

# Implicit Curve and Surfaces

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[some slide ideas by Prof. Wojciech Jarosz]

# Implicit curves and surfaces

- Parametric models, meshes and subdivs are shape representations that explicitly represent the curve points and surface boundaries
- Implicit curves and surfaces are an alternative shape representation where boundaries are implicitly defined as the isovalues of a function

$$S = \{\mathbf{p} | f(\mathbf{p}) = 0\}$$

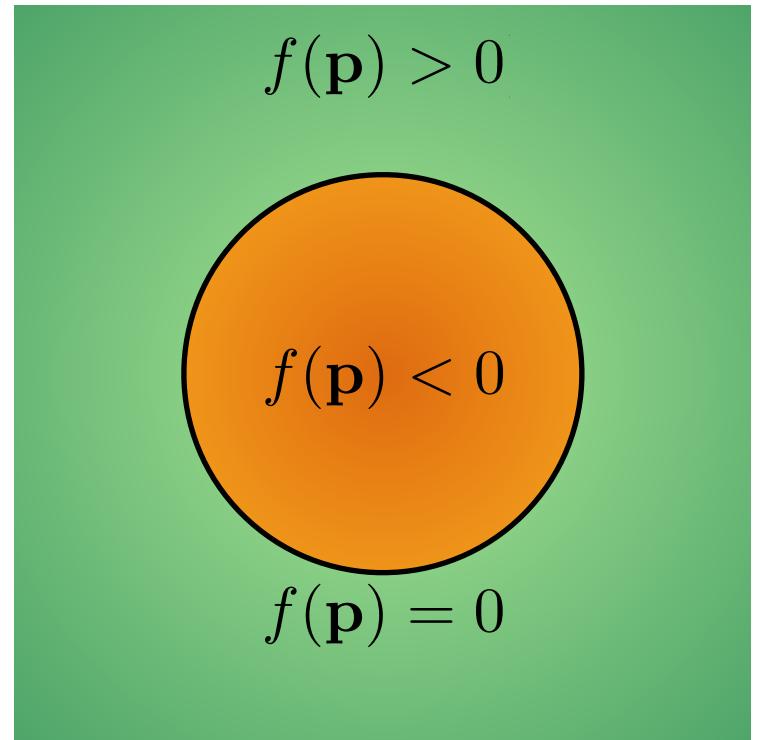
# Signed Distance Functions

- The most used implicit representation is to consider functions that encode the signed distance to the boundary
  - The sign indicates whether we are outside or inside the surface

$O = \{\mathbf{p} | f(\mathbf{p}) > 0\}$  outside

$S = \{\mathbf{p} | f(\mathbf{p}) = 0\}$  curve/surface

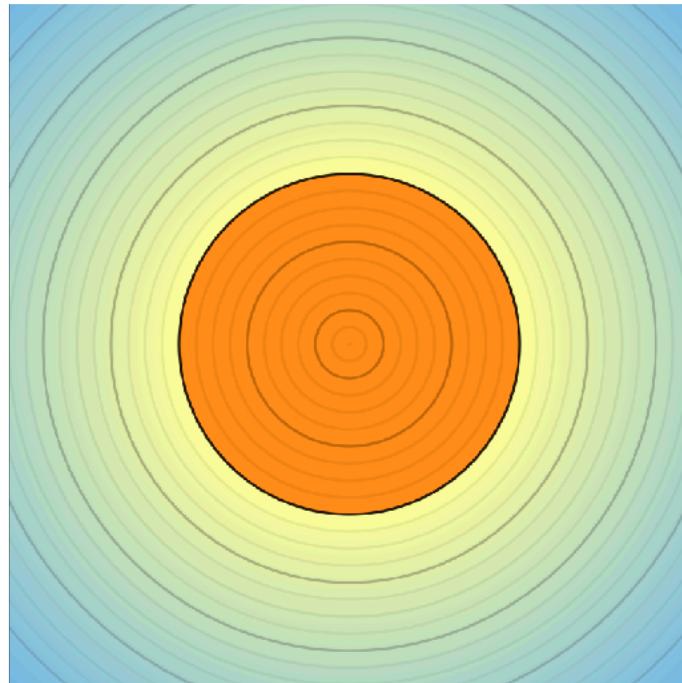
$I = \{\mathbf{p} | f(\mathbf{p}) < 0\}$  indice



# Signed Distance Functions

- Example for circles and spheres

$$f(\mathbf{p}) = |\mathbf{p} - \mathbf{c}| - r$$



# Signed Distance Functions

- Normals of SDFs are computed as the gradient of the function

$$\mathbf{n} = \nabla f(\mathbf{p}) = \left( \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right) (\mathbf{p})$$

- Since the gradient is often not available analytically, we estimate it numerically by finite differences

$$n_x \approx \frac{f(p_x + h) - f(p_x - h)}{2h}$$

$$n_y \approx \frac{f(p_y + h) - f(p_y - h)}{2h}$$

$$n_z \approx \frac{f(p_z + h) - f(p_z - h)}{2h}$$

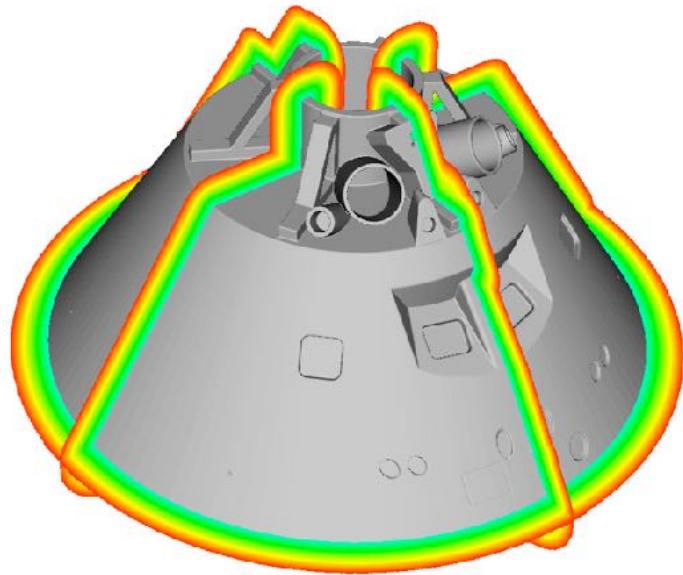
# Signed Distance Functions

- As for many numerical approximation we need to pay attention to numerical precision, in this case for the choice of increment when computing normals



# Signed Distance Functions

- SDFs for surfaces are represented in all points in a volume
- To keep memory usage limited, real implementations store SDFs only in a narrow band around the surface using sparse hash grids



[<https://al-ro.github.io/projects/sdf/>]

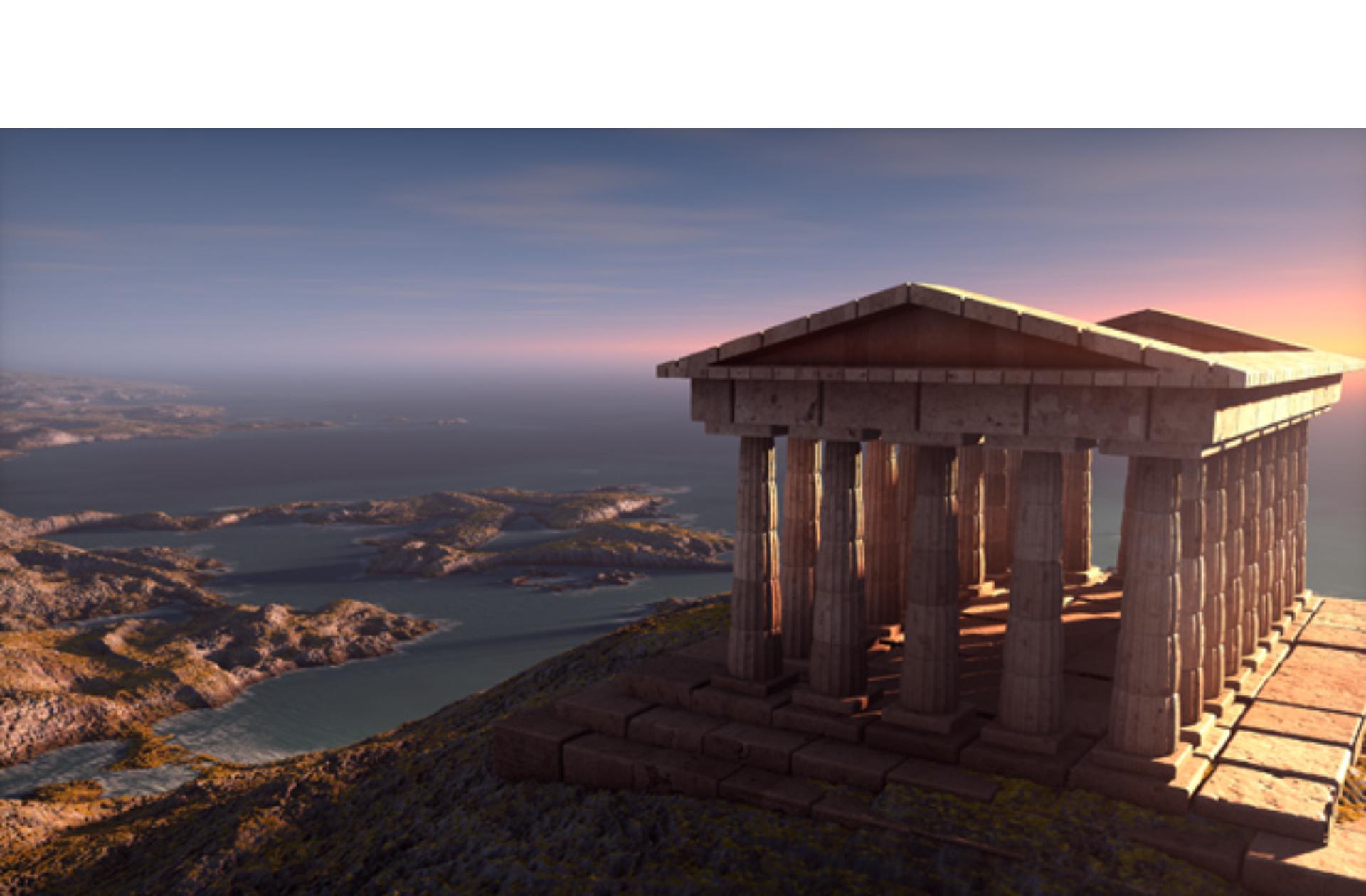
# Signed Distance Functions

- Pros: easy and robust determination of inside/outside
  - used in collision detection for animation
- Pros: easy to determine if a point is on the surface
  - used in raytracing
- Cons: hard to enumerate points on the surfaces
- Cons: hard to modify directly
  
- Applications: Great for procedural modeling
- Applications: Very useful in deep learning

# Implicit Modeling



[Inigo Quilez – <https://www.shadertoy.com/view/4tByz3>]



[Inigo Quilez – <https://www.shadertoy.com/view/IdScDh>]



[Inigo Quilez – <https://www.shadertoy.com/view/4ttSWf>]



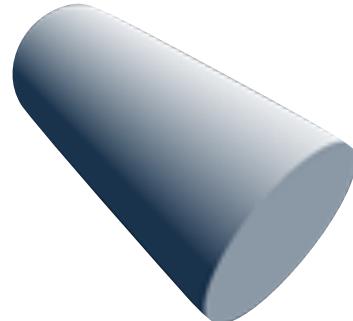
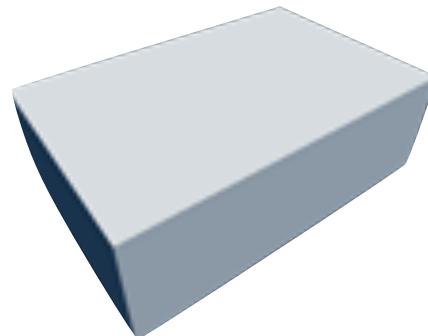
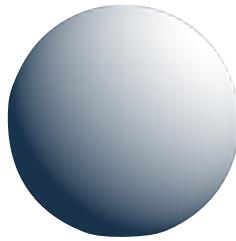
[Inigo Quilez – <https://www.shadertoy.com/view/3lsSzf>]

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# Primitive Shapes

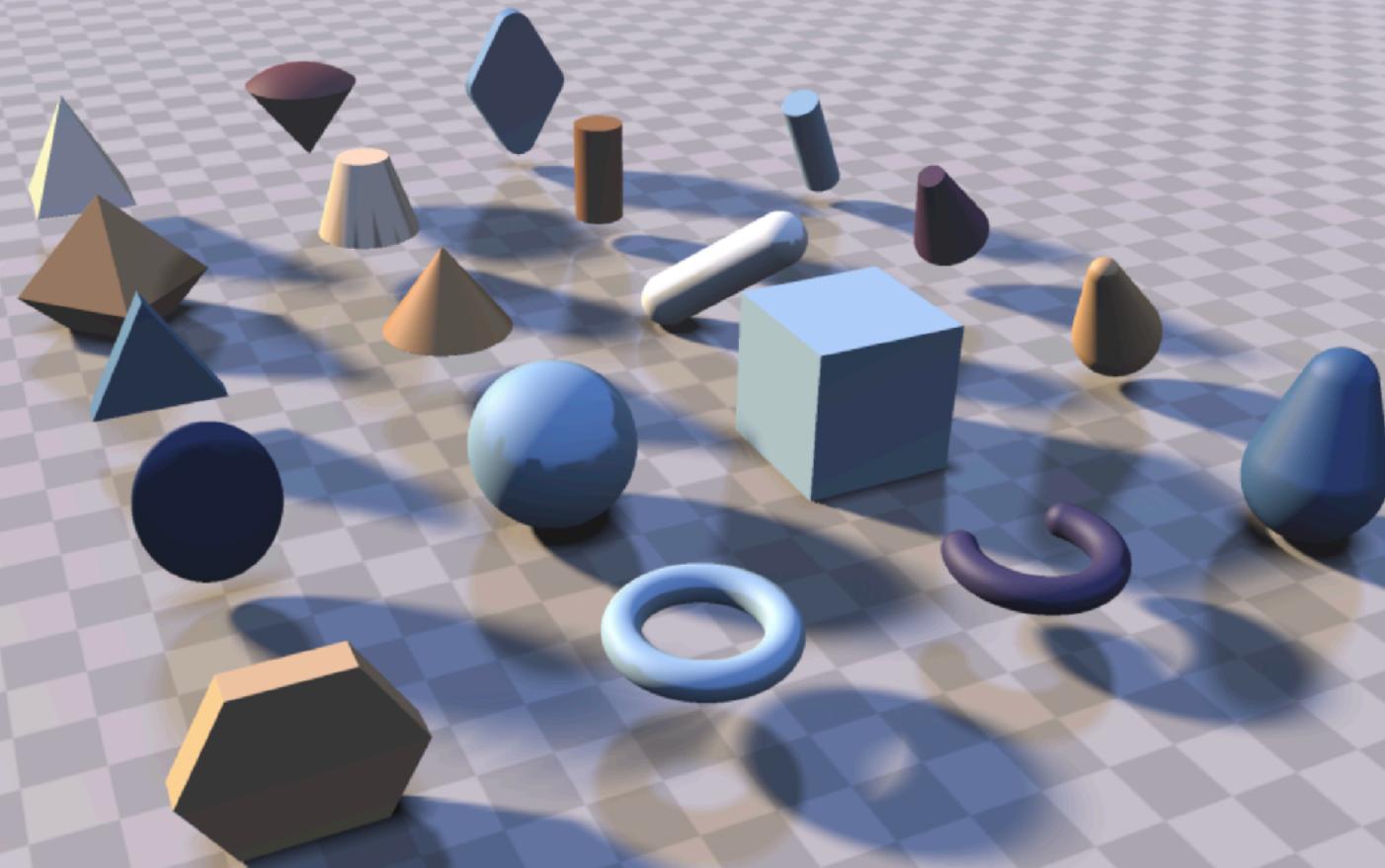
- Create objects by combining basic shapes and sculpting
- Primitive shapes are all shapes you can analytically compute distance
- A good list can be found at <http://www.iquilezles.org>

```
float sdSphere(vec3f p, float s) { return length(p)-s; }
float sdBox(vec3f p, vec3f b) { vec3 q = abs(p) - b;
    return length(max(q,0.0)) + min(max(q.x,max(q.y,q.z)),0.0); }
float sdCylinder(vec3f p, float h, float r) {
    vec2 d = abs(vec2(length(p.xz),p.y)) - vec2(h,r);
    return min(max(d.x,d.y),0.0) + length(max(d,0.0)); }
```



# Primitive Shapes

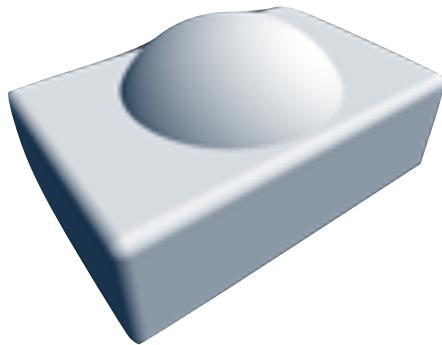
- Primitive shapes are all shapes you can analytically compute distance



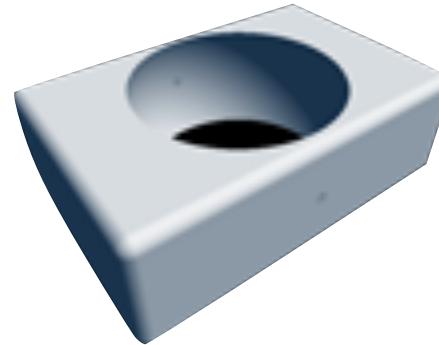
# Boolean Operations

- Boolean operations in modeling are defined over object volumes
- We are interested in computing the surface of the resulting volume
- With SDFs we can trivially compute booleans

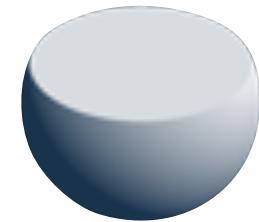
Union



Subtraction



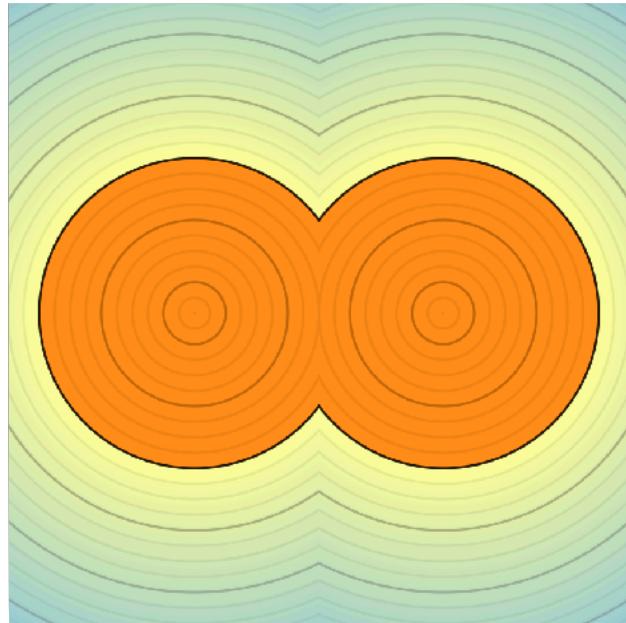
Intersection



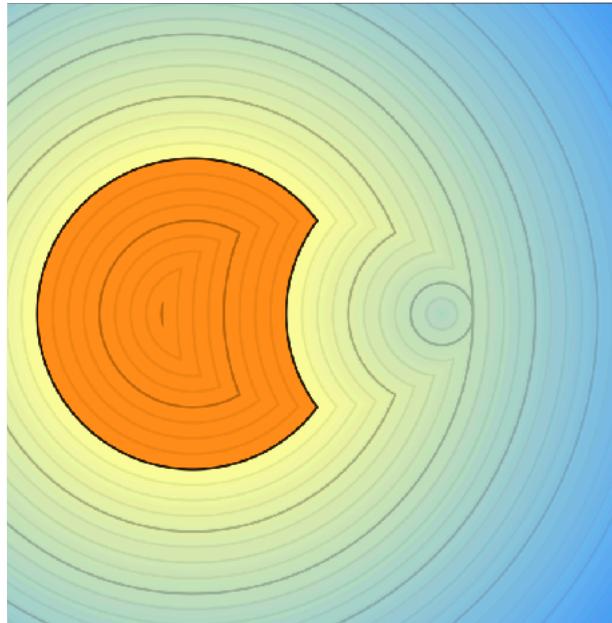
# Boolean Operations

- Boolean can be defined by simply combining SDFs with min/max operations

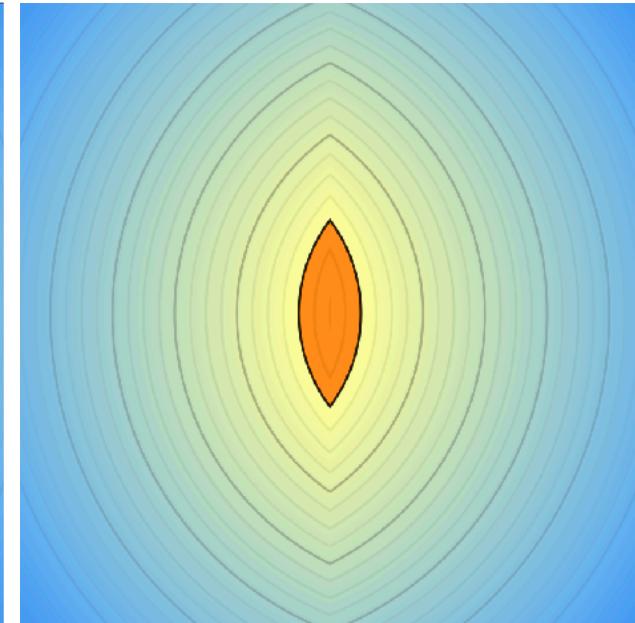
Union



Subtraction



Intersection



$$f_u(\mathbf{p}) = \min(f_1(\mathbf{p}), f_2(\mathbf{p})) \quad f_s(\mathbf{p}) = \max(f_1(\mathbf{p}), -f_2(\mathbf{p})) \quad f_i(\mathbf{p}) = \max(f_1(\mathbf{p}), f_2(\mathbf{p}))$$

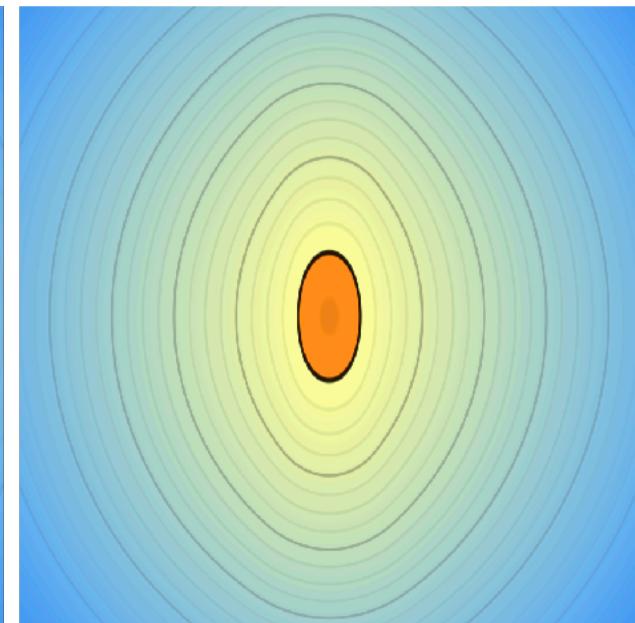
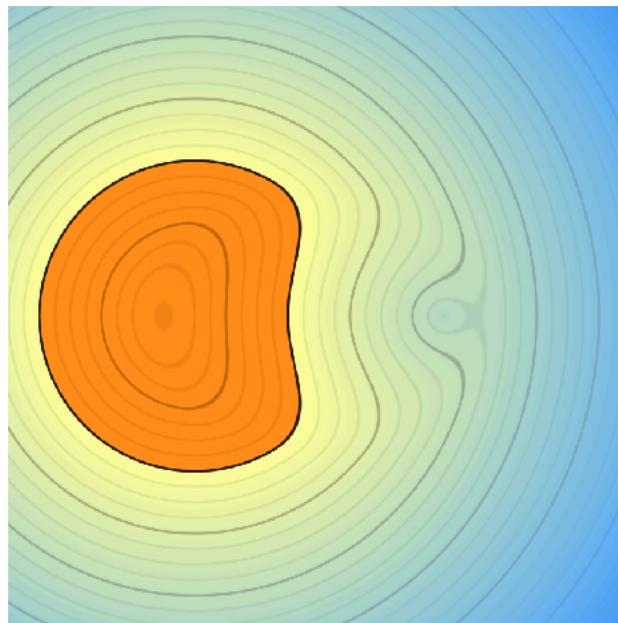
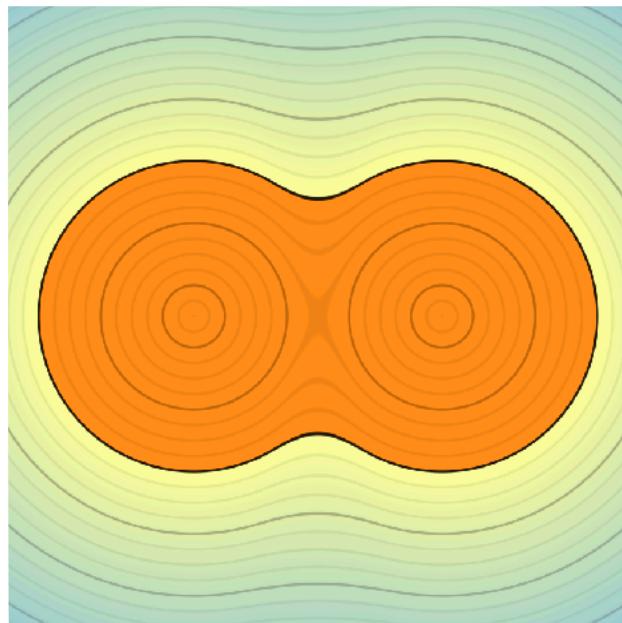
# Smooth Boolean Operations

- Boolean operations can be generalized to perform smooth blending between shapes by introducing blending functions

“Smooth” Union

“Smooth” Subtraction

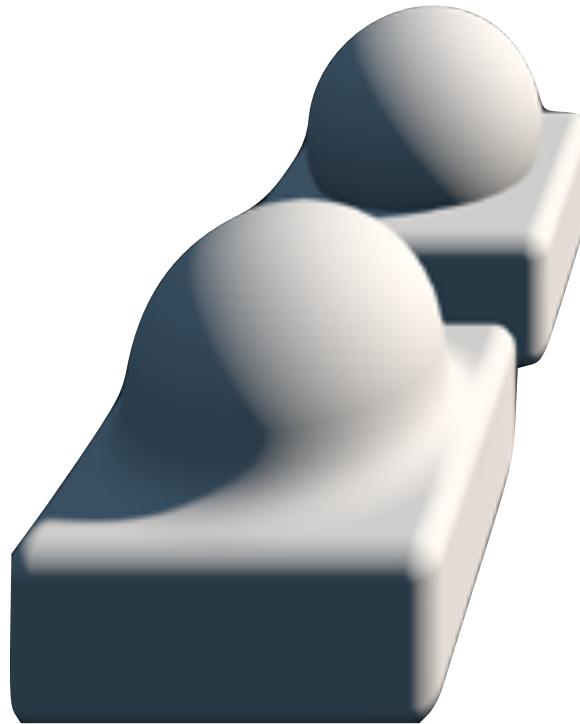
“Smooth” Intersection



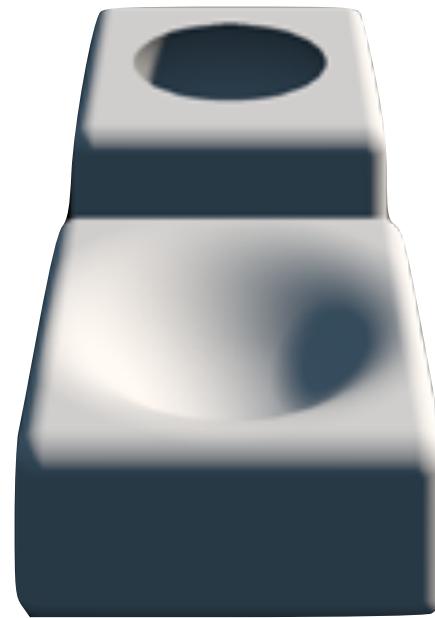
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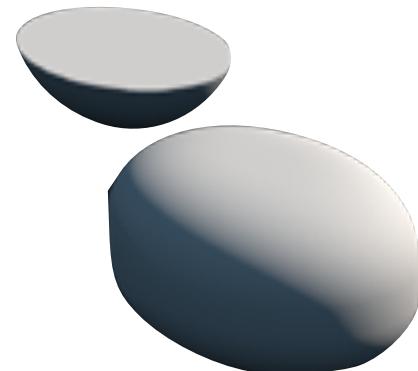
Union



Subtraction



Intersection



# Smooth Boolean Operations

- Boolean operations can be generalized to perform smooth blending between shapes by introducing blending functions



# Boolean Operations

```
float opUnion( float d1, float d2 ) { min(d1,d2); }

float opSubtraction( float d1, float d2 ) {
    return max(-d1,d2); }

float opIntersection( float d1, float d2 ) {
    return max(d1,d2); }

float opSmoothUnion( float d1, float d2, float k ) {
    float h = clamp( 0.5 + 0.5*(d2-d1)/k, 0.0, 1.0 );
    return mix( d2, d1, h ) - k*h*(1.0-h); }

float opSmoothSubtraction( float d1, float d2, float k ) {
    float h = clamp( 0.5 - 0.5*(d2+d1)/k, 0.0, 1.0 );
    return mix( d2, -d1, h ) + k*h*(1.0-h); }

float opSmoothIntersection( float d1, float d2, float k ) {
    float h = clamp( 0.5 - 0.5*(d2-d1)/k, 0.0, 1.0 );
    return mix( d2, d1, h ) + k*h*(1.0-h); }
```

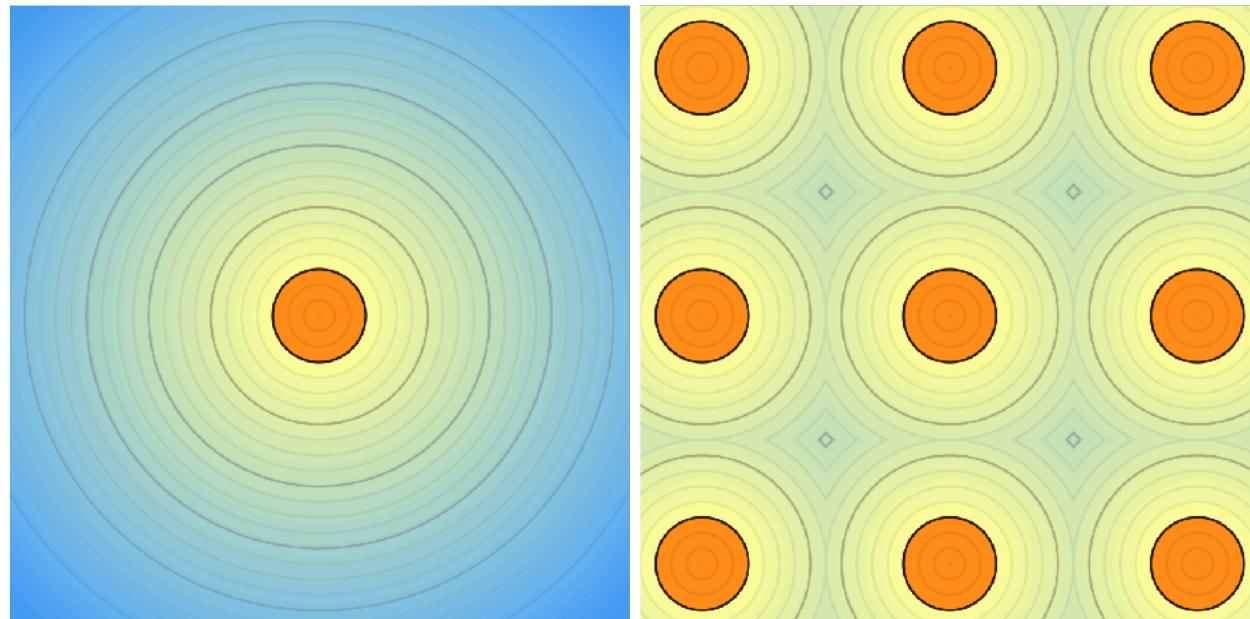
# Transforms and Repetition

- We can transform an SDF by querying the function with the point inversely transformed

$$Tf(\mathbf{p}) = f(T^{-1}\mathbf{p})$$

- We can repeat a shape by taking the modulus of the point

$$f_r(\mathbf{p}, \mathbf{c}) = f(\text{mod}(\mathbf{p} + \mathbf{c}/2, \mathbf{c}) - \mathbf{c}/2)$$



# Rendering Implicit Surfaces

# Rendering Implicit Surfaces

- Method 1: convert SDF to poly lines (2D) or meshes (3D)
  - Many well-studied algorithms to do this
  - Different tradeoffs
  - All quite tricky to implement correctly, so won't cover in details
- Method 2: retrace SDFs directly
  - Fairly robust method
  - Still not well studied for all cases

# Marching squares

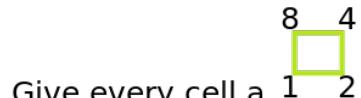
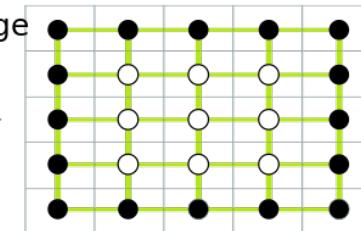
1	1	1	1	1
1	2	3	2	1
1	3	3	3	1
1	2	3	2	1
1	1	1	1	1

Threshold  
with iso-value

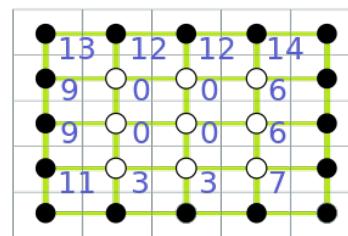


0	0	0	0	0
0	1	1	1	0
0	1	1	1	0
0	1	1	1	0
0	0	0	0	0

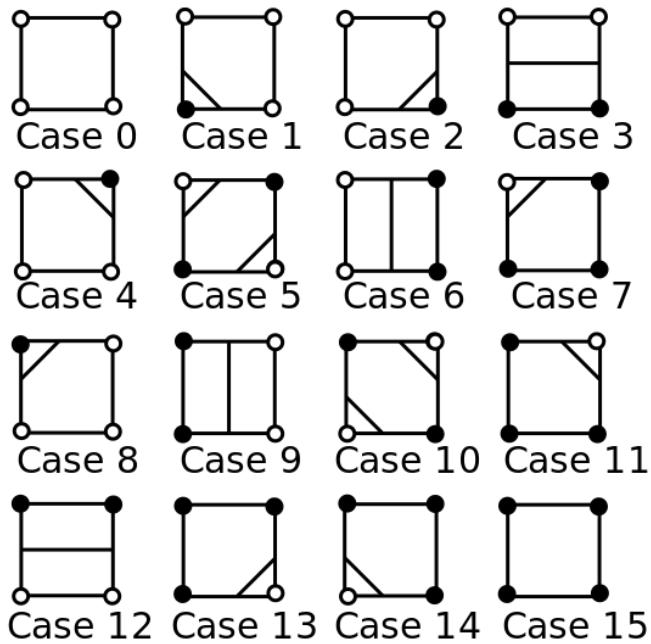
Binary image  
to cells



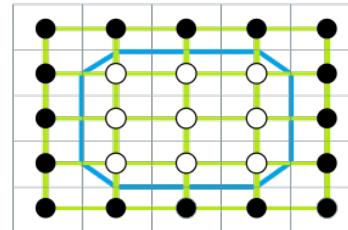
Give every cell a  
number based on  
which corners are  
true/false



Look-up table contour lines



Look up the contour  
lines in the database  
and put them in  
the cells



Look at the original  
values and use linear  
interpolation to  
determine a  
more accurate position  
of all the line end-points



1	1	1	1	1
1	2	3	2	1
1	3	3	3	1
1	2	3	2	1
1	1	1	1	1

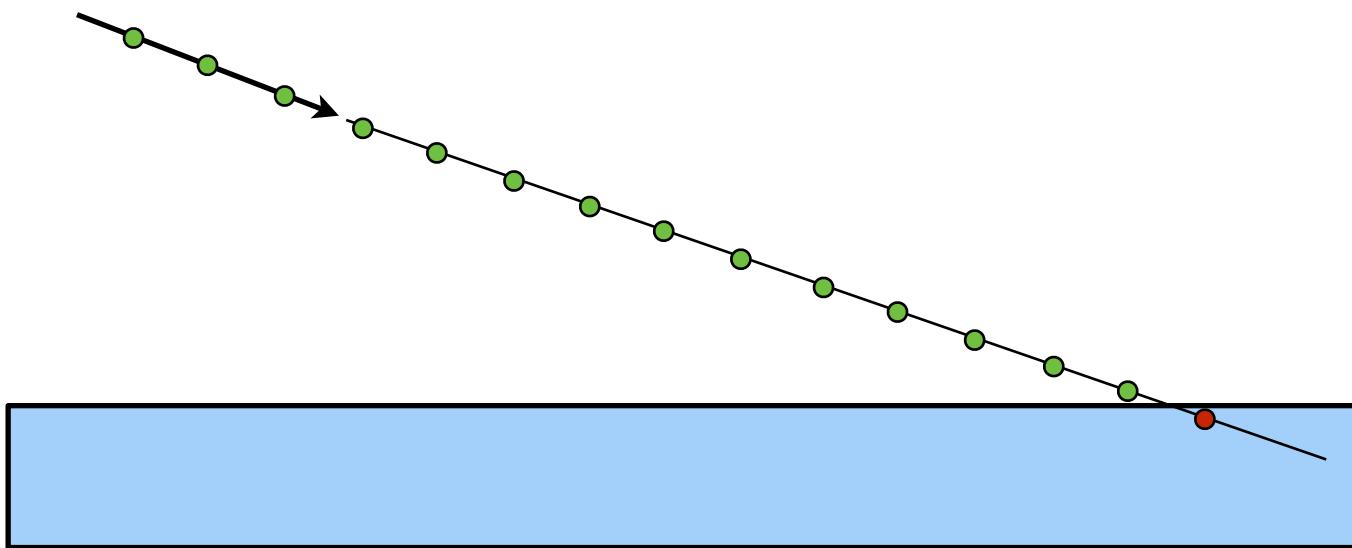
[Wikipedia]

# Ray tracing implicits

- For models that are boolean combination of analytics primitives, we could compute the solution numerically since method exists for all those surfaces
- But that would be restrictive and would not work for general SDF
- The most common solution is to solve the problem numerically
  - Several methods exist in practice

# Ray marching

- The simplest method is to walk along the ray at fixed increments and stop when the SDF is negative
- This method works in all cases, but it is not very accurate nor very fast



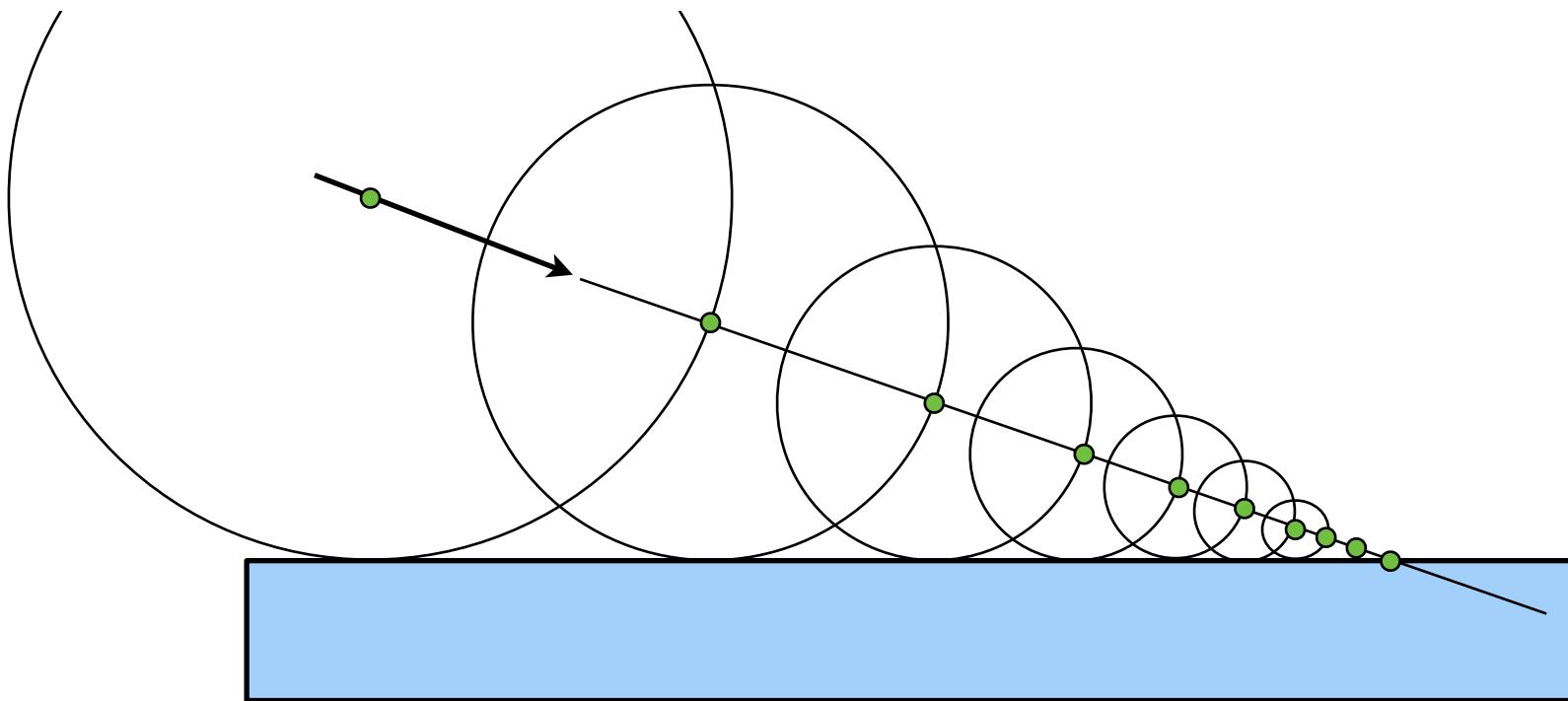
# Ray marching

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- This method works in all cases, but it is not very accurate nor very fast

```
bool raytrace(ray3f ray, SDF* sdf, float* dist) {  
    auto t = ray.tmin;  
    while(t < ray.tmax) {  
        auto p = eval_ray(ray, t);  
        if(eval_sdf(sdf, p) < 0) { *dist = t; return true; }  
        t += step_size;  
    }  
    return false;  
}
```

# Sphere tracing

- The key to make ray marching faster and more accurate is to step along the ray each time with the longest distance we know it is safe
- That distance is just the SDF itself evaluated at the point we are at



# Sphere tracing

- The key to make ray marching faster and more accurate is to step along the ray each time with the longest distance we know it is safe
- That distance is just the SDF itself evaluated at the point we are at

```
bool spheretrace(ray3f ray, SDF* sdf, float* dist) {  
    auto t = ray.tmin;  
    while(t < ray.tmax) {  
        auto p = eval_ray(ray, t);  
        auto d = eval_sdf(sdf, p);  
        if(d < epsilon) { *dist = t; return true; }  
        t += d;  
    }  
    return false;  
}
```

# Texture mapping

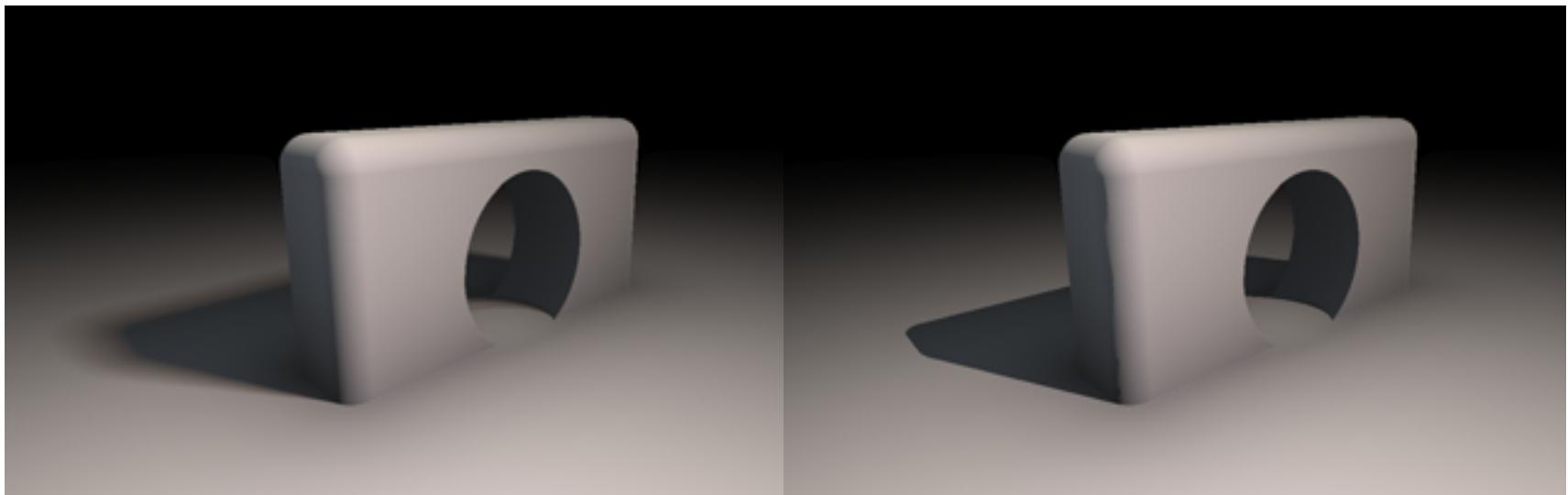
- SDFs do not define texture coordinates and support booleans
- Instead of applying 2D texture, we apply 3D textures to them
- 3D texture are defined in the volume so we can look them up at any position
- Just like real-world objects that have the inside filled in



[<http://lernertandsander.com/cubes>]

# Lighting SDFs

- Since we can retrace them, we can use any lighting algorithm
- We can also cheat lighting by taking advantage of the SDF nature



# Dreams





