Improving Performance of a Path-Based Equivalence Checker using Counter-Examples

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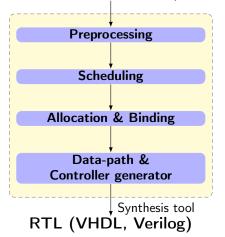
March 31, 2019

Outline

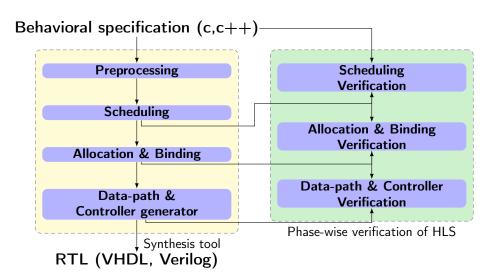
- High-level Synthesis (HLS)
- Path-based Equivalence Checker (PBEC)
- Overall Approach
- Experimental Results
- Conclusion & Future Work

High-level Synthesis (HLS)

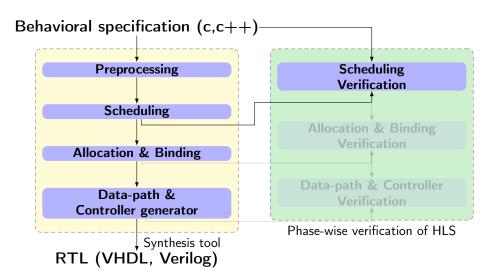
Behavioral specification (c,c++)



High-level Synthesis (HLS)



High-level Synthesis (HLS)



Verification of HLS

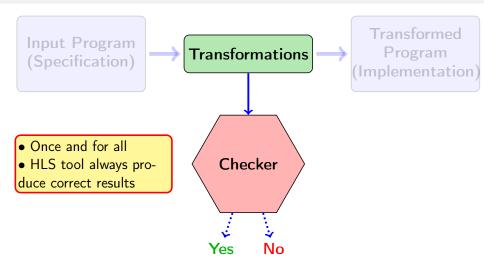


Verification of HLS

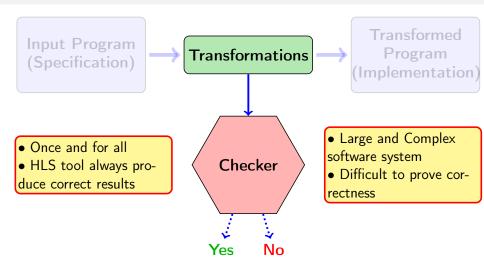


Is the Specification "functionally equivalent" to Implementation?

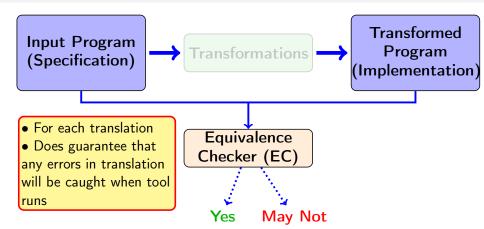
Verification of HLS:Correct by Construction



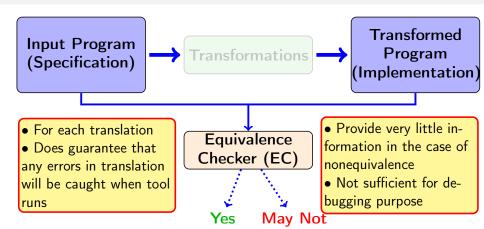
Verification of HLS:Correct by Construction



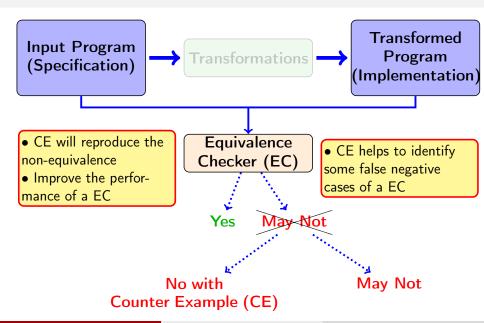
Verification of HLS: Translation Validation



Verification of HLS: Translation Validation



Motivation



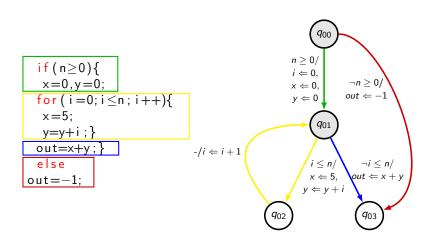
Path-based Equivalence Checkers (PBEC)-Related Works

- C. Karfa et al, "An equivalence-checking method for scheduling verification in high-level synthesis," IEEE TCAD, (2008).
- Lee et al, "Equivalence checking of scheduling with speculative code transformations in high-level synthesis", ASP-DAC (2011).
- K. Banerjee et al, "Verification of code motion techniques using value propagation", IEEE TCAD, (2014). [VP Method]
- J. Hu et al "Equivalence checking between SLM and RTL using machine learning techniques," ISQED (2016).
- R. Chouksey et al, "Translation validation of code motion transformations involving loops", IEEE TCAD, (2018). [EVP Method]

PBEC

- Behaviors are represented by Finite State Machine with Data (FSMD).
- Decompose each FSMD using cutpoints.
- Path: Finite sequence of states from a cutpoint to another cutpoint.
- Equivalence of FSMDs is established by showing path level equivalence between two FSMDs.

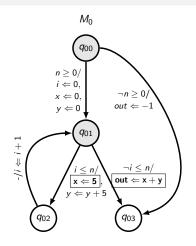
Representing a program using FSMD

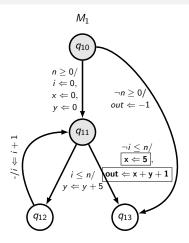


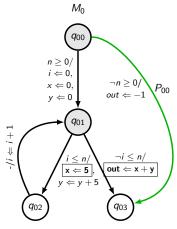
Overall Approach

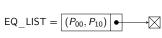
In the case of nonequivalence reported by PBEC

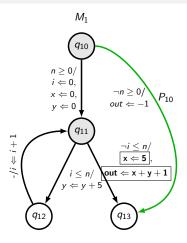
- Counter Trace (cTrace) generation.
- 2 Modeling the cTrace to generate counter example using CBMC.
- Incorporate the results with PBEC.



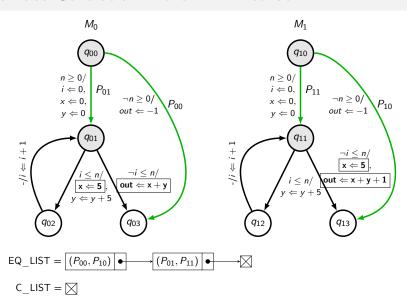


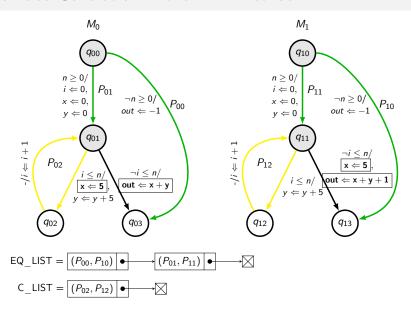


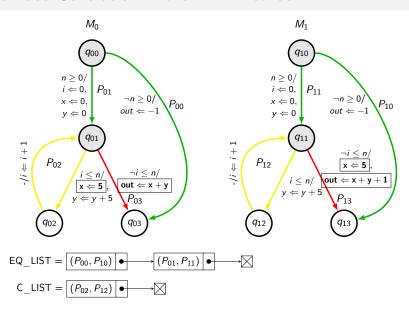




C LIST = ⊠







In case of nonequivalence

cTrace of
$$M_0 = \langle$$

In case of nonequivalence

ullet Can not find equivalent path (say lpha) ____

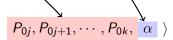


cTrace of $M_0 = \langle$

In case of nonequivalence

ullet Can not find equivalent path (say lpha)

cTrace of $M_0 = \langle$



In case of nonequivalence

- ullet Can not find equivalent path (say lpha)
- C LIST _
- Paths from EQ_LIST

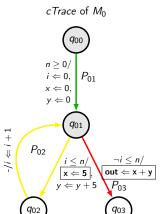
cTrace of
$$M_0 = \langle P_{00}, P_{01}, \cdots, P_{0i}, P_{0j}, P_{0j+1}, \cdots, P_{0k}, \alpha \rangle$$

In case of nonequivalence

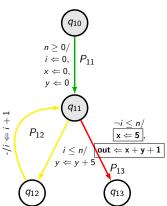
- Can not find equivalent path (say α)
- C_LIST __
- Paths from EQ_LIST
- cTrace of M_0 and M_1

cTrace of
$$M_0 = \langle P_{00}, P_{01}, \cdots, P_{0i}, P_{0j}, P_{0j+1}, \cdots, P_{0k}, \alpha \rangle$$

cTrace of
$$M_1 = \langle P_{10}, P_{11}, \cdots, P_{1i}, P_{1j}, P_{1j+1}, \cdots, P_{1k}, \beta \rangle$$



cTrace of M_1



```
#include <assert.h>
                                              //cTrace for M1
    void main()
                                          23
                                                 if(n>=0)
                                          24
4
      int i_s,x_s,y_s,n,out_s;
                                          25
5
      int i_t,x_t,v_t,out_t;
                                          26
6
      __CPROVER_assume(n>=0);
                                          27
      assert(!(n>=0));
                                          28
                                                   while (i_t <= n)
                                          29
                                          30
8
                                                     v_t = v_t + 5;
    // cTrace for MO
                                          31
                                                     i_t=i_t+1;
9
      if(n >= 0)
                                          32
10
                                          33
                                                   x t=5:
11
        i_s=0; x_s=0; y_s=0;
                                          34
12
        __CPROVER_assume(i_s<=n)
                                          35
13
        assert(!(i_s<=n));
14
        while(i s<=n)
15
                                              //Live variables
                                          36
16
           x s=5:
17
                                          37
           v_s = v_s + 5;
                                          38
18
           i_s=i_s+1;
```

```
i t=0:x t=0:v t=0:
        CPROVER assume(i t<=n):
        assert(!(i_t<=n));
        out t=x t+v t+1:
     assert(x s = x t):
      assert(y_s = y_t);
39
   //Output variable
40
    assert(out_s = out_t);
41
```

out_s= x_s+y_s ;

19

20

21

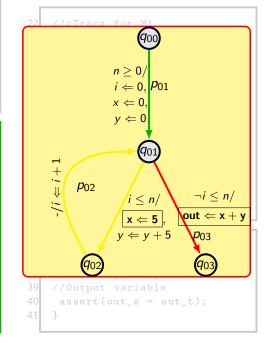
```
#include <assert.h>
   void main()
4
     int i_s,x_s,y_s,n,out_s;
5
     int i_t,x_t,y_t,out_t;
6
     __CPROVER_assume(n>=0);
     assert(!(n>=0));
           • s – Variables appearing in the cTrace of M_0.
           • t – Variables appearing in the cTrace of M_1.

    n – common Variable.

              CPROVER assume - allow only those computations
              that satisfy a given condition.
                                            assert(x s = x t):
```

```
1  #include <assert.h>
2  void main()
3  {
    int i_s,x_s,y_s,n,out_s;
    int i_t,x_t,y_t,out_t;
    __CPROVER_assume(n>=0);
7  assert(!(n>=0));
```

```
8
    // cTrace for MO
9
      if(n>=0)
10
11
        i_s=0; x_s=0; y_s=0;
12
        __CPROVER_assume(i_s<=n)
13
        assert(!(i_s<=n));
14
        while(i_s<=n)
15
16
          x_s=5;
17
           y_s = y_s + 5;
18
           i_s=i_s+1;
19
20
        out_s=x_s+y_s;
21
```



```
n \geq 0/
       i \Leftarrow 0, p_{11}
      x \Leftarrow 0,
      v \Leftarrow 0
                                \neg i \leq n/
                                x ⇐ 5
p_{12}
           i < n/ | out \Leftarrow x + y + 1
        y \Leftarrow y + 5
                               p_{13}
```

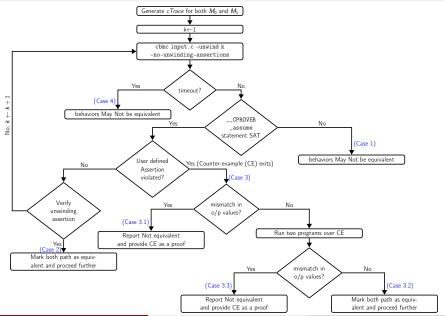
```
22
    //cTrace for M1
23
      if(n>=0)
24
         i_t=0; x_t=0; y_t=0;
26
         CPROVER assume(i t<=n):
         assert(!(i_t <= n));
         while(i_t <= n)</pre>
           v_t = v_t + 5;
           i_t=i_t+1;
33
         x_t=5;
         out_t=x_t+y_t+1;
35
```

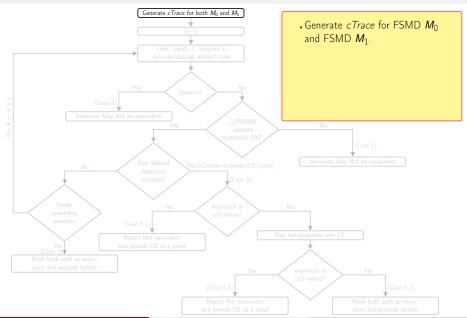
```
//Live variables
assert(x_s = x_t);
assert(y_s = y_t);
//Output variable
assert(out_s = out_t);
}
```

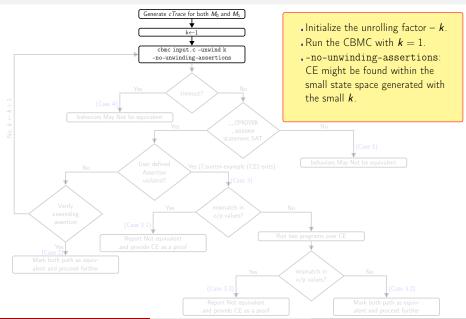
```
22 //cTrace for M1

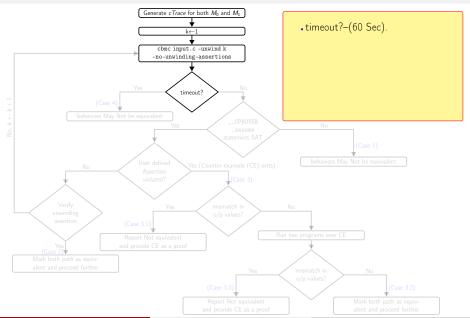
    CBMC verifies the specified assertions.

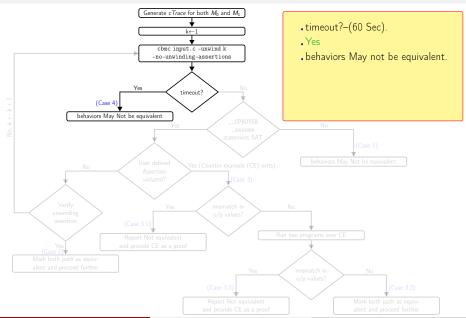
• If any violation of an assertion is detected, a
  counter-example is generated.
• n = 0 the values of the variable 'out' differs.
                                    x t=5:
                            36
                                //Live variables
                            37
                                  assert(x_s = x_t);
                            38
                                  assert(y_s = y_t);
                            39
                                //Output variable
                            40
                                 assert(out_s = out_t);
                            41
```

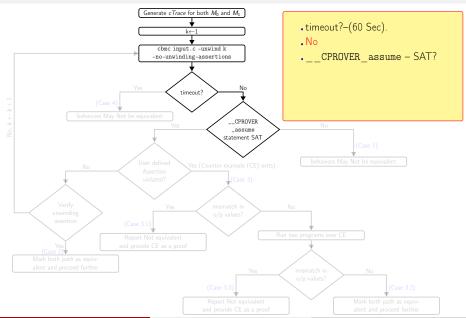


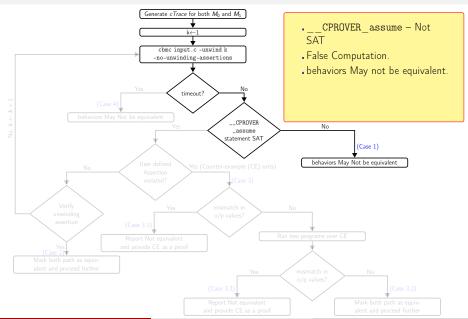


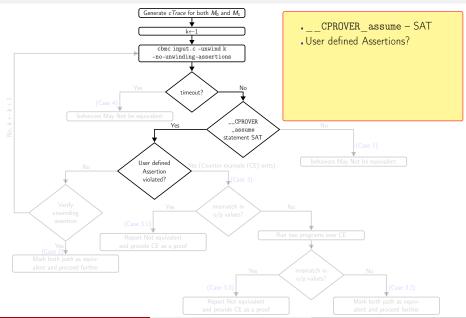


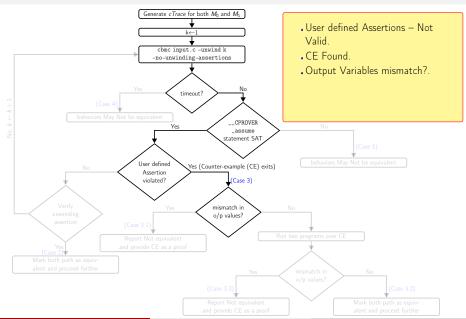


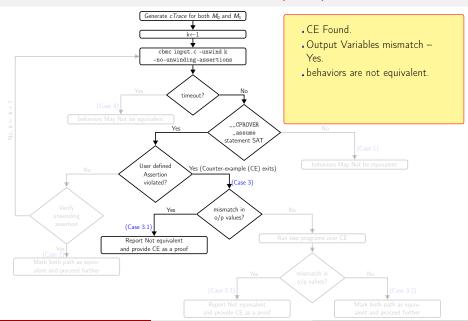


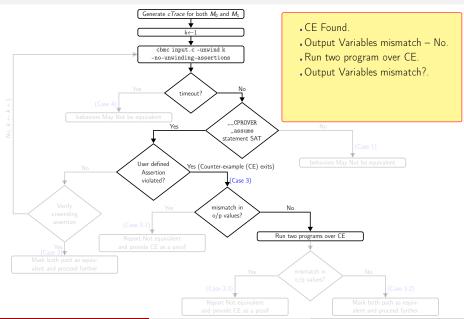


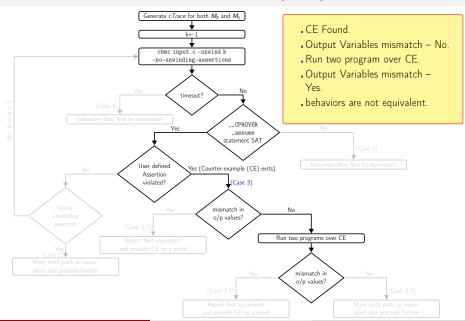


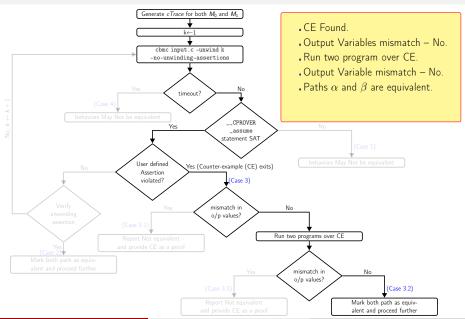


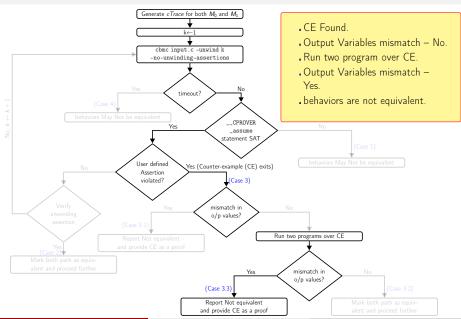


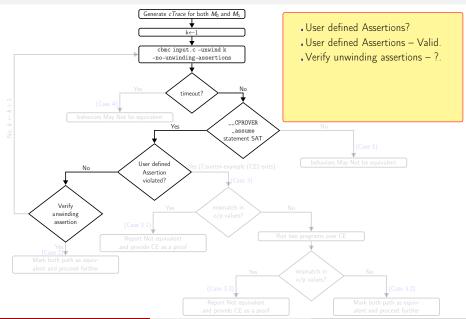


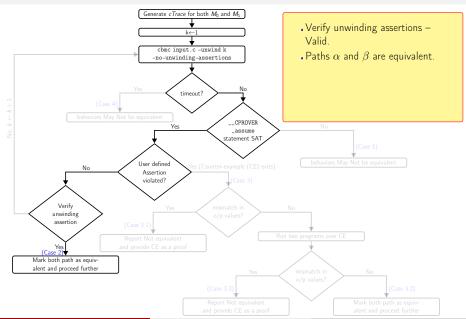


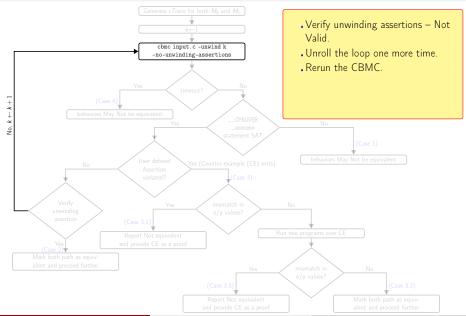












Benchmarks	#Path	#State		Decision		Time (ms)		Lines
		M_0	M_1	EVP	Our	EVP	Our	Lilles
DIFFEQ	3	15	9	Е	Е	25	25	-
LRU	39	33	32	E	E	1038	1038	-
DCT	1	8	16	MNE	NE	85	766	185
PERFECT	7	6	4	MNE	NE	56	227	74
MODN	9	8	9	MNE	NE	66	890	137
GCD	11	8	4	MNE	NE	31	100	97
Test Case	6	5	5	MNE	MNE	20	26	32

E - Equivalent, MNE - May Not be Equivalent, NE - Not Equivalent

• Implemented CEG on top of the EVP.

Benchmarks	#Path	#State		Decision		Time (ms)		Lines
		M_0	M_1	EVP	Our	EVP	Our	Lilles
DIFFEQ	3	15	9	Е	Е	25	25	-
LRU	39	33	32	Е	Е	1038	1038	-
DCT	1	8	16	MNE	NE	85	766	185
PERFECT	7	6	4	MNE	NE	56	227	74
MODN	9	8	9	MNE	NE	66	890	137
GCD	11	8	4	MNE	NE	31	100	97
Test Case	6	5	5	MNE	MNE	20	26	32

E - Equivalent, MNE - May Not be Equivalent, NE - Not Equivalent

• No side effect on the existing method.

Benchmarks	#Path	#State		Decision		Time (ms)		Lines
		M_0	M_1	EVP	Our	EVP	Our	Lilles
DIFFEQ	3	15	9	Е	Е	25	25	-
LRU	39	33	32	E	E	1038	1038	-
DCT	1	8	16	MNE	NE	85	766	185
PERFECT	7	6	4	MNE	NE	56	227	74
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GCD	11	8	4	MNE	NE	31	100	97
Test Case	6	5	5	MNE	MNE	20	26	32

E - Equivalent, MNE - May Not be Equivalent, NE - Not Equivalent

 The EVP takes strong decisions about the non-equivalence of behaviors.

Benchmarks	#Path	#State		Decision		Time (ms)		Lines
		M_0	M_1	EVP	Our	EVP	Our	Lilles
DIFFEQ	3	15	9	Е	Е	25	25	-
LRU	39	33	32	E	Е	1038	1038	-
DCT	1	8	16	MNE	NE	85	766	185
PERFECT	7	6	4	MNE	NE	56	227	74
MODN	9	8	9	MNE	NE	66	890	137
GCD	11	8	4	MNE	NE	31	100	97
Test Case	6	5	5	MNE	MNE	20	26	32

E - Equivalent, MNE - May Not be Equivalent, NE - Not Equivalent

• Finds a scenario where the EVP gives false negative result.

Conclusion & Future Works

- Proposed a CEG mechanism for the PBEC.
- PBEC is further strengthened with the CEG mechanism.
- For some scenarios PBEC reports not equivalent and provide CE as a proof.
- Identified a false negative result of the EVP method.
- Similar CEG mechanism can also be developed for other reported equivalence checking methods as well.
- Enhance the EVP to handle false negative cases.

Thank you!