## Kruskal's Algorithm

```
Algorithm Kruskal(E, cost, n, t)
    //E is the set of edges in G. G has n vertices. cost[u, v] is the
     // cost of edge (u, v). t is the set of edges in the minimum-cost
       spanning tree. The final cost is returned.
5
         Construct a heap out of the edge costs using Heapify;
         for i := 1 to n do parent[i] := -1;
         // Each vertex is in a different set.
         i := 0; mincost := 0.0;
10
         while ((i < n-1) and (heap not empty)) do
11
12
             Delete a minimum cost edge (u, v) from the heap
13
             and reheapify using Adjust;
14
             j := Find(u); k := Find(v);
15
             if (j \neq k) then
16
17
18
                 i := i + 1;
                 t[i,1] := u; t[i,2] := v;
                 mincost := mincost + cost[u, v];
19
20
                  Union(j, k);
21
^{22}
         if (i \neq n-1) then write ("No spanning tree");
23
24
         else return mincost;
25 }
```