

# KSHITIJ NIKHAL

## AI Researcher

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## EDUCATION

**Ph.D. Electrical Engineering**    **University of Nebraska-Lincoln**  
📅 2023 (Expected)    📍 Lincoln, NE, USA

- **Key Question:** "How to distill discriminative information across domains with minimal or no supervision, while mitigating the impact of poor generalization?" for biometric applications.
- **Minor:** Computer Science. **PhD Advisor:** Dr. Benjamin S. Riggan.

**M.S. Electrical Engineering**    **University of Nebraska-Lincoln**  
📅 2021    📍 Lincoln, NE, USA

- **GPA:** 4.0. **Research focus:** Computer Vision & Unsupervised Learning.
- **Master's Thesis:** Learning Discriminative and Efficient Attention for Person Re-Identification Using Agglomerative Clustering Frameworks.

**B.E. Computer Science**    **University of Pune**  
📅 2017    📍 Pune, MH, India

- **Grade:** First class with Distinction.
- **Bachelor's Thesis:** Evaluating Facial Expressions in Real Time.

## EXPERIENCE

**Research Assistant**    **University of Nebraska-Lincoln**  
📅 Jan 2020 – Present    📍 Lincoln, NE, USA

- Two Focus Areas:** 1. Accurate Recognition 2. Efficient Recognition.
1. **Focus:** Accurate biometric intelligence in challenging scenarios (500m range, atmospheric turbulence, aerial sensors, etc.)  
**Supported by:** IARPA BRIAR (Biometric Recognition and Identification at Altitude and Range) Program.
  2. **Focus:** Efficient, Dynamic and Deployable biometric models, ensuring reliability in extreme environments.  
**Supported by:** U.S. Army Research Lab/UMD's ArtIAMAS (AI and Autonomy for Multi-Agent Systems) Program.

**AI Resident**    **Google X, the Moonshot Factory**  
📅 May 2021 – Aug 2021, Aug 2022 – Dec 2022    📍 Mountain View, CA, USA

- Two AI Residencies (2021 & 2022):**
1. **Contributions:** Few-shot learning vision model to identify defects on the electrical grid using StreetView-like imagery.  
**Impact:** Substantial cost/time savings by eliminating manual work.
  2. **Contributions:** Photogrammetry on oblique aerial imagery to infer key electrical properties of power poles.  
**Impact:** Capability of a fine-detailed map of the electric grid.

**Software Engineer**    **TomTom Maps**  
📅 Jan 2017 – Dec 2019    📍 Pune, MH, India

1. **Contributions:** End-to-end ML Pipeline for map feature extraction (e.g., roads, building footprints, etc.,).  
**Impact:** 100x time reduction of manual cartography hours.
2. **Contributions:** Developing Graph & ML models with multi-modal data (e.g., GPS, multi-spectral imagery) to fix map inconsistencies.  
**Impact:** 2x more accurate, real-time map.

## SUMMARY

- 6+ years of research experience:
1. Concept Development at TomTom
  2. Research Assistantship at UNL.
  3. AI Research at Google X.

**PhD Focus Areas:** Unsupervised, Cross-Domain Recognition  
**Funded** by two "high-risk /high-payoff" programs:  

1. US Intelligence's IARPA BRIAR.
2. US Army/UMD's ArtIAMAS.

**Skills:** Unsupervised Learning, Computer Vision, Optimization, Domain Adaptation, Python, C++, PyTorch, TensorFlow, OpenCV.

## PATENTS

- P** Meta-learning for detecting object anomaly from images.
- P** Inferring Electrical Properties using Photogrammetry (Pending)

## RECENT PUBLICATIONS

- P** HashReID: Dynamic Network with Binary Codes for Efficient Person ReID  
Under Review
- P** Weakly Supervised Face and Whole Body Recognition in Turbulent Environments  
Under Review
- P** Cross-Spectral Attention for Unsupervised RGB-IR Face Verification and Person Re-identification  
Under Review at TIPS Journal 2023
- P** Mitigating Catastrophic Interference using Unsupervised Multi-Part Attention for RGB-IR Face Recognition  
CVPRW 2023
- P** Multi-Context Grouped Attention for Unsupervised Person Re-Identification  
TBIOM Journal 2023
- P** Unsupervised Attention Based Instance Discriminative Learning for Person Re-Identification  
WACV 2021
- P** MAGEC: Machine Assisted Geometry Extraction and Creation  
ICMV 2019