

MATH 446/OR 481

Project 6

November 29, 2022

Project Conclusion

In this project, we fit various models of varying complexity to the electrical power usage data over three 6-year periods - 1992 - 1997, 2002 - 2007, and 2012 - 2017.

The linear model is a poor fit to the data, and is evident visually and by the large root mean squared errors (RMSE) obtained. To model the oscillating data, we add sinusoids to our model. On evaluation, we observe that the model fit improves visually with addition of sinusoids, and the RMSE also decreases.

In summary, the following four models have been considered -

$$y = c_1 + c_2 t \quad (1)$$

$$y = c_1 + c_2 t + c_3 \cos 2\pi t + c_4 \sin 2\pi t \quad (2)$$

$$y = c_1 + c_2 t + c_3 \cos 2\pi t + c_4 \sin 2\pi t + c_5 \cos 4\pi t + c_6 \sin 4\pi t \quad (3)$$

$$y = c_1 + c_2 t + c_3 \cos 2\pi t + c_4 \sin 2\pi t + c_5 \cos 4\pi t + c_6 \sin 4\pi t + c_7 \cos 6\pi t + c_8 \sin 6\pi t \quad (4)$$

Model 3 and 4 fare similarly in terms of RMSE, and Model 3 can be considered to be the best balance of accuracy and computational expense.

The plots, model details, and result discussion follow for all datasets and models. The procedure for computing the coefficients is outlined in the Appendix.

Model 1 - $y = c_1 + c_2 t$

The command window output is shown below, which summarizes the model details - coefficients, and RMSE.

```

Command Window

Model Equation - y = c_1 + c_2 * t

Model for data from 1992 - 1997
coeffs    values
-----
"c_1"     75.132
"c_2"     1.7502

RMS Error = 6.79707084

Model for data from 2002 - 2007
coeffs    values
-----
"c_1"     93.899
"c_2"     1.2929

RMS Error = 7.99100986

Model for data from 2012 - 2017
coeffs    values
-----
"c_1"     101.89
"c_2"     0.13604

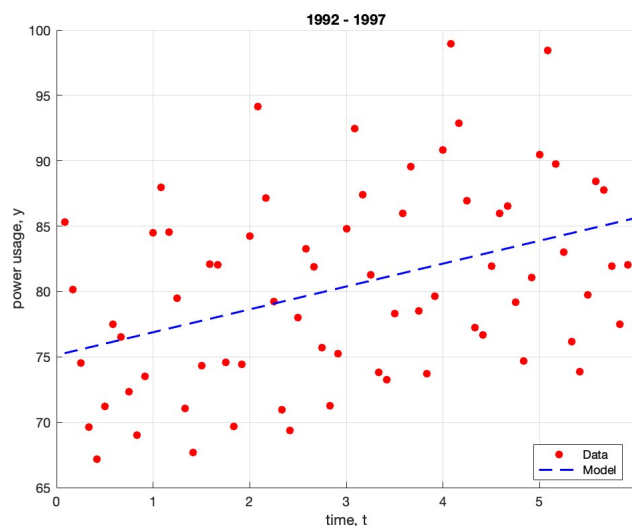
RMS Error = 9.17746541

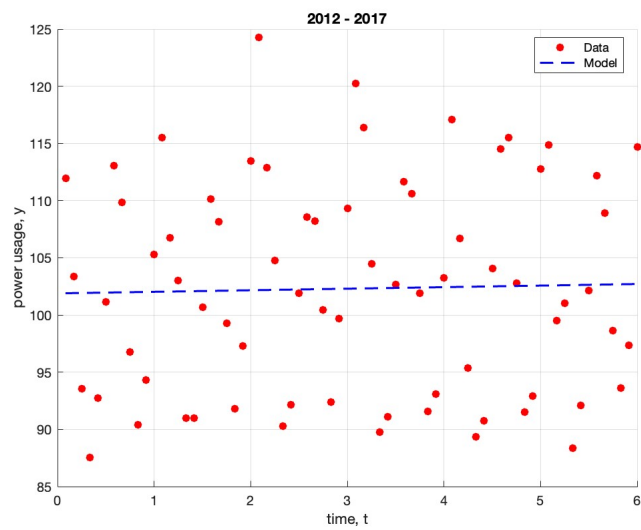
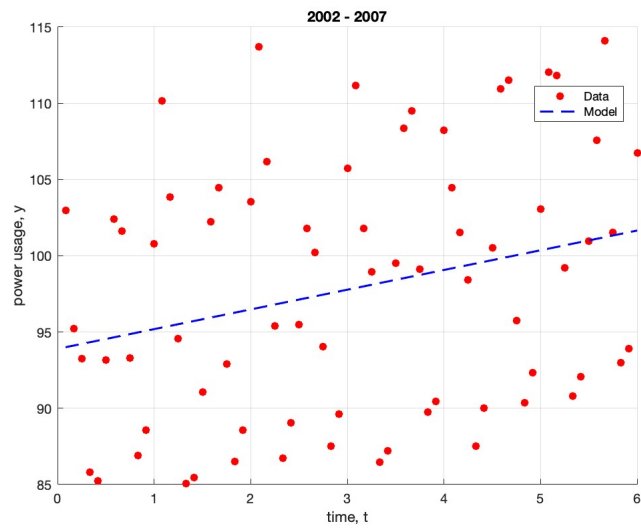
fx >>

```

The coefficient c_2 represents the rate of increase of power consumption over time. The period with fastest rising energy consumption is hence 1992 - 1997, because of highest value of c_2 .

The raw data is plotted with the linear model for all three datasets.





Model 2 - $y = c_1 + c_2 t + c_3 \cos 2\pi t + c_4 \sin 2\pi t$

The command window output is shown below, which summarizes the model details - coefficients, and RMSE.

```

Command Window
Model Equation - y = c_1 + c_2 * t + c_3 * cos(2 * pi * t) + c_4 * sin(2 * pi * t)

Model for data from 1992 - 1997
coeffs      values
-----
"c_1"       75.004
"c_2"       1.7924
"c_3"       4.0262
"c_4"       1.8917

RMS Error = 6.02586502

Model for data from 2002 - 2007
coeffs      values
-----
"c_1"       94.015
"c_2"       1.2548
"c_3"       1.9408
"c_4"      -0.21598

RMS Error = 7.87108646

Model for data from 2012 - 2017
coeffs      values
-----
"c_1"      102.09
"c_2"      0.071678
"c_3"      2.6804
"c_4"     -0.52323

RMS Error = 8.97269472

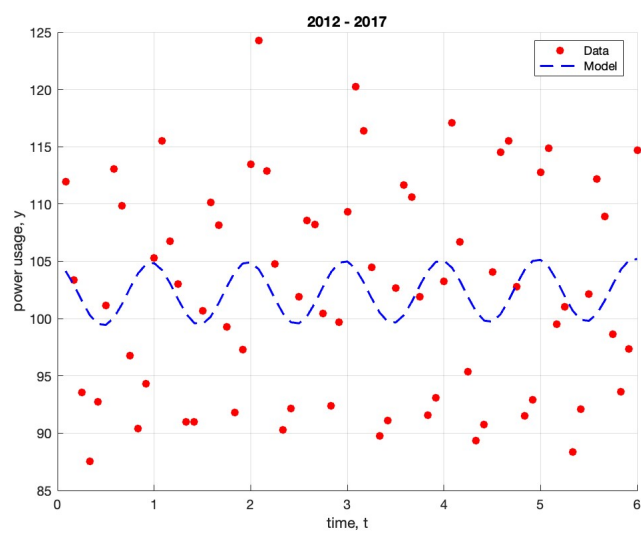
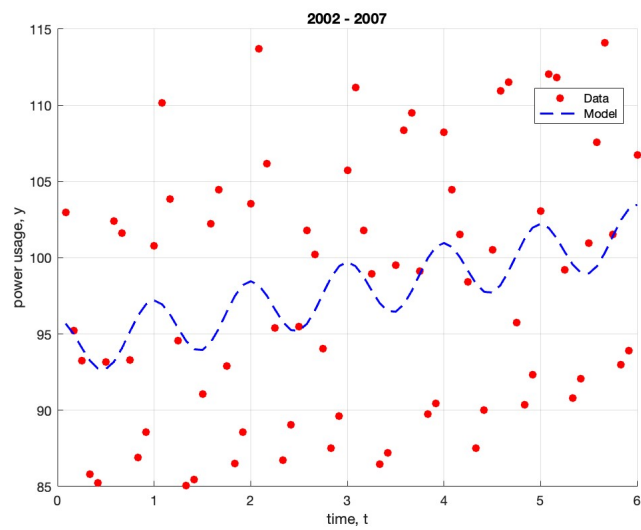
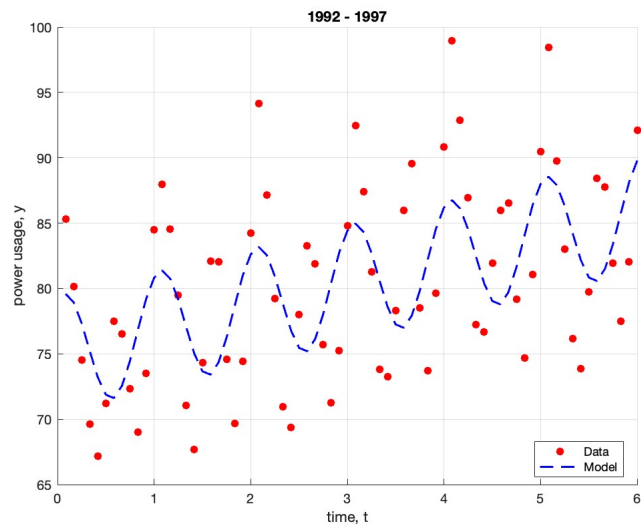
fx >>

```

We see slight changes in the coefficient c_2 and RMSE, compared to Model 1.

The RMSE has decreased, but not very significantly. The model type has changed, and we can no longer strictly consider c_2 as the rate of increase in load consumption. c_2 would now be a less accurate estimate of the rate of increase in load consumption as compared to Model 1.

The raw data is plotted with the linear model for all three datasets.



Model 3 - $y = c_1 + c_2 t + c_3 \cos 2\pi t + c_4 \sin 2\pi t + c_5 \cos 4\pi t + c_6 \sin 4\pi t$

The command window output is shown below, which summarizes the model details - coefficients, and RMSE.

```
Command Window
Model Equation - y = c_1 + c_2 * t + c_3 * cos(2 * pi * t) + c_4 * sin(2 * pi * t)
                  + c_5 * cos(4 * pi * t) + c_6 * sin(4 * pi * t)

Model for data from 1992 - 1997
coeffs      values
-----
"c_1"       74.49
"c_2"       1.9613
"c_3"       4.0121
"c_4"       1.9442
"c_5"       1.7945
"c_6"       7.9365

RMS Error = 1.81406481

Model for data from 2002 - 2007
coeffs      values
-----
"c_1"       93.328
"c_2"       1.4806
"c_3"       1.9219
"c_4"      -0.14574
"c_5"       1.9198
"c_6"      10.333

RMS Error = 2.62254835

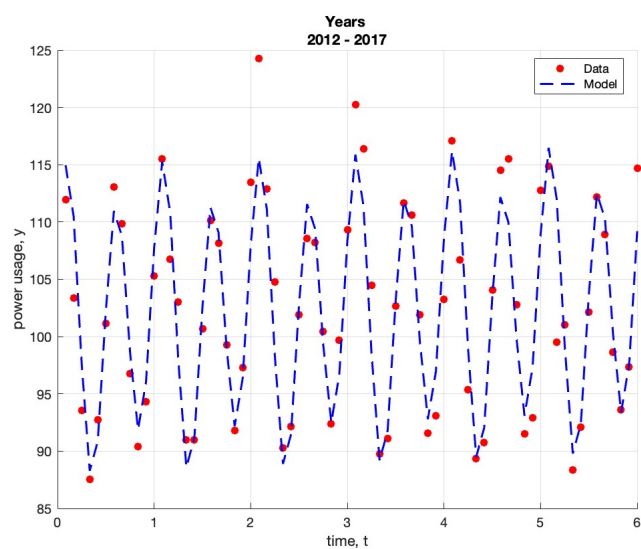
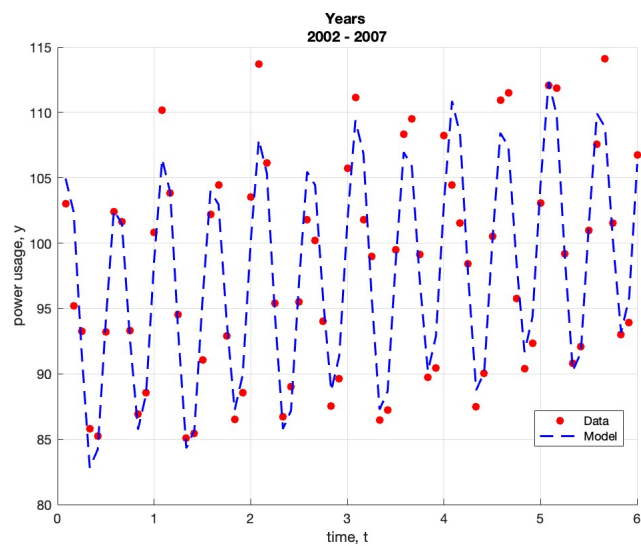
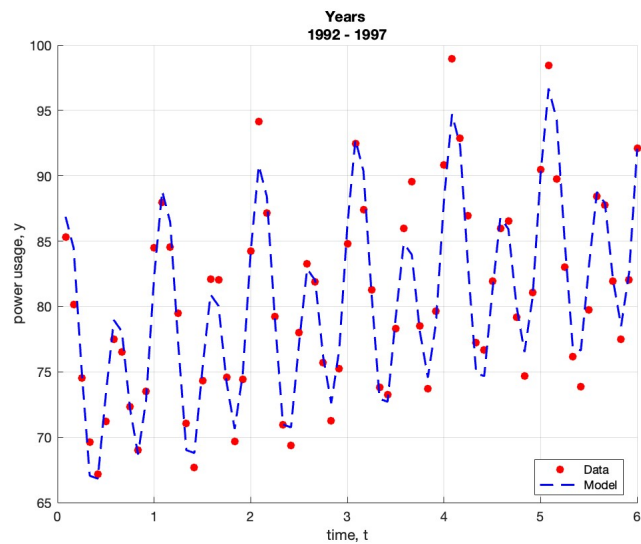
Model for data from 2012 - 2017
coeffs      values
-----
"c_1"      101.39
"c_2"      0.30157
"c_3"       2.6612
"c_4"     -0.45173
"c_5"       3.3484
"c_6"      11.323

RMS Error = 3.31025953

fx >>
```

We see that the RMSE has dropped significantly when compared to Model 1. c_2 has remained similar to Model 2 for the first 2 datasets, but changes to 4 times the magnitude for the third dataset, when compared to Model 2.

The raw data is plotted with the linear model for all three datasets.



Model 4 - $y = c_1 + c_2 t + c_3 \cos 2\pi t + c_4 \sin 2\pi t + c_5 \cos 4\pi t + c_6 \sin 4\pi t + c_7 \cos 6\pi t + c_8 \sin 6\pi t$

The command window output is shown below, which summarizes the model details - coefficients, and RMSE.

```

Command Window
Model Equation - y = c_1 + c_2 * t + c_3 * cos(2 * pi * t) + c_4 * sin(2 * pi * t)
                  + c_5 * cos(4 * pi * t) + c_6 * sin(4 * pi * t)
                  + c_7 * cos(6 * pi * t) + c_8 * sin(6 * pi * t)

Model for data from 1992 - 1997
coeffs      values
-----
"c_1"       74.542
"c_2"       1.9442
"c_3"       4.0136
"c_4"       1.9389
"c_5"       1.796
"c_6"       7.934
"c_7"       1.1952
"c_8"      -0.0081727

RMS Error = 1.60543530

Model for data from 2002 - 2007
coeffs      values
-----
"c_1"       93.381
"c_2"       1.4632
"c_3"       1.9234
"c_4"      -0.15117
"c_5"       1.9213
"c_6"       10.33
"c_7"       1.4537
"c_8"       0.22615

RMS Error = 2.40758319

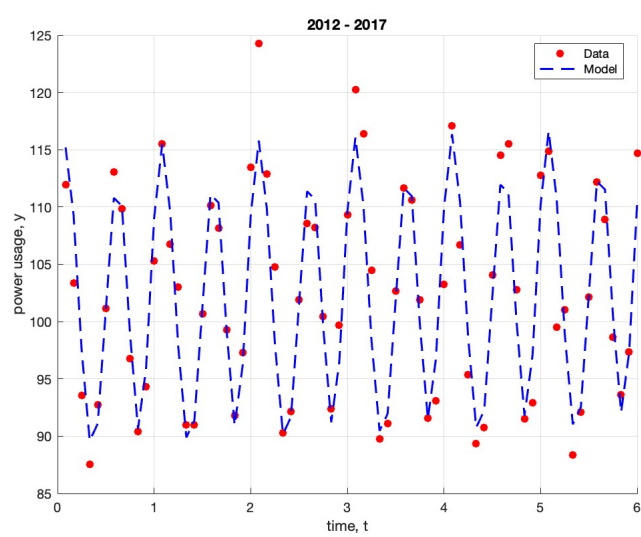
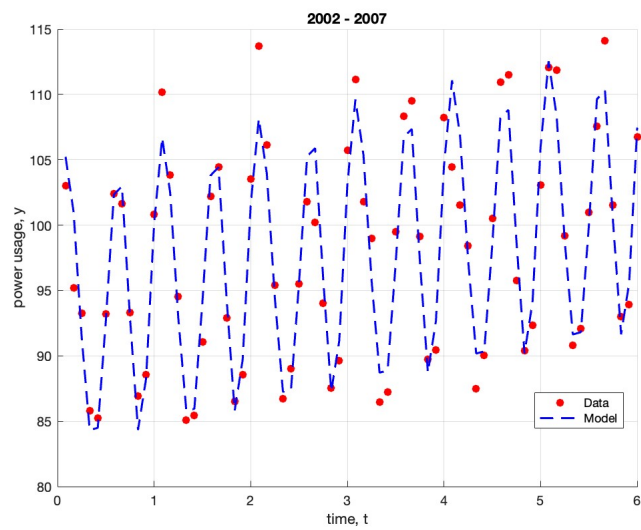
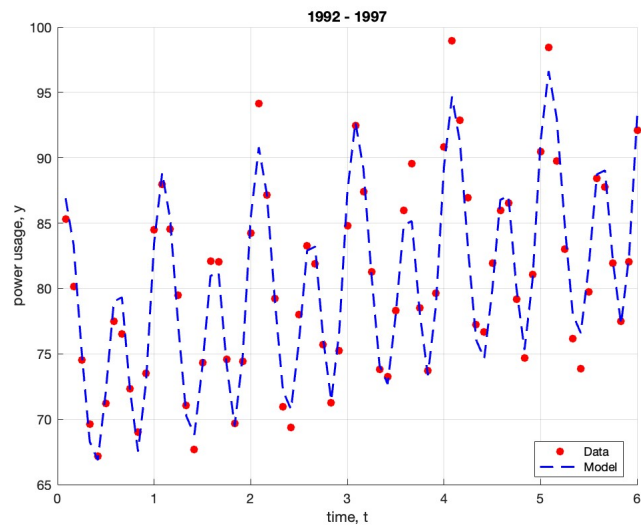
Model for data from 2012 - 2017
coeffs      values
-----
"c_1"      101.43
"c_2"      0.28628
"c_3"       2.6625
"c_4"     -0.45648
"c_5"       3.3497
"c_6"      11.32
"c_7"       1.2825
"c_8"       0.20585

RMS Error = 3.18039942
fx >>

```

We see that the RMSE is similar to that obtained with Model 4, and we might be overfitting the data if we include more sinusoids. c_2 is similar to what was obtained in Model 3.

The raw data is plotted with the linear model for all three datasets.



Appendix - Fitting a model to given data

Say we want to fit Model 2 - $y = c_1 + c_2 t + c_3 \cos 2\pi t + c_4 \sin 2\pi t$ to a given dataset (t_i, w_i) where $i = 1, 2, \dots, N$ (the procedure is identical for other models). Then, we want the coefficients c_1, c_2, c_3, c_4 such that the root mean squared error (RMSE) defined as

$$RMSE = E = \sqrt{\frac{1}{N} \sum_{i=1}^N (y_i - w_i)^2}$$

is a minimum. Here, $y_i = y(t_i)$.

Using differential calculus, the RMSE is minimum when the partial derivatives of the error w.r.t each coefficient are zero. Thus, we have the condition

$$\frac{\partial E}{\partial c_j} = 0$$

where $j = 1, 2, \dots, 4$.

This can be simplified as

$$\sum_{i=1}^N (y_i - w_i) \frac{\partial y_i}{\partial c_j} = 0$$

for $j = 1, 2, \dots, 4$.

Further simplifying,

$$\sum_{i=1}^N y_i \frac{\partial y_i}{\partial c_j} = \sum_{i=1}^N w_i \frac{\partial y_i}{\partial c_j}$$

for $j = 1, 2, \dots, 4$.

Now, $y_i = y(t_i) = c_1 + c_2 t_i + c_3 \cos 2\pi t_i + c_4 \sin 2\pi t_i$ and

$$\begin{aligned} \frac{\partial y_i}{\partial c_1} &= 1 \\ \frac{\partial y_i}{\partial c_2} &= t_i \\ \frac{\partial y_i}{\partial c_3} &= \cos 2\pi t_i \\ \frac{\partial y_i}{\partial c_4} &= \sin 2\pi t_i \end{aligned}$$

Combining, we now have a set of four equations in four variables c_1, c_2, \dots, c_4 to be solved for the

values of the coefficients, which can be accomplished by matrix methods.

$$\begin{bmatrix} \sum 1 & \sum t_i & \sum \cos 2\pi t_i & \sum \sin 2\pi t_i \\ \sum t_i & \sum t_i^2 & \sum t_i \cos 2\pi t_i & \sum t_i \sin 2\pi t_i \\ \sum \cos 2\pi t_i & \sum t_i \cos 2\pi t_i & \sum \cos 2\pi t_i \cos 2\pi t_i & \sum \cos 2\pi t_i \sin 2\pi t_i \\ \sum \sin 2\pi t_i & \sum t_i \sin 2\pi t_i & \sum \sin 2\pi t_i \cos 2\pi t_i & \sum \sin 2\pi t_i \sin 2\pi t_i \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \end{bmatrix} = \begin{bmatrix} \sum w_i \\ \sum t_i w_i \\ \sum w_i \cos 2\pi t_i \\ \sum w_i \sin 2\pi t_i \end{bmatrix}$$

We have the matrix equation $Ac = b$ and the solution in MATLAB is $c = A \backslash b$.

MATLAB Code - p6_1.m

```
clc; clear; close all

fprintf('Model Equation - y = c_1 + c_2 * t\n')
fprintf('\n')

% time vector
t = ((1:72)/12)';

% load data
load e02.txt
load e12.txt
load e92.txt

y = [e92 e02 e12];

years_names = ["1992 - 1997", "2002 - 2007", "2012 - 2017"];
coeffs_names = ["c_1"; "c_2"];

% compute and evaluate model
for i = 1:size(y, 2)

    y_data = y(:, i);
    A = zeros(2, 2);
    b = zeros(2, 1);

    % first equation
    A(1, 1) = length(y_data);
    A(1, 2) = sum(t);
    b(1) = sum(y_data);

    % second equation
    A(2, 1) = A(1, 2);
    A(2, 2) = sum(t.*t);
    b(2) = sum(t.*y_data);

    % solve for coefficients
    coeffs = A\b;

    % print model info and slope
```

```
fprintf('Model for data from %s\n', years_names(i))
tbl = table;
tbl.coeffs = coeffs_names;
tbl.values = coeffs;
disp(tbl)

% predicted values
y_predict = coeffs(1) + coeffs(2)*t;

% root mean squared error
rmse = sqrt(mean((y_data - y_predict).^2));
fprintf('    RMS Error = %.8f\n', rmse)
fprintf('\n')

% plot data with model
figure()
scatter(t, y_data, 'ro', 'filled')
hold on
plot(t, y_predict, 'b--', 'LineWidth', 1.5)
hold off
xlabel('time, t')
ylabel('power usage, y')
titlestring = years_names(i);
title(titlestring)
legend('Data', 'Model', 'Location', 'best')
grid

end
```

MATLAB Code - p6_2.m

```
clc; clear; close all

fprintf(['Model Equation - y = c_1 + c_2 * t + c_3 * cos(2 * pi * t) + ' ...
'c_4 * sin(2 * pi * t)\n'])
fprintf('\n')

% time vector
t = ((1:72)/12)';

% load data
load e02.txt
load e12.txt
load e92.txt

y = [e92 e02 e12];

years_names = ["1992 - 1997", "2002 - 2007", "2012 - 2017"];
coeffs_names = ["c_1"; "c_2"; "c_3"; "c_4"];

% compute and evaluate model
for i = 1:size(y, 2)

    y_data = y(:, i);
    A = zeros(4, 4);
    b = zeros(4, 1);

    % first equation
    A(1, 1) = length(y_data);
    A(1, 2) = sum(t);
    A(1, 3) = sum(cos(2*pi*t));
    A(1, 4) = sum(sin(2*pi*t));
    b(1) = sum(y_data);

    % second equation
    A(2, 1) = A(1, 2);
    A(2, 2) = sum(t.*t);
    A(2, 3) = sum(t.*cos(2*pi*t));
    A(2, 4) = sum(t.*sin(2*pi*t));
    b(2) = sum(t.*y_data);
```

```
% third equation
A(3, 1) = A(1, 3);
A(3, 2) = A(2, 3);
A(3, 3) = sum(cos(2*pi*t).*cos(2*pi*t));
A(3, 4) = sum(cos(2*pi*t).*sin(2*pi*t));
b(3) = sum(cos(2*pi*t).*y_data);

% fourth equation
A(4, 1) = A(1, 4);
A(4, 2) = A(2, 4);
A(4, 3) = A(3, 4);
A(4, 4) = sum(sin(2*pi*t).*sin(2*pi*t));
b(4) = sum(sin(2*pi*t).*y_data);

% solve for coefficients
coeffs = A\b;

% print model info and slope
fprintf('Model for data from %s\n', years_names(i))
tbl = table;
tbl.coeffs = coeffs_names;
tbl.values = coeffs;
disp(tbl)

% predicted values
y_predict = coeffs(1) + coeffs(2)*t + coeffs(3)*cos(2*pi*t) + ...
coeffs(4)*sin(2*pi*t);

% root mean squared error
rmse = sqrt(mean((y_data - y_predict).^2));
fprintf('    RMS Error = %.8f\n', rmse)
fprintf('\n')

% plot data with model
figure()
scatter(t, y_data, 'ro', 'filled')
hold on
plot(t, y_predict, 'b--', 'LineWidth', 1.5)
hold off
xlabel('time, t')
```



```
ylabel('power usage, y')
titlestring = years_names(i);
title(titlestring)
legend('Data', 'Model', 'Location', 'best')
grid

end
```

MATLAB Code - p6_3.m

```

clc; clear; close all

fprintf(['Model Equation - y = c_1 + c_2 * t + c_3 * cos(2 * pi * t) + ' ...
'c_4 * sin(2 * pi * t)\n
'c_5 * cos(4 * pi * t) + c_6 * sin(4 * pi * t)\n'])
fprintf('\n')

% time vector
t = ((1:72)/12)';

% load data
load e92.txt
load e02.txt
load e12.txt

y = [e92 e02 e12];

years_names = ["1992 - 1997", "2002 - 2007", "2012 - 2017"];
coeffs_names = ["c_1"; "c_2"; "c_3"; "c_4"; "c_5"; "c_6"];

% compute and evaluate model
for i = 1:size(y, 2)

    y_data = y(:, i);
    A = zeros(6, 6);
    b = zeros(6, 1);

    % first equation
    A(1, 1) = length(y_data);
    A(1, 2) = sum(t);
    A(1, 3) = sum(cos(2*pi*t));
    A(1, 4) = sum(sin(2*pi*t));
    A(1, 5) = sum(cos(4*pi*t));
    A(1, 6) = sum(sin(4*pi*t));
    b(1) = sum(y_data);

    % second equation
    A(2, 1) = A(1, 2);
    A(2, 2) = sum(t.*t);

```

```
A(2, 3) = sum(t.*cos(2*pi*t));
A(2, 4) = sum(t.*sin(2*pi*t));
A(2, 5) = sum(t.*cos(4*pi*t));
A(2, 6) = sum(t.*sin(4*pi*t));
b(2) = sum(t.*y_data);

% third equation
A(3, 1) = A(1, 3);
A(3, 2) = A(2, 3);
A(3, 3) = sum(cos(2*pi*t).*cos(2*pi*t));
A(3, 4) = sum(cos(2*pi*t).*sin(2*pi*t));
A(3, 5) = sum(cos(2*pi*t).*cos(4*pi*t));
A(3, 6) = sum(cos(2*pi*t).*sin(4*pi*t));
b(3) = sum(cos(2*pi*t).*y_data);

% fourth equation
A(4, 1) = A(1, 4);
A(4, 2) = A(2, 4);
A(4, 3) = A(3, 4);
A(4, 4) = sum(sin(2*pi*t).*sin(2*pi*t));
A(4, 5) = sum(sin(2*pi*t).*cos(4*pi*t));
A(4, 6) = sum(sin(2*pi*t).*sin(4*pi*t));
b(4) = sum(sin(2*pi*t).*y_data);

% fifth equation
A(5, 1) = A(1, 5);
A(5, 2) = A(2, 5);
A(5, 3) = A(3, 5);
A(5, 4) = A(4, 5);
A(5, 5) = sum(cos(4*pi*t).*cos(4*pi*t));
A(5, 6) = sum(cos(4*pi*t).*sin(4*pi*t));
b(5) = sum(cos(4*pi*t).*y_data);

% sixth equation
A(6, 1) = A(1, 6);
A(6, 2) = A(2, 6);
A(6, 3) = A(3, 6);
A(6, 4) = A(4, 6);
A(6, 5) = A(5, 6);
A(6, 6) = sum(sin(4*pi*t).*sin(4*pi*t));
b(6) = sum(sin(4*pi*t).*y_data);
```

```
% solve for coefficients
coeffs = A\b;

% print model info and slope
fprintf('Model for data from %s\n', years_names(i))
tbl = table;
tbl.coeffs = coeffs_names;
tbl.values = coeffs;
disp(tbl)

% predicted values
y_predict = coeffs(1) + coeffs(2)*t + coeffs(3)*cos(2*pi*t) + ...
coeffs(4)*sin(2*pi*t) + coeffs(5)*cos(4*pi*t) + coeffs(6)*sin(4*pi*t);

% root mean squared error
rmse = sqrt(mean((y_data - y_predict).^2));
fprintf('    RMS Error = %.8f\n', rmse)
fprintf('\n')

% plot data with model
figure()
scatter(t, y_data, 'ro', 'filled')
hold on
plot(t, y_predict, 'b--', 'LineWidth', 1.5)
hold off
xlabel('time, t')
ylabel('power usage, y')
titlestring = ['Years ', years_names(i)];
title(titlestring)
legend('Data', 'Model', 'Location', 'best')
grid

end
```

MATLAB Code - p6_4.m

```

clc; clear; close all

fprintf(['Model Equation - y = c_1 + c_2 * t + c_3 * cos(2 * pi * t) + ' ...
'c_4 * sin(2 * pi * t)\n
'c_5 * cos(4 * pi * t) + c_6 * sin(4 * pi * t)\n' ...
,
, ...
'+ c_7 * cos(6 * pi * t) + c_8 * sin(6 * pi * t)\n'])
fprintf('\n')

% time vector
t = ((1:72)/12)';

% load data
load e92.txt
load e02.txt
load e12.txt

y = [e92 e02 e12];

years_names = ["1992 - 1997", "2002 - 2007", "2012 - 2017"];
coeffs_names = ["c_1"; "c_2"; "c_3"; "c_4"; "c_5"; "c_6"; "c_7"; "c_8"];

% compute and evaluate model
for i = 1:size(y, 2)

y_data = y(:, i);
A = zeros(8, 8);
b = zeros(8, 1);

% first equation
A(1, 1) = length(y_data);
A(1, 2) = sum(t);
A(1, 3) = sum(cos(2*pi*t));
A(1, 4) = sum(sin(2*pi*t));
A(1, 5) = sum(cos(4*pi*t));
A(1, 6) = sum(sin(4*pi*t));
A(1, 7) = sum(cos(6*pi*t));
A(1, 8) = sum(sin(6*pi*t));
b(1) = sum(y_data);

```

```
% second equation
A(2, 1) = A(1, 2);
A(2, 2) = sum(t.*t);
A(2, 3) = sum(t.*cos(2*pi*t));
A(2, 4) = sum(t.*sin(2*pi*t));
A(2, 5) = sum(t.*cos(4*pi*t));
A(2, 6) = sum(t.*sin(4*pi*t));
A(2, 7) = sum(t.*cos(6*pi*t));
A(2, 8) = sum(t.*sin(6*pi*t));
b(2) = sum(t.*y_data);

% third equation
A(3, 1) = A(1, 3);
A(3, 2) = A(2, 3);
A(3, 3) = sum(cos(2*pi*t).*cos(2*pi*t));
A(3, 4) = sum(cos(2*pi*t).*sin(2*pi*t));
A(3, 5) = sum(cos(2*pi*t).*cos(4*pi*t));
A(3, 6) = sum(cos(2*pi*t).*sin(4*pi*t));
A(3, 7) = sum(cos(2*pi*t).*cos(6*pi*t));
A(3, 8) = sum(cos(2*pi*t).*sin(6*pi*t));
b(3) = sum(cos(2*pi*t).*y_data);

% fourth equation
A(4, 1) = A(1, 4);
A(4, 2) = A(2, 4);
A(4, 3) = A(3, 4);
A(4, 4) = sum(sin(2*pi*t).*sin(2*pi*t));
A(4, 5) = sum(sin(2*pi*t).*cos(4*pi*t));
A(4, 6) = sum(sin(2*pi*t).*sin(4*pi*t));
A(4, 7) = sum(sin(2*pi*t).*cos(6*pi*t));
A(4, 8) = sum(sin(2*pi*t).*sin(6*pi*t));
b(4) = sum(sin(2*pi*t).*y_data);

% fifth equation
A(5, 1) = A(1, 5);
A(5, 2) = A(2, 5);
A(5, 3) = A(3, 5);
A(5, 4) = A(4, 5);
A(5, 5) = sum(cos(4*pi*t).*cos(4*pi*t));
A(5, 6) = sum(cos(4*pi*t).*sin(4*pi*t));
```

```
A(5, 7) = sum(cos(4*pi*t).*cos(6*pi*t));
A(5, 7) = sum(cos(4*pi*t).*sin(6*pi*t));
b(5) = sum(cos(4*pi*t).*y_data);
```

```
% sixth equation
```

```
A(6, 1) = A(1, 6);
A(6, 2) = A(2, 6);
A(6, 3) = A(3, 6);
A(6, 4) = A(4, 6);
A(6, 5) = A(5, 6);
A(6, 6) = sum(sin(4*pi*t).*sin(4*pi*t));
A(6, 7) = sum(sin(4*pi*t).*cos(6*pi*t));
A(6, 8) = sum(sin(4*pi*t).*sin(6*pi*t));
b(6) = sum(sin(4*pi*t).*y_data);
```

```
% seventh equation
```

```
A(7, 1) = A(1, 7);
A(7, 2) = A(2, 7);
A(7, 3) = A(3, 7);
A(7, 4) = A(4, 7);
A(7, 5) = A(5, 7);
A(7, 6) = A(6, 7);
A(7, 7) = sum(cos(6*pi*t).*cos(6*pi*t));
A(7, 8) = sum(cos(6*pi*t).*sin(6*pi*t));
b(7) = sum(cos(6*pi*t).*y_data);
```

```
% eighth equation
```

```
A(8, 1) = A(1, 8);
A(8, 2) = A(2, 8);
A(8, 3) = A(3, 8);
A(8, 4) = A(4, 8);
A(8, 5) = A(5, 8);
A(8, 6) = A(6, 8);
A(8, 7) = A(7, 8);
A(8, 8) = sum(sin(6*pi*t).*sin(6*pi*t));
b(8) = sum(sin(6*pi*t).*y_data);
```

```
% solve for coefficients
```

```
coeffs = A\b;
```

```
% print model info and slope
```

```
fprintf('Model for data from %s\n', years_names(i))
tbl = table;
tbl.coeffs = coeffs_names;
tbl.values = coeffs;
disp(tbl)

% predicted values
y_predict = coeffs(1) + coeffs(2)*t + coeffs(3)*cos(2*pi*t) + ...
coeffs(4)*sin(2*pi*t) + coeffs(5)*cos(4*pi*t) + ...
coeffs(6)*sin(4*pi*t) + coeffs(7)*cos(6*pi*t) + ...
coeffs(8)*sin(6*pi*t);

% root mean squared error
rmse = sqrt(mean((y_data - y_predict).^2));
fprintf('    RMS Error = %.8f\n', rmse)
fprintf('\n')

% plot data with model
figure()
scatter(t, y_data, 'ro', 'filled')
hold on
plot(t, y_predict, 'b--', 'LineWidth', 1.5)
hold off
xlabel('time, t')
ylabel('power usage, y')
titlestring = years_names(i);
title(titlestring)
legend('Data', 'Model', 'Location', 'best')
grid

end
```