

# Receiver Operating Characteristic for thresholding-based decision

Laboratory 2, DEPI

## Objective

Simulate a binary constant-signal detection system based on thresholding, and characterize the system via the Receiver Operating Characteristic.

## Theoretical aspects

Consider a binary message encoded with two constant levels 0 and  $A$ , affected by white noise. A sample of the signal is equal to:

$$r = s + n,$$

where  $s$  is the true signal (0 or  $A$ ), and  $n$  is the sample of noise.

The receiver decides what is the true signal by comparing the sample  $r$  with a threshold  $T$ , whose value depends on the specific decision criterion used:

- Maximum Likelihood
- Minimum error probability
- etc.

For one decision, there can be 4 outcomes:

- correct rejection: signal is 0, detection is 0
- false alarm: signal is 0, detection is 1
- miss: signal is 1, detection is 0
- hit (correct detection): signal is 1, detection is 1

The Receiver Operating Characteristic (ROC) curve is the plot of  $P(\text{hit})$  against  $P(\text{false alarm})$ .

## Exercises

1. Simulate threshold-based detection with a single sample, as follows:
  - Generate a vector of 100000 values 0 or  $A$ , with equal probability (hint: use `rand()` and compare to 0.5)
  - Add over it a random noise with normal distribution  $\mathcal{N}(0, \sigma^2 = 1)$
  - Compare each element with  $T$  to decide which sample is logical 0 or logical 1 ( $A$ )
  - Compare the decision result with the true original vector, and count how many correct detections and how many false alarms have been.
  - Estimate  $P(\text{hit})$  and  $P(\text{false alarm})$  by dividing the above numbers to the size of the vector
2. Wrap the above code into a function `[phit, pfa] = myThreshDet(T)` that returns the two probabilities for a given  $T$ . Draw the ROC by running the function for 100 values of  $T$  uniformly spaced between 0 and  $A$ , and plotting the resulting vector `phit` against `pfa` (
3. Repeat the same simulation for two samples per bit:
  - double the values of the starting vector, making two consecutive 0 or  $A$  values, e.g.

`[00AA00AAAA00AA...]`
  - the decision now uses **the average value** of the two consecutive samples of a bit
  - plot the ROC and compare with the first one. Which is better?

## Final questions

1. In a practical scenario, what is the disadvantage of using 2 samples for detection, compared to just 1?