

## Lab 2

1. Plot on the same figure the signals  $\sin(2\pi ft)$  and  $\cos(2\pi ft)$  , with  $f = 0.3$  and  $t \in [0, 10]$ .
2. Load the audio file 'Kalimba.mp3' in the Matlab workspace. Only load samples between 1 and 200000 (to avoid out of memory error)
  - a. Play it through the computer's audio device
  - b. Change the sampling frequency to half the correct value, and play again. How will the sound be changed?
  - c. Amplify the sound by multiplying the data by 4. Play the sound and observe the difference.
  - d. Swap the left and right channels (it's a stereo file) and play the sound again.

## Lab 3

1. Load the **Lena** image (use `imread()`), convert it to double, convert it to grayscale, scale the values to the  $[0, 1]$  range, and display the image (use `imshow()`).
2. Construct a new image based on the **Lena**, but in which each pixel value is set as a linear combination of the original pixels around it, as in the following equation:

$$\begin{aligned} y[i, j] = & \frac{1}{9}x[i-1, j-1] + \frac{1}{9}x[i-1, j] + \frac{1}{9}x[i-1, j+1] \\ & + \frac{1}{9}x[i, j-1] + \frac{1}{9}x[i, j] + \frac{1}{9}x[i, j+1] \\ & + \frac{1}{9}x[i+1, j-1] + \frac{1}{9}x[i+1, j] + \frac{1}{9}x[i+1, j+1] \end{aligned}$$

Ignore the first and last row/column, if needed.

Display the resulting image in a new window. How did it change?

3. Repeat Exercise 2 but change the values of the coefficients to

$$\begin{bmatrix} 0 & -1 & 0 \\ -1 & 5 & -1 \\ 0 & -1 & 0 \end{bmatrix}$$

## Lab 4

1. Load the **Lena** image (use `imread()`), convert it to a grayscale image, convert it to **double** type, adapt the values to the  $[0, 1]$  range, and display it (use `imshow()`).
2. Create a video sequence by scrolling the Lena image circularly to the right, by 3 pixels at every frame. Display the video at 25fps.

Code template for creating a video sequence in Matlab:

```
height = ...; % desired height
width  = ...; % desired width
NoF    = ...; % desired number of frames
% an array of size height x width x 1 x NoF:
video  = zeros(height, width, 1, NoF);
for i = 1:NoF
    video(:,:,i) = ... the frame number i ... ;
end

% Play the sequence
imshow(video);
```

## Lab 5

1. Create a function `mysys1()` that implements the following system  $H_1$ :

$$y[n] = H_1\{x[n]\} = \frac{1}{4}x[n] - \frac{1}{2}x[n-1] + \frac{1}{4}x[n-2]$$

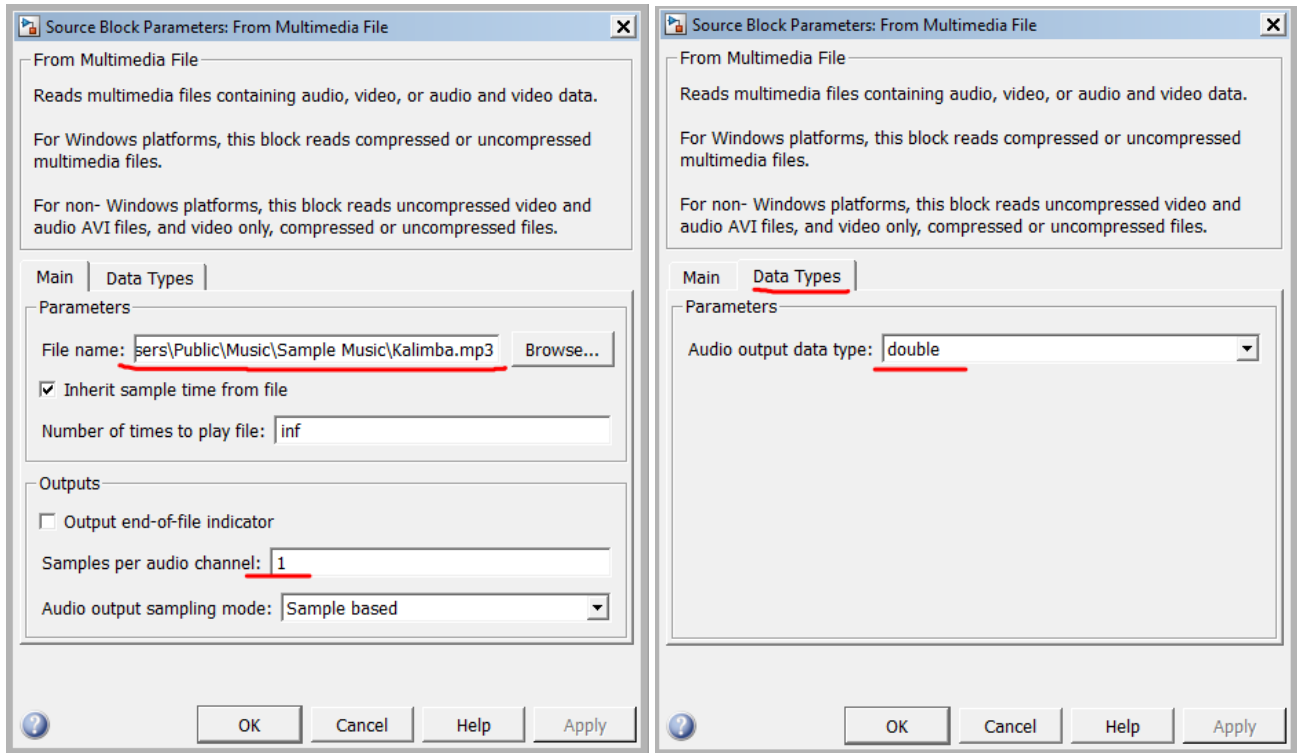
- the function takes 1 input argument **x** and outputs 1 result vector **y**
2. In a separate script, test the linearity of this system in the following way:
  - generate two random vectors **x** and **y** and two random numbers **a** and **b**
  - apply the function `mysys1()` to **a\*x**, **b\*y**, and **a\*x + b\*y**, and check if the results verify the linearity equation
  - the check shall be repeated for 5 times, with 5 different randomly generated data
  - is the system linear?

## Lab 6

1. Create a Simulink model to implement the following system  $H_1$ :

$$y[n] = H_1\{x[n]\} = \frac{1}{4}(x[n] + x[n-1] + x[n-2] + x[n-3])$$

- the system should be implemented as a Subsystem block with one input and one output signal
2. Apply the system to the audio data (mp3 file) loaded with `FromMultimediaFile` block and play the resulting output using `Buffer` and `ToAudioDevice` blocks.
    - make sure you set the properties of the `FromMultimediaFile` block as shown below:



## Lab 7

1. Create a Simulink model to implement the following system  $H_1$ :

$$y[n] = H_1\{x[n]\} = 0.8y[n-1] + 0.25x[n] + 0.1x[n-1]$$

- the system should be implemented as a Subsystem block with one input and one output signal
2. Test linearity of this system as follows:
    - create three copies of the system inside the model (copy/paste)
    - use two random input vectors  $\mathbf{x}$  and  $\mathbf{y}$  (use two *Random* blocks)
    - apply input signals  $\mathbf{x}$ ,  $\mathbf{y}$  and  $\mathbf{x}+\mathbf{y}$  to the three copies of the system
    - add the outputs of the systems which have  $\mathbf{x}$  and  $\mathbf{y}$  as inputs, then subtract the output of the system which has  $\mathbf{x} + \mathbf{y}$  as input
    - show the resulting signal. Is the system linear?

## Lab 9

1. Generate a 100 samples long signal  $\mathbf{x}$  defined as  $x[n] = 0.7 \cos(2\pi f_1 n) + 1.2 \sin(2\pi f_2 n)$ , with  $f_1 = 0.05$  and  $f_2 = 0.1$ .
  - a. Plot the signal in the top half of a figure (use `subplot()`).
  - b. Compute the Fourier series coefficients with `fft()` and plot their magnitude in the lower half of the figure.
2. Take the Fourier series coefficients of the above signal  $\mathbf{x}$ , and keep only the coefficients of the DC + first two sinusoidal components. Generate the signal from the Fourier coefficients with `ifft()` and plot it. What is the resulting signal?

## Lab 12

1. Use the Filter Design tool in Matlab (`fdatool`) to design an oscillator with frequency 0.05. Implement it in Simulink, visualize & play the output signal.
  - design a system of order 2 with 2 conjugate poles placed **on the unit circle** at the correct frequency, and 2 zeros at low & high frequencies
  - implement the system in Simulink. You can **omit the input signal** (not necessary, an oscillator has no input)
  - set a non-zero initial condition in the system, to start-up the oscillator
  - play the resulting output using **Buffer** and **ToAudioDevice** blocks. What frequency do you hear when running the simulation?