presentation:
  - Measure attention on pages, images with behavior and visual saliency



- (Web-scale) social media analysis:
- More info:
  - <a href="http://ir.mathcs.emory.edu/">http://ir.mathcs.emory.edu/</a>
  - Email: eugene@mathcs.emory.edu



### Fall 2017: Al++

- Will teach AI again in Spring 2017
- Planned changes:
  - Add more intro exercises + labs on Python programming
  - Add final (team) project (AlGym? MindCraft?)
  - **≻Other suggestions?**

### The End.

Good luck on your finals preparation

➤ Please help with evaluations. The written comments will help me design a better course for Fall 2017!