

Fourth Semester B.E. Degree Examination, Dec.2014/Jan.2015
Advanced Mathematics - II

Time: 3 hrs.

Max. Marks: 100

Note: Answer any FIVE full questions.

Important Note : 1. On completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages.
 2. Any revealing of identification, appeal to evaluator and /or equations written eg, 42+8 = 50, will be treated as malpractice.

1. a. If l, m, n are the direction cosines of a line then prove that $l^2 + m^2 + n^2 = 1$. (06 Marks)
 b. Find angle between any two diagonals of a cube. (07 Marks)
 c. Find angle between two lines whose direction cosines satisfy the equations, $l + m + n = 0$ and $2l^2 + 2m^2 - mn = 0$. (07 Marks)

2. a. With the usual notations derive the equation of the plane in the form $lx + my + nz = 0$. (06 Marks)
 b. Find the equation of the plane through $(1, 2, -1)$ and perpendicular to the planes $x + y - 2z = 5$ and $3x + y + 4z = 12$. (07 Marks)
 c. Find the shortest distance between the lines,

$$\frac{x-6}{3} = \frac{y-7}{-1} = \frac{z-4}{1}$$
 and

$$\frac{x}{-3} = \frac{y+9}{2} = \frac{z-2}{4}$$
 (07 Marks)

3. a. Prove that $\vec{a} \times (\vec{b} \times \vec{c}) = \vec{b}(\vec{c} \cdot \vec{a}) - \vec{c}(\vec{a} \cdot \vec{b})$. (06 Marks)
 b. Find the sine of angle between the vectors $\vec{a} = 2\hat{i} - 2\hat{j} + \hat{k}$ and $\vec{b} = \hat{i} - 2\hat{j} + 2\hat{k}$. (07 Marks)
 c. Show that the vectors $\vec{a} = \hat{i} - 2\hat{j} + 3\hat{k}$, $\vec{b} = 2\hat{i} + \hat{j} + \hat{k}$ and $\vec{c} = 3\hat{i} + 4\hat{j} - \hat{k}$ are coplanar. (07 Marks)

4. a. Find the unit normal vector to the space curve $\vec{r} = 4 \sin t \hat{i} + 4 \cos t \hat{j} + 3t \hat{k}$. (06 Marks)
 b. A particle moves along the curve $\vec{r} = \cos 2t \hat{i} + \sin 2t \hat{j} + t \hat{k}$. Find the velocity and acceleration at $t = \frac{\pi}{8}$ along $\sqrt{2} \hat{i} + \sqrt{2} \hat{j} + \hat{k}$. (07 Marks)
 c. Find angle between the surfaces $x^2 + y^2 + z^2 = 9$ and $x = z^2 + y^2 - 3$ at $(2, -1, 2)$. (07 Marks)

5. a. Find the directional derivative of x^2yz^3 at $(1, 1, 1)$ in the direction of $\hat{i} + \hat{j} + 2\hat{k}$. (06 Marks)
 b. If $\vec{F} = (x + y + 1)\hat{i} + \hat{j} - (x + y)\hat{k}$ then show that $\vec{F} \cdot \text{curl } \vec{F} = 0$ (07 Marks)
 c. Show that the vector $\vec{F} = (3x^2 - 2yz)\hat{i} + (3y^2 - 2zx)\hat{j} + (3z^2 - 2xy)\hat{k}$ is irrotational. (07 Marks)

6 a. Prove that $L[\sin at] = \frac{a}{s^2 + a^2}$. (05 Marks)

b. Find $L[\sin t \sin 2t \sin 3t]$. (05 Marks)

c. Find $L[te^{-t} \sin 2t]$. (05 Marks)

d. Find $L\left[\frac{e^{at} - e^{bt}}{t}\right]$. (05 Marks)

7 a. If $L[f(t)] = \int_0^\infty e^{-st} f(t) dt$ then prove that $L[f''(t)] = s^2 L[f(t)] - sf(0) - f'(0)$. (05 Marks)

b. Find $L^{-1}\left[\frac{s+2}{s^2 - 4s + 13}\right]$. (05 Marks)

c. Find $L^{-1}\left[\frac{s+1}{(s-2)^3}\right]$. (05 Marks)

d. Find $L^{-1}\left[\log\left(\frac{s-a}{s-b}\right)\right]$. (05 Marks)

8 a. Using Laplace transform solve $y'' - 2y' + y = e^{2t}$ with $y(0) = 0$, $y'(0) = 1$. (10 Marks)

b. Using Laplace transform solve the simultaneous equation,

$$\frac{dx}{dt} + y = \sin t$$

$$\frac{dy}{dt} + x = \cos t$$

given that $x(0)=1$, $y(0)=0$

(10 Marks)

SOLUTIONS OF ADVANCED MATHEMATICS-II. Dec14 / Jan15

④ If l, m and n are the direction cosines of a

$$\text{line then } l = \cos \alpha = \frac{x}{r}$$

$$m = \cos \beta = \frac{y}{r}$$

$$n = \cos \gamma = \frac{z}{r}$$

$$\Rightarrow l^2 + m^2 + n^2 = \cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = \frac{x^2}{r^2} + \frac{y^2}{r^2} + \frac{z^2}{r^2}$$

$$= \frac{x^2 + y^2 + z^2}{r^2} = \frac{r^2}{r^2} = 1.$$

$$\therefore l^2 + m^2 + n^2 = 1.$$

⑤ Let us consider a cube as shown

Let 'a' be the side of a cube

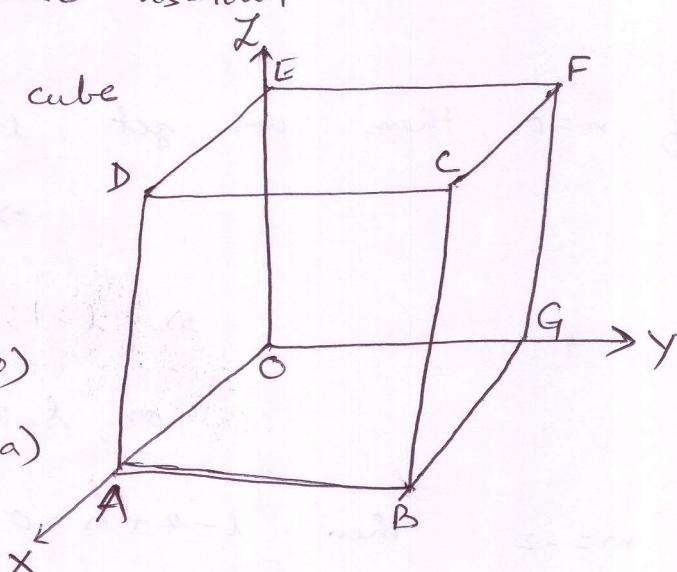
The co-ordinates of the

vertices can be given as

$$O(0,0,0), A(a,0,0), B(a,a,0)$$

$$C(a,a,a), D(a,0,a), E(0,0,a)$$

$$F(0,a,a), G(0,a,0).$$



The diagonals of this cube are OC, EB, AF and DG .

Let us consider the diagonals OC & EB .

The direction ratios of OC are $a-0, a-0, a-0 = a, a, a$

The direction ratios of EB are $a-0, a-0, 0-a = a, a, -a$

So the angle between these two diagonals is given by

$$\cos \theta = \frac{a(a) + a(a) + a(-a)}{\sqrt{a^2 + a^2 + a^2} \cdot \sqrt{a^2 + a^2 + (-a)^2}} = \frac{a^2 + a^2 - a^2}{\sqrt{3a^2} \cdot \sqrt{3a^2}} = \frac{a^2}{3a^2} = \frac{1}{3}$$

$$\Rightarrow \theta = \cos^{-1} \frac{1}{3} = \arccos \left(\frac{1}{3} \right)$$

Similarly we can show angle between DG & AF also as $\cos^{-1} \left(\frac{1}{3} \right)$.

(c) Given $l+m+n=0 \rightarrow ①$
 & $2l+2m-nm=0 \rightarrow ②$

From eqn ① we can write $l = -(m+n)$.

Using this in ② we get $2(-m-n) + 2m - nm = 0$

$$-2m - 2n + 2m - nm = 0 \Rightarrow -2n - nm = 0.$$

$$\Rightarrow -n(2+m) = 0$$

$$\Rightarrow n=0 \text{ or } m=-2$$

If $n=0$ then we get $l+m=0 \Rightarrow l=-m$

\Rightarrow If $l=1$ then $m=-1$

$\Rightarrow l=1; m=-1; n=0;$

or $l, m \& n$ are proportional to $1, -1 \& 0$

If $m=-2$ then $l-2+n=0 \Rightarrow l=2-n$

If $n=1$ then $l=1$

So if $m=2$ then $l=1$ for $n=1$

$\therefore l, m \& n$ are proportional to $1, -2, 1$.

$$\therefore \cos \theta = \frac{1(1) + (-1)(-2) + 0(1)}{\sqrt{1^2 + (-1)^2 + 0^2} \cdot \sqrt{1^2 + (-2)^2 + 1^2}} = \frac{1+2}{\sqrt{2} \cdot \sqrt{6}} = \frac{3}{\sqrt{2} \cdot \sqrt{6}} = \frac{\sqrt{3}}{2} \Rightarrow \boxed{\theta = \pi/6}$$

2@ Here l, m, n are direction cosines of the normal to the plane and p is the length of the perpendicular to the plane from the origin.

Suppose the plane meets the Co-ordinate axes at A, B, C with intercepts a, b and c respectively.

\therefore The equation of the plane is $\frac{x}{a} + \frac{y}{b} + \frac{z}{c} = 1$

$$\text{Now } l = \cos \alpha = \frac{P}{a}$$

$$m = \cos \beta = \frac{P}{b} \quad \& \quad n = \frac{P}{c}$$

$$\Rightarrow \frac{lx + my + nz}{P} = 1, \Rightarrow lx + my + nz = P.$$

⑥ The equation of the plane passing thro' the point

$(1, 2, -1)$ is given by $a(x-1) + b(y-2) + c(z+1) = 0$

$$\Rightarrow a(x-1) + b(y-2) + c(z+1) = 0$$

The Direction ratios normal to this plane are a, b, c .

The Direction ratios of the plane normal to the given

planes are $1, 1, -2$ & $3, -1, 4$ respectively.

$$\therefore \text{we can write } a+b-2c=0 \\ 3a-b+4c=0.$$

Eliminating a, b & c from the above three eqns

we get
$$\begin{vmatrix} x-1 & y-2 & z+1 \\ 1 & 1 & -2 \\ 3 & -1 & 4 \end{vmatrix} = 0$$

$$\Rightarrow (x+1)(4-2) - (y-2)(4+6) + (z+1)(-1-3) = 0$$

$$\Rightarrow 2(x-1) - 10(y-2) - 4(z+1) = 0$$

$$\Rightarrow 2x-2 - 10y + 20 - 4z - 4 = 0$$

$$\Rightarrow 2x - 10y - 4z = 2 - 20 + 4 = -14$$

$$\Rightarrow x - 5y - 2z = -7 \Rightarrow x - 5y - 2z + 7 = 0$$

is the required plane.

(c) The shortest distance between the two given lines is given by $l(x_2 - x_1) + m(y_2 - y_1) + n(z_2 - z_1)$

$$\text{where } x_1 = 6 \quad x_2 = 0$$

$$y_1 = 7 \quad y_2 = -9$$

$$z_1 = 4 \quad z_2 = 2$$

$l, m \text{ & } n$ are given by $\frac{a}{\sqrt{a^2+b^2+c^2}}, \frac{b}{\sqrt{a^2+b^2+c^2}} \text{ & } \frac{c}{\sqrt{a^2+b^2+c^2}}$

where $a, b \text{ & } c$ are obtained from a_1, b_1, c_1 & a_2, b_2, c_2

$$\text{which are } a_1 = 3; b_1 = -1, c_1 = 1 \Rightarrow 3a - b + c = 0$$

$$a_2 = -3; b_2 = 2; c_2 = 4 \Rightarrow -3a + 2b + 4c = 0$$

\therefore The shortest distance is \perp to both lines.

$$\Rightarrow \frac{a}{\begin{vmatrix} 3 & -1 \\ -3 & 2 \end{vmatrix}} = \frac{b}{\begin{vmatrix} 3 & -1 \\ -3 & 2 \end{vmatrix}} = \frac{c}{\begin{vmatrix} 3 & -1 \\ -3 & 2 \end{vmatrix}} \Rightarrow \frac{a}{-6} = \frac{b}{-5} = \frac{c}{3}$$

$$\Rightarrow \frac{a}{-2} = \frac{b}{-5} = \frac{c}{-1}$$

$$\Rightarrow a = -2; b = -5; c = 1$$

$$\text{So } l = \frac{-2}{\sqrt{(-2)^2 + (-5)^2 + 1^2}} = \frac{-2}{\sqrt{30}}; m = \frac{-5}{\sqrt{(-2)^2 + (-5)^2 + 1^2}} = \frac{-5}{\sqrt{30}} \text{ & } n = \frac{1}{\sqrt{30}}.$$

$$\therefore \text{The shortest distance} = \frac{-2(0-6) + \left(\frac{-5}{\sqrt{30}}\right)(-9-7) + \frac{1}{\sqrt{30}}(2-4)}{\sqrt{30}} \\ = \frac{12}{\sqrt{30}} + \frac{80}{\sqrt{30}} - \frac{2}{\sqrt{30}} = \frac{90}{\sqrt{30}} = 3\sqrt{30}.$$

³ ② To prove $\vec{a} \times (\vec{b} \times \vec{c}) = \vec{b}(\vec{c} \cdot \vec{a}) - \vec{c}(\vec{a} \cdot \vec{b})$

Let $\vec{a} = a_1\hat{i} + a_2\hat{j} + a_3\hat{k}$; $\vec{b} = b_1\hat{i} + b_2\hat{j} + b_3\hat{k}$ & $\vec{c} = (c_1\hat{i} + c_2\hat{j} + c_3\hat{k})$

$$\text{Now } \vec{a} \times (\vec{b} \times \vec{c}) = \vec{a} \times \vec{d} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ d_1 & d_2 & d_3 \end{vmatrix}$$

$$\vec{b} \times \vec{c} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = \vec{d}$$

$$\therefore (b_2c_3 - c_2b_3)\hat{i} + (b_1c_3 - b_3c_1)\hat{j} + (b_1c_2 - b_2c_1)\hat{k} = d_1\hat{i} + d_2\hat{j} + d_3\hat{k}$$

$$\text{So } \vec{a} \times (\vec{b} \times \vec{c}) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ d_1 & d_2 & d_3 \end{vmatrix}$$

$$= \hat{i}(a_2d_3 - d_2a_3) - \hat{j}(a_1d_3 - a_3d_1) + \hat{k}(a_1d_2 - a_2d_1)$$

$$= \hat{i}[a_2(b_1c_2 - b_2c_1) - a_3(b_3c_1 - c_3b_1)] - \hat{j}[a_1(b_1c_2 - b_2c_1) + a_3(b_2c_3 - c_2b_3)]$$

$$\begin{aligned}
& + \hat{k} \left(a_1 (b_3 c_1 - b_1 c_3) - a_2 (b_2 c_3 - c_2 b_3) \right) \\
& = \left[(a_2 c_2 + a_3 c_3) b_1 - (a_2 b_2 + a_3 b_3) c_1 \right] \hat{i} \\
& + \left[(a_1 c_1 + a_3 c_3) b_2 - (a_1 b_1 + a_3 b_3) c_2 \right] \hat{j} \\
& + \left[(a_1 c_1 + a_2 c_2) b_3 - (a_1 b_1 + a_2 b_2) c_3 \right] \hat{k} \\
& = \left[(a_1 c_1 + a_2 c_2 + a_3 c_3) b_1 - (a_1 b_1 + a_2 b_2 + a_3 b_3) c_1 \right] \hat{i} \\
& + \left[(a_1 c_1 + a_2 c_2 + a_3 c_3) b_2 - (a_1 b_1 + a_2 b_2 + a_3 b_3) c_2 \right] \hat{j} \\
& + \left[(a_1 c_1 + a_2 c_2 + a_3 c_3) b_3 - (a_1 b_1 + a_2 b_2 + a_3 b_3) c_3 \right] \hat{k} \\
& = \left[(\vec{a} \cdot \vec{c}) b_1 - (\vec{a} \cdot \vec{b}) c_1 \right] \hat{i} \\
& + \left[(\vec{a} \cdot \vec{c}) b_2 - (\vec{a} \cdot \vec{b}) c_2 \right] \hat{j} \\
& + \left[(\vec{a} \cdot \vec{c}) b_3 - (\vec{a} \cdot \vec{b}) c_3 \right] \hat{k} \\
& = (\vec{a} \cdot \vec{c}) (b_1 \hat{i} + b_2 \hat{j} + b_3 \hat{k}) - (\vec{a} \cdot \vec{b}) (c_1 \hat{i} + c_2 \hat{j} + c_3 \hat{k}). \\
& = (\vec{a} \cdot \vec{c}) \vec{b} - (\vec{a} \cdot \vec{b}) \vec{c} \\
\therefore \vec{a} \times (\vec{b} \times \vec{c}) & = (\vec{a} \cdot \vec{c}) \vec{b} - (\vec{a} \cdot \vec{b}) \vec{c}.
\end{aligned}$$

3(b)

$\sin \theta$ between a & b is given by

$$\sin \theta = \frac{|\vec{a} \times \vec{b}|}{|\vec{a}| |\vec{b}|}$$

$$\text{So } \vec{a} \times \vec{b} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 2 & -2 & 1 \\ 1 & -2 & 2 \end{vmatrix} = \hat{i}(-4+2) - \hat{j}(4-1) + \hat{k}(-4+2) \\ = -2\hat{i} - 3\hat{j} - 2\hat{k}$$

$$\therefore |\vec{a} \times \vec{b}| = \sqrt{(-2)^2 + (-3)^2 + (-2)^2} = \sqrt{17}.$$

$$|\vec{a}| = \sqrt{(2)^2 + (-1)^2 + 1^2} = \sqrt{9} = 3; \quad |\vec{b}| = \sqrt{1^2 + (-2)^2 + 2^2} = \sqrt{9} = 3$$

$$\therefore \sin \theta = \frac{\sqrt{17}}{3 \times 3} = \frac{\sqrt{17}}{9}$$

3(c) To show that the three vectors are coplanar

we need to show $\vec{a} \cdot (\vec{b} \times \vec{c}) = 0$.

$$\text{So } \vec{a} \cdot (\vec{b} \times \vec{c}) = \begin{vmatrix} 1 & -2 & 3 \\ 2 & 1 & 1 \\ 3 & 4 & -1 \end{vmatrix} = 1(-1-4) - (-2)(-2-3) + 3(8-3)$$

$$= 1(-5) + 2(-5) + 3(5) = 0.$$

$\therefore \vec{a}, \vec{b}$ and \vec{c} are coplanar.

4(a) Given $\vec{r} = 4 \sin t \hat{i} + 4 \cos t \hat{j} + 3t \hat{k}$

$$\text{Then } \vec{T} = \frac{d\vec{r}}{dt} = 4 \cos t \hat{i} - 4 \sin t \hat{j} + 3 \hat{k}$$

$$\Rightarrow |\vec{T}| = \sqrt{(4 \cos t)^2 + (-4 \sin t)^2 + 3^2} = \sqrt{16 \cos^2 t + 16 \sin^2 t + 9} \\ = \sqrt{16 + 9} = \sqrt{25} = 5$$

$$\text{So } \hat{T} = \frac{\vec{T}}{|\vec{T}|} = \frac{4 \cos t \hat{i} - 4 \sin t \hat{j} + 3 \hat{k}}{5}$$

$$\text{Further } \frac{d\hat{T}}{dt} = -\frac{4}{5} \sin t \hat{i} - \frac{4}{5} \cos t \hat{j} + 0$$

$$\Rightarrow \frac{d\hat{T}}{ds} = \frac{d\hat{T}/dt}{ds/dt} = \frac{d\hat{T}/dt}{|d\vec{r}/dt|} = \frac{-\frac{4}{5} (\sin t \hat{i} + \cos t \hat{j})}{5}$$

$$\Rightarrow \frac{d\hat{T}}{ds} = -\frac{4}{25} (\sin t \hat{i} + \cos t \hat{j})$$

$$\Rightarrow \left| \frac{d\hat{T}}{ds} \right| = \sqrt{\left(-\frac{4}{25} \sin t \right)^2 + \left(-\frac{4}{25} \cos t \right)^2} = \sqrt{\frac{16}{625} (\cos^2 t + \sin^2 t)} \\ = \frac{4}{25}$$

\therefore The unit normal vector to the given (space)

$$\text{curve is } \hat{n} = \frac{d\hat{T}/ds}{\left| d\hat{T}/ds \right|} = \frac{-\frac{4}{25} (\sin t \hat{i} + \cos t \hat{j})}{\frac{4}{25}}$$

$$\Rightarrow \hat{n} = -(\sin t \hat{i} + \cos t \hat{j})$$

4(b) Given $\vec{r} = \cos 2t \hat{i} + \sin 2t \hat{j} + t \hat{k}$

$$\vec{v} = \frac{d\vec{r}}{dt} = -2 \sin 2t \hat{i} + 2 \cos 2t \hat{j} + \hat{k}$$

$$\Rightarrow \vec{v} \Big|_{t=\frac{\pi}{8}} = -2 \sin \frac{\pi}{4} \hat{i} + 2 \cos \frac{\pi}{4} \hat{j} + \hat{k} = -\sqrt{2} \hat{i} + \sqrt{2} \hat{j} + \hat{k}$$

$\therefore \vec{v} = \frac{d\vec{r}}{dt} = -\sqrt{2} \hat{i} + \sqrt{2} \hat{j} + \hat{k}$ is the velocity at $t = \pi/8$

Now $\vec{a} = \frac{d\vec{v}}{dt} = -4 \cos 2t \hat{i} - 4 \sin 2t \hat{j}$

$$\Rightarrow \vec{a} \Big|_{t=\frac{\pi}{8}} = -4 \cos \frac{\pi}{4} \hat{i} - 4 \sin \frac{\pi}{4} \hat{j} = -4\sqrt{2} \hat{i} - 4\sqrt{2} \hat{j}$$

$$\Rightarrow \vec{a} = -2\sqrt{2} \hat{i} - 2\sqrt{2} \hat{j} \text{ at } t = \pi/8$$

Now velocity along the vector \vec{b} is $\vec{v} \cdot \hat{b} = \vec{v} \Big|_{t=\pi/8} \cdot \frac{\vec{b}}{|\vec{b}|}$

we know $\vec{v} \Big|_{t=\pi/8} = -\sqrt{2} \hat{i} + \sqrt{2} \hat{j} + \hat{k}$ & $\frac{\vec{b}}{|\vec{b}|} = \frac{\sqrt{2} \hat{i} + \sqrt{2} \hat{j} + \hat{k}}{\sqrt{(\sqrt{2})^2 + (\sqrt{2})^2 + 1^2}}$

$$\text{so } \vec{v} \cdot \hat{b} = (-\sqrt{2} \hat{i} + \sqrt{2} \hat{j} + \hat{k}) \cdot \left(\frac{\sqrt{2} \hat{i} + \sqrt{2} \hat{j} + \hat{k}}{\sqrt{5}} \right) = -\frac{2+2+1}{\sqrt{5}} = \frac{1}{\sqrt{5}}$$

Now acceleration \vec{a} along $\vec{b} = \vec{a} \Big|_{t=\pi/8} \cdot \frac{\vec{b}}{|\vec{b}|}$

$$= (-2\sqrt{2} \hat{i} - 2\sqrt{2} \hat{j}) \cdot \left(\frac{\sqrt{2} \hat{i} + \sqrt{2} \hat{j} + \hat{k}}{\sqrt{5}} \right) = -\frac{4+4}{\sqrt{5}} = -\frac{8}{\sqrt{5}}$$

4 (c) Let the two given surfaces be $\phi = x^2 + y^2 + z^2 - 9$
and $\psi = x^2 + y^2 - x - 3$.

The angle between these two surfaces be the angle between their normals. Say \hat{n}_1 and \hat{n}_2 respectively.

We know $\hat{n}_1 = \frac{\vec{n}_1}{|\vec{n}_1|}$ and $\vec{n}_1 = [\nabla \phi]_{\text{at } (2, -1, 2)}$.

Wly $\hat{n}_2 = \frac{\vec{n}_2}{|\vec{n}_2|}$ and $\vec{n}_2 = [\nabla \psi]_{\text{at } (2, -1, 2)}$.

$$\text{So } \vec{n}_1 = (\nabla \phi)_{(2, -1, 2)} = \left(2x \hat{i} + 2y \hat{j} + 2z \hat{k} \right) \underset{\text{at } (2, -1, 2)}{=} 4\hat{i} - 2\hat{j} + 4\hat{k}$$

$$\Rightarrow |\vec{n}_1| = \sqrt{4^2 + (-2)^2 + 4^2} = \sqrt{36} = 6.$$

$$\therefore \hat{n}_1 = \frac{4\hat{i} - 2\hat{j} + 4\hat{k}}{6}$$

$$\text{Now } \vec{n}_2 = (\nabla \psi)_{(2, -1, 2)} = \left(-\hat{i} + 2y \hat{j} + 2z \hat{k} \right) \underset{(2, -1, 2)}{=} -\hat{i} - 2\hat{j} + 4\hat{k}$$

$$\Rightarrow |\vec{n}_2| = \sqrt{(-1)^2 + (-2)^2 + 4^2} = \sqrt{21}. \quad \therefore \hat{n}_2 = \frac{\vec{n}_2}{|\vec{n}_2|} = \frac{-\hat{i} - 2\hat{j} + 4\hat{k}}{\sqrt{21}}$$

$$\begin{aligned} \text{Now } \cos \theta &= \frac{\vec{n}_1 \cdot \vec{n}_2}{|\vec{n}_1| \cdot |\vec{n}_2|} = \frac{4\hat{i} - 2\hat{j} + 4\hat{k}}{6} \cdot \frac{-\hat{i} - 2\hat{j} + 4\hat{k}}{\sqrt{21}} \\ &= \frac{4(-1) + (-2)(-2) + 4(4)}{6(\sqrt{21})} = \frac{-4 + 4 + 16}{6(\sqrt{21})} = \frac{8}{3\sqrt{21}} \end{aligned}$$

$\Rightarrow \theta = \cos^{-1} \left(\frac{8}{3\sqrt{21}} \right)$ is the angle b/w the two surfaces.

5(a) We know the directional derivative of $\phi = xyz^3$ in the direction of \vec{a} is $\nabla \phi \cdot \hat{a}$

$$\nabla \phi = 2xyz^3 \hat{i} + x^2z^3 \hat{j} + 3x^2yz^2 \hat{k} \Rightarrow (\nabla \phi)_{\text{at } (1,1,1)} = 2\hat{i} + \hat{j} + 3\hat{k}$$

$$\hat{a} = \frac{\vec{a}}{|\vec{a}|} = \frac{\hat{i} + \hat{j} + 2\hat{k}}{\sqrt{1^2 + 1^2 + 2^2}} = \frac{\hat{i} + \hat{j} + 2\hat{k}}{\sqrt{6}}$$

\therefore The directional derivative of ϕ along a is $(2\hat{i} + \hat{j} + 3\hat{k}) \cdot \left(\frac{\hat{i} + \hat{j} + 2\hat{k}}{\sqrt{6}} \right)$

$$\nabla \phi \cdot \hat{a} \underset{\text{at } (1,1,1)}{=} \frac{2+1+6}{\sqrt{6}} = \frac{9}{\sqrt{6}}$$

5(b) To show that $\vec{F} \cdot \text{curl } \vec{F} = 0$ we need to show that

$$\vec{F} \cdot (\nabla \times \vec{F}) = 0; \quad \text{first } \text{curl } \vec{F} = \nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x+y+1 & 1 & -(x+y) \end{vmatrix}$$

$$= \hat{i}(-1-0) - \hat{j}(-1-0) + \hat{k}(0-1) = -\hat{i} + \hat{j} - \hat{k}.$$

$$\begin{aligned} \text{now } \vec{F} \cdot \nabla \times \vec{F} &= ((x+y+1)\hat{i} + \hat{j} - (x+y)\hat{k}) \cdot (-\hat{i} + \hat{j} - \hat{k}) \\ &= (x+y+1)(-1) + 1 + (x+y) = 0 \end{aligned}$$

5(c) To show that the vector \vec{F} is irrotational, we show $\text{curl } \vec{F} = 0$

$$\text{so } \text{curl } \vec{F} = \nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 3x^2 - 2yz & 3y^2 - 2zx & 3z^2 - 2xy \end{vmatrix} = \begin{matrix} \hat{i}(-2x+2x) \\ -\hat{j}(-2y+2y) \\ +\hat{k}(-2z+2z) \end{matrix}$$

$$= 0$$

$$\Rightarrow \text{curl } \vec{F} = \nabla \times \vec{F} = 0 \Rightarrow \vec{F} \text{ is irrotational.}$$

$$6 @ L(\sin at) = \int_0^\infty e^{-st} \sin at \, dt = \left[\frac{e^{-st}}{-s^2 + a^2} (-s \sin at - a \cos at) \right]_0^\infty$$

$$= \frac{e^{-\infty}}{s^2 + a^2} (s \sin at + a \cos at) \Big|_{at=t=\infty} - \frac{e^{-0}}{s^2 + a^2} (-s \sin 0 - a \cos 0) = 0 + \frac{a}{a^2 + s^2}$$

$$\text{So } L(\sin at) = \frac{a}{s^2 + a^2};$$

$$\begin{aligned} b) L(\sin t \sin 2t \sin 3t) &= L(\sin t \cdot \frac{1}{2} [L(s(2t-3t)) - L(s(2t+3t))]) \\ &= \frac{1}{2} L(\sin t (\cos t - \cos 5t)) - \frac{1}{2} L(\sin t \cos t) - \frac{1}{2} L(\sin t \cos 5t) \\ &= \frac{1}{2} L\left(\frac{1}{2} \sin 2t\right) - \frac{1}{2} L\left(\frac{1}{2} \sin(5+t) - \sin(5-t)\right) \\ &= \frac{1}{4} L(\sin 2t) - \frac{1}{4} L(\sin 6t) + \frac{1}{4} \sin 4t \\ &= \frac{1}{4} \left(\frac{2}{s^2 + 2^2} \right) - \frac{1}{4} \frac{6}{s^2 + 6^2} + \frac{1}{4} \frac{4}{s^2 + 4^2} = \frac{2}{4} \left(\frac{1}{s^2 + 2^2} - \frac{3}{s^2 + 6^2} + \frac{2}{s^2 + 4^2} \right) \\ &= \frac{1}{2} \left(\frac{1}{s^2 + 2^2} - \frac{3}{s^2 + 6^2} + \frac{2}{s^2 + 4^2} \right) \end{aligned}$$

$$c) L(t e^{-t} \sin 2t) = L(e^{-t}, t \sin 3t).$$

$$\text{we know } L(\sin 3t) = \frac{3}{s^2 + 3^2} \Rightarrow L(t \sin 3t) = (-1) \frac{d}{ds} \left(\frac{3}{s^2 + 9} \right)$$

$$= - \frac{-3}{(s^2 + 9)^2} \cdot \frac{d}{ds}(s^2 + 9) = \frac{3}{(s^2 + 9)} \cdot 2s = \frac{6s}{(s^2 + 9)^2}$$

$$\Rightarrow L(e^{-t} t \sin 3t) = \frac{6(s+1)}{(s+1)^2 + 18(s+1)^2 + 81} = \frac{6(s+1)}{(s+1)^4 + 18(s+1)^2 + 81}$$

$$d) L\left(\frac{e^{at} - e^{bt}}{t}\right) = L\left(\frac{e^{at}}{t} - \frac{e^{bt}}{t}\right) = L\left(\frac{e^{at}}{t}\right) - L\left(\frac{e^{bt}}{t}\right)$$

$$\mathcal{L}(e^{at} - e^{bt}) = \frac{1}{s-a} - \frac{1}{s-b}$$

$$\Rightarrow \mathcal{L}\left(\frac{e^{at} - e^{bt}}{t}\right) = \int_s^\infty \left(\frac{1}{s-a} - \frac{1}{s-b}\right) ds = \log(s-a) - \log(s-b) \Big|_s^\infty$$

$$= \log\left(\frac{s-a}{s-b}\right) \Big|_s^\infty = \log\left(\frac{1-\frac{a}{s}}{1-\frac{b}{s}}\right) \Big|_s^\infty = \log 1 - \log\left(\frac{(s-a)}{s-b}\right)$$

$$= 0 - \log \frac{s-a}{s-b} = \log \frac{b-a}{s-a}$$

7(a) Given $\mathcal{L}(f(t)) = \int_0^\infty e^{-st} f(t) dt$

$$\Rightarrow \mathcal{L}(f'(t)) = \int_0^\infty e^{-st} f'(t) dt = \left[e^{-st} f(t) \right]_0^\infty - \int_0^\infty e^{-st} (-f'(t)) dt$$

$$= 0 - f(0) + s \int_0^\infty e^{-st} f(t) dt$$

$$\Rightarrow \mathcal{L}(f'(t)) = s \mathcal{L}(f(t)) - f(0)$$

now $\mathcal{L}(f''(t)) = \int_0^\infty e^{-st} f''(t) dt = \left[e^{-st} f'(t) \right]_0^\infty - \int_0^\infty e^{-st} (-f'(t)) dt$

$$= 0 - f'(0) + s \int_0^\infty e^{-st} f'(t) dt$$

$$= -f'(0) + s \mathcal{L}(f'(t))$$

$$= -f'(0) + s [s \mathcal{L}(f(t)) - f(0)]$$

$$\Rightarrow \mathcal{L}(f''(t)) = s^2 \mathcal{L}(f(t)) - s f(0) - f'(0)$$

7(b) Let $F(s) = \frac{s+2}{s^2 - 4s + 13} = \frac{s+2}{(s-2)^2 + 9} = \frac{(s-2)+4}{(s-2)^2 + 9}$

$$\Rightarrow \mathcal{L}^{-1}(F(s)) = \mathcal{L}^{-1}\left(\frac{(s-2)}{(s-2)^2 + 9}\right) + \mathcal{L}^{-1}\left[\frac{4}{(s-2)^2 + 9}\right] = e^{2t} \left[\mathcal{L}^{-1}\left(\frac{s}{s^2 + 9}\right) + \mathcal{L}^{-1}\left(\frac{4}{s^2 + 9}\right) \right]$$

$$= e^{2t} \left[\cos 3t + \frac{4}{3} \sin 3t \right].$$

$$\therefore L^{-1} \left[\frac{s+2}{(s-2)^2 + 3^2} \right] = e^{2t} \left[\cos 3t + \frac{4}{3} \sin 3t \right].$$

7(c) Let $F(s) = \frac{s+1}{(s-2)^3} = \frac{s-2+3}{(s-2)^3} = \frac{(s-2)}{(s-2)^3} + \frac{3}{(s-2)^3}$

$$= \frac{1}{(s-2)^2} + \frac{3}{(s-2)^3}$$

$$\Rightarrow L^{-1}(F(s)) = L^{-1} \left(\frac{1}{(s-2)^2} + \frac{3}{(s-2)^3} \right) = L^{-1} \left(\frac{1}{(s-2)^2} \right) + 3 L^{-1} \left(\frac{1}{(s-2)^3} \right).$$

$$= e^{2t} L^{-1} \left(\frac{1}{s^2} \right) + 3 e^{2t} L^{-1} \left(\frac{1}{s^3} \right).$$

$$= e^{2t} \frac{t^{2-1}}{(2-1)!} + 3e^{2t} \cdot \frac{t^{3-1}}{(3-1)!} = e^{2t} \frac{t}{1} + 3e^{2t} \frac{t^2}{2!}$$

$$\Rightarrow L^{-1} \left(\frac{s+1}{(s-2)^3} \right) = t e^{2t} + \frac{3}{2} e^{2t} \cdot t^2 = t e^{2t} \left[1 + \frac{3t}{2} \right].$$

7(d) Let $F(s) = \log \frac{(s-a)}{(s-b)}$ so $L^{-1}(F(s)) = L^{-1} \left(\log \frac{s-a}{s-b} \right)$

$$\text{Let } f(t) = L^{-1}(F(s)) = L^{-1} \left(\log \frac{(s-a)}{(s-b)} \right).$$

$$\Rightarrow t f(t) = L^{-1} \left(-\frac{d}{ds} \log \frac{(s-a)}{(s-b)} \right) = -L^{-1} \left[\frac{d}{ds} \left\{ \log \frac{(s-a)}{(s-b)} \right\} \right]$$

$$= -L^{-1} \left[\frac{1}{s-a} - \frac{1}{s-b} \right] = L^{-1} \left(\frac{1}{s-b} \right) - L^{-1} \left(\frac{1}{s-a} \right)$$

$$tf(t) = e^{bt} - e^{at}$$

$$\Rightarrow f(t) = \frac{e^{bt} - e^{at}}{t}$$

$$\therefore L^{-1} \left(\log \frac{(s-a)}{(s-b)} \right) = \frac{e^{bt} - e^{at}}{t}$$

8 (a) Taking Laplace Transform on both sides of the given diff. eqn.

$$\text{we get } L(y'' - 2y' + y) = L(e^{2t}) \Rightarrow L(y'') - 2L(y') + L(y) = \frac{1}{s-2}$$

$$s^2 L(y) - s y(0) - y'(0) - 2(s L(y) - y(0)) + L(y) = \frac{1}{s-2}$$

$$\Rightarrow (s^2 - 2s + 1)L(y) - 1 = \frac{1}{s-2} \Rightarrow (s-1)^2 L(y) = \frac{1}{s-2} + 1 = \frac{s-1}{s-2}$$

$$\Rightarrow L(y) = \frac{s-1}{s-2} * \frac{1}{(s-1)^2} = \frac{1}{(s-2)(s-1)} = \frac{1}{s-2} - \frac{1}{s-1}$$

$$\Rightarrow y = L^{-1}\left(\frac{1}{s-2} - \frac{1}{s-1}\right) = e^{2t} - e^t$$

So the soln of the given differential eqn is $\boxed{y = e^{2t} - e^t}$

8 (b) Taking Laplace Transforms on both sides of the two equations

$$L(x' + y) = L(\sin t) \quad \text{and} \quad L(y' + x) = L(\cos t)$$

$$\Rightarrow L(x') + L(y) = \frac{1}{s^2+1} \quad \Rightarrow L(y') + L(x) = \frac{s}{s^2+1}$$

$$\Rightarrow sL(x) - x(0) + L(y) = \frac{1}{s^2+1} \rightarrow ① \quad \Rightarrow -sL(y) - y(0) + L(x) = \frac{s}{s^2+1} \rightarrow ②$$

$$\Rightarrow sL(x) + L(y) = \frac{1}{s^2+1} + 1 * s \Rightarrow s^2 L(x) + sL(y) = s\left(1 + \frac{1}{1+s^2}\right)$$

$$L(x) + sL(y) = \frac{s}{s^2+1} * 1 \Rightarrow L(x) + sL(y) = \frac{s}{s^2+1}$$

$$(s^2-1)L(x) = s + \frac{s}{1+s^2} - \frac{s}{1+s^2} = s$$

$$\Rightarrow L(x) = \frac{s}{s^2-1} \Rightarrow x = L^{-1}\left(\frac{s}{s^2-1}\right) = \cosh t$$

also we have $y = \sin t - x' = \sin t - \sinh t$ ($\because x = \cosh t$)

i.e. The solns of the given simultaneous equations are

$$\boxed{y = \sin t - \sinh t} \quad \& \quad \boxed{x = \cosh t}.$$