

# CA 01 Wittman Robot Y axis

CA 01 Wittman Robot Y axis Inverter error Rectification Procedure

# Select Login

# ADMIN

# PW = WBIPL

# Set axis position to 18 mm ( check then bush for minimum gap on Y arm side )

# Set int option

# Select absolute encoder

# Select Y axis

# Remove Reference point

# Set Reference point

# Take home position