# **Syllabus**

# Savitribal Phule Pune University Fourth Year of Computer Engineering (2015 Course) 410242: Artificial Intelligence and Robotics

Teaching Scheme:

Credit

**Examination Scheme:** 

TH: 03 Hours/Week

03

In-Sem (Paper) : 30 Marks

End-Sem (Paper): 70 Marks

Prerequisite Courses: 210254 - Principles of Programming Languages

Companion Course: 410246 - Laboratory Practice I

#### Course Objectives

- To understand the concept of Artificial Intelligence (AI)
- To learn various peculiar search strategies for AI
- To acquaint with the fundamentals of mobile robotics
- To develop a mind to solve real world problems unconventionally with optimality.

### **Course Outcomes**

On completion of the course, student will be able to -

- Identify and apply suitable Intelligent agents for various AI applications
- Design smart system using different informed search / uninformed search or heuristic approaches.
- Identify knowledge associated and represent it by ontological engineering to plan a strategy to solve given problem.
- Apply the suitable algorithms to solve AI problems.

## **Course Contents**

Unit1: Introduction

(08 Hours)

Artificial Intelligence: Introduction, Typical Applications. State Space Search: Depth Bounded DFS, Depth First Iterative Deepening. Heuristic Search: Heuristic Functions, Best First Search, Hill Climbing, Variable Neighborhood Descent, Beam Search, Tabu Search. Optimal Search: A\* algorithm, Iterative Deepening A\*, Recursive Best First Search, Pruning the CLOSED and OPEN Lists.

(Refer Chapter 1)

Unit 1 : Problem Decomposition and Planning

(08 Hours)

Problem Decomposition: Goal Trees, Rule Based Systems, Rule Based Expert Systems. Planning: STRIPS, Forward and Backward State Space Planning, Goal Stack Planning, Plan Space Planning, A Unified Framework For Planning. Constraint Satisfaction: N-Queens, Constraint Propagation, Scene Labeling, Higher order and Directional Consistencies, Backtracking and Look ahead Strategies. (Refer Chapter 2)

# Upit III : Logic and Reasoning

(08 Hours)

Knowledge Based Reasoning: Agents, Facets of Knowledge. Logic and Inferences: Formal Logic, Propositional and First Order Logic, Resolution in Propositional and First Order Logic, Deductive Retrieval, Backward Chaining, Second order Logic. Knowledge Representation: Conceptual Dependency, Frames, Semantic nets.

(Refer Chapter 3)

Unit IV: Natural Language Processing and ANN

(08 Hours)

Natural Language Processing: Introduction, Stages in natural language Processing, Application of NLP in Machine Translation, Information Retrieval and Big Data Information Retrieval. Learning: Supervised, Unsupervised and Reinforcement learning. Artificial Neural Networks (ANNs): Concept, Feed forward and Feedback ANNs, Error Back Propagation, Boltzmann Machine.

(Refer Chapter 4)

Unit V: Robotics

(08 Hours)

Robotics: Fundamentals, path Planning for Point Robot, Sensing and mapping for Point Robot, Mobile Robot Hardware, Non Visual Sensors like: Contact Sensors, Inertial Sensors, Infrared Sensors, Sonar, Radar, laser Rangefinders, Biological Sensing. Robot System Control: Horizontal and Vertical Decomposition, Hybrid Control Architectures, Middleware, High-Level Control, Human-Robot Interface. (Refer Chapter 5)

Unit VI: Robots in Practice

(08 Hours)

Robot Pose Maintenance and Localization: Simple Landmark Measurement, Servo Control, Recursive Filtering, Global Localization. Mapping: Sensorial Maps, Topological Maps, Geometric Maps, Exploration. Robots in Practice: Delivery Robots, Intelligent Vehicles, Mining Automation, Space Robotics, Autonomous Aircrafts, Agriculture, Forestry, Domestic Robots.

(Refer Chapter 6)



#### UNIT I

Chapter 1: Intelligence Searching Techniques	Chapter 1:	Intelligence	Searching	Techniques
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Syllabus: Artificial Intelligence: Introduction, Typical Applications. State Space Search : Depth Bounded DFS, Depth First Iterative Deepening.

Heuristic Search : Heuristic Functions, Best First Search, Hill Climbing, Variable Neighborhood Descent, Beam Search, Tabu Search.

Optimal Search :  $A^*$  algorithm, Iterative Deepening  $A^*$  , Recursive Best First Search, Pruning the CLOSED and OPEN Lists.

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Syllabus: Problem Decomposition: Goal Trees, Rule Based Systems, Rule Based Expert Systems.

Planning: STRIPS, Forward and Backward State Space Planning, Goal Stack Planning, Plan Space Planning, A Unified Framework For Planning.

Constraint Satisfaction: N-Queens, Constraint Propagation, Scene Labeling, Higher order and Directional Consistencies, Backtracking and Look ahead Strategies.

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Syllabus: Knowledge Based Reasoning: Agents, Facets of Knowledge. Logic and Inferences: Formal Logic, Propositional and First Order Logic, Resolution in Propositional and First Order Logic, Deductive Retrieval, Backward Chaining, Second order Logic Knowledge Representation: Conceptual Dependency, Frames, Semantic nets.

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Artificial Neural Networks (ANNs): Concept, Feed forward and Feedback ANNs, Error Back Propagation, Boltzmann Machine.

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Syllabus: Robotics: Fundamentals, path Planning for Point Robot, Sensing and mapping for Point Robot, Mobile Robot Hardware, Non Visual Sensors like: Contact Sensors, Inertial Sensors, Infrared Sensors, Sonar, Radar, laser Rangefinders, Biological Sensing. Robot System Control: Horizontal and Vertical Decomposition, Hybrid Control Architectures, Middleware, High-Level Control, Human-Robot Interface.

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### Chapter 6: Robots in Practice

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Syllabus: Robot Pose Maintenance and Localization: Simple Landmark Measurement, Servo Control, Recursive Filtering, Global Localization

Mapping : Sensorial Maps, Topological Maps, Geometric Maps, Exploration.

Robots in Practice : Delivery Robots, Intelligent Vehicles, Mining Automation, Space Robotics, Autonomous Aircrafts, Agriculture, Forestry, Domestic Robots.

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