Robotics 1
Material and Textbook Cross-references

http://www.diag.uniroma1.it/~deluca/rob1_en.php

Prof. Alessandro De Luca

This document describes the relationships between topics in the course program, content of PowerPoint slides of the lectures (available as PDF files in the course website), and associated parts (chapters/sections) in the course textbook in English.

The names of the files with lecture slides are in the format "NN_filename.pdf", with the number of pages in parentheses.

Textbook:

B. Siciliano, L. Sciavicco, G. Villani, G. Oriolo: "Robotics: Modelling, Planning and Control", Springer, 2009 (3rd Edition)

Note:

The above is the translated version of the book:

B. Siciliano, L. Sciavicco, G. Villani, G. Oriolo: "Robotica: Modellistica, pianificazione e controllo", McGraw-Hill, 2008 (3a Edizione)

Organization of chapters and sections is the same in the English and Italian versions.

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Topic in the course program	Textbook cross-references	Slides (with number of pages) and other course material
Introduction		
Course program and information	---	00_Information.pdf (21) with 15 videos
Industrial robot manipulators	Chap. 1	01_IndustrialRobots.pdf (68) with 31 videos + 2019_WorldRobotics_Presentation_Industrial&Service.pdf 2018_WorldRobotics_Presentation_Industrial&Service.pdf 2018_WorldRobotics_ExecSummary_Service.pdf 2018_WorldRobotics_ExecSummary_Industrial.pdf 2017_WorldRobotics_ExecSummary_Service.pdf 2017_WorldRobotics_Presentation_Service.pdf 2017_WorldRobotics_ExecSummary_Industrial.pdf 2017_WorldRobotics_Presentation_Industrial.pdf 2016_WorldRobotics_ExecSummary_Industrial.pdf 2016_WorldRobotics_PressCharts_industrial.pdf 2016_WorldRobotics_ExecSummary_Service.pdf 2016_WorldRobotics_PressCharts_Service.pdf
Service applications		02_ServiceRobots.pdf (69) with 32 videos
Components		
Mechanics and Actuators	Chap. 5	03_CompsActuators.pdf (23) with 7 videos
Proprioceptive sensors		04_CompsSensorsProprio.pdf (27) with 1 video
Exteroceptive sensors		05_CompsSensorsExtero.pdf (58) with 20 videos
Robot programming Supervision and control architectures	Chap. 6	06_ProgrammingArchitectures.pdf (47) with 5 videos
Kinematic models of manipulators		
Representations for position/orientation Homogeneous transformations	Chap. 2: Par. 2.1-2.3, 2.5-2.6	07_PositionOrientation.pdf (20)
	Chap. 2: Par. 2.4, 2.7	08_EulerRPYHomogeneous.pdf (14)
Direct kinematics	Chap. 2: Par. 2.8 (except 2.8.3), 2.10	09_DirectKinematics.pdf (31) with 2 videos 09_Exercise_DH_KukaLWR4 (8) with 3 videos + *Matlab symbolic code:* dirkin_SCARA.m
Further examples of direct kinematics	Chap. 2: Par. 2.9 (except 2.9.2)	Robotics1_Homework1_10-11 (6) [KUKA KR5] Robotics1_Homework1_11-12 (14) [COMAU Smart5 NJ4] Data_ABB-IRB6400.pdf Data_COMAU-SmartS2.pdf

		Data_Fanuc-2000i.pdf Product_ABB-IRB6400PE.pdf Product_Bosch-SR6SR8.pdf
Inverse Kinematics (including numerical methods)	Chap. 2: Par. 2.12 Chap. 3: Par. 3.7.1-3.7.2, only begin of 3.7.3	10_InverseKinematics.pdf (41) with 2 videos Article_KinInvPuma600.pdf
Differential kinematics (including singularities)	Chap. 3: Par. 3.1-3.4, 3.6	11_DifferentialKinematics.pdf (31)
Inverse differential kinematics	Chap. 3: Par. 3.5, 3.7.4	12_InverseDiffKinStatics.pdf (37)
Statics and force transformations	Chap. 3: Par. 3.8 (except 3.8.3)	
Manipulability	Chap. 3: Par. 3.9	
Planning of motion trajectories		
Joint space trajectories	Chap. 4: Par. 4.1-4.2	13_TrajectoryPlanningJoints.pdf (30) with 7 videos
Operational space trajectories	Chap. 4: Par. 4.3	14_TrajectoryPlanningCartesian.pdf (28) with 3 videos
Motion control		
Joint- and Cartesian-level kinematic control	Chap. 8: Par. 8.1 Chap. 3: Par. 3.7.5	15_KinematicControl.pdf (29) with 2 videos
Independent joint control (dynamic, single axis)	Chap. 8: Par. 8.3-8.4	16_DynamicControlSingleAxis.pdf (17)