# IIR filter design with Pade method

Lab 2, SDP

### **Objective**

Using the Pade method for designing IIR filters of various types

#### Theoretical notions

#### **Exercises**

1. Use the Pade method to find out the parameters of the system with the following system function

$$H(z) = \frac{b_0 + b_1 z^{-1} + b_2 z^{-2}}{1 + a_1 z^{-1} + a_2 z^{-2}},$$

considering the desired impulse response to be:

$$h_d[n] = \left(\frac{1}{3}\right)^n \cos\left(\frac{n\pi}{4}\right).$$

2. Use Matlab to solve numerically the Pade system for the previous exercise:

$$\begin{bmatrix} h_d[0] \\ h_d[1] \\ h_d[2] \\ h_d[3] \\ h_d[4] \end{bmatrix} = \begin{bmatrix} 0 & 0 & 1 & 0 & 0 \\ -h_d[0] & 0 & 0 & 1 & 0 \\ -h_d[1] & -h_d[0] & 0 & 0 & 1 \\ -h_d[2] & -h_d[1] & 0 & 0 & 0 \\ -h_d[3] & -h_d[2] & 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} a_1 \\ a_2 \\ b_0 \\ b_1 \\ b_2 \end{bmatrix}$$

3. Implement in Matlab a function for creating and then solving the equation system resulting from the Pade method:

1

The function shall have the following arguments:

- order: the order of the designed filter
- hd: a vector holding the first samples of the desired impulse response

The function shall return the coefficients of the system function for the resulting filter:

- b: the numerator coefficients
- a: the denominator coefficients
- 4. Use the pade\_method() function above to design a second order filter with the Pade method, for approximating the desired impulse response given below:

$$h_d[n] = \left(\frac{1}{3}\right)^n \cdot \cos(\frac{\pi}{4}n) \cdot u[n]$$

5. Use impz() to find the impulse response of a filter with

$$H(z) = \frac{1 - 1.7z^{-1} + 0.7z^{-2}}{1 + 1.3z^{-1} + 0.4z^{-2}}.$$

Then use our pade\_method() to approximate a filter of order 2 from the impulse response. Do we obtain the same H(z) back again?

6. Load a sample audio file in Matlab and filter it with the filter found above. Play the filtered signal. How does it sounde like? Compare it with the original signal.

## **Final questions**

1. TBD