

## Week 2

27 January 2025 23:42



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2 Lecture

## Linear transformations

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

↗  
special structure  
vector space

## Principle of Superposition

for any  $\alpha, \beta \in \mathbb{R}$ &  $u, v \in \mathbb{R}^n$ a f. s. f satisfies (SP) iff

$$f(\alpha u + \beta v) = \alpha f(u) + \beta f(v)$$

[Satisfy this to get superposition]

1)  $f(x)$   $x \in \mathbb{R}^3$

$\times$   $f\left(\begin{matrix} x_1 \\ x_2 \\ x_3 \end{matrix}\right) = f(x) = \boxed{x_1^2 - 2x_2 + x_3}$

$f: \mathbb{R}^n \rightarrow \mathbb{R}$

2) Ex:  $f: \mathbb{R}^n \rightarrow \mathbb{R}$

$\checkmark$  Fix  $a \in \mathbb{R}^n$   $a = \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix}$

$\forall x \in \mathbb{R}^n$   $\nrightarrow x \rightarrow$  belongs to  $\mathbb{R}^n$  and apply f

$f(x) = a^T x = (a_1 \dots a_n) \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$

Result in  $\Rightarrow f(x) = \boxed{a_1 x_1 + \dots + a_n x_n} = \sum_{i=1}^n a_i x_i$

## Linear map / transformation / function

Let  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  be a function which satisfies superposition

principle. Then  $f$  is a linear function

$$f(\alpha u + \beta v) = \alpha f(u) + \beta f(v)$$

from  $\mathbb{R}^n \rightarrow \mathbb{R}$ .

$\forall \alpha, \beta \in \mathbb{R}$

$u, v \in \mathbb{R}^n$

every fixed vector in  $\mathbb{R}^n$   
will give rise to a  
linear transformation  
from  $\mathbb{R}^n \rightarrow \mathbb{R}$  • (important)

Ex:  $f: \mathbb{R}^n \rightarrow \mathbb{R}$ . Fix  $a \in \mathbb{R}^n$ ,

$$f_a(x) = a^T x = \sum_{i=1}^n a_i x_i$$

$$\begin{aligned} f(\alpha x + \beta y) &= a^T (\alpha x + \beta y) = \alpha a^T x + \beta a^T y \\ &= \alpha f(x) + \beta f(y) \end{aligned}$$

Ex:  $f: \mathbb{R}^n \rightarrow \mathbb{R}$

$$f(v) = f\begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix} = v_1 + v_2 + \dots + v_n$$

$$f(\alpha u + \beta v) = f\begin{pmatrix} \alpha u_1 + \beta v_1 \\ \vdots \\ \alpha u_n + \beta v_n \end{pmatrix} = \alpha f(u) + \beta f(v)$$

$$v = \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix}$$

$$f(v) = a^T \cdot v = [1 \ 1 \ \dots \ 1] \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}$$

$$f(v) = v_1 + v_2 + \dots + v_n = \underbrace{\begin{bmatrix} 1 & 1 & \dots & 1 \end{bmatrix}}_{n \text{ times}} \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}$$

This  $f$  is not a linear transformation.

Ex:  $f: \mathbb{R}^n \rightarrow \mathbb{R}$

$n = 2$

$$f\left(\begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}\right) = \max \{v_1, \dots, v_n\}$$

$f(u+v) = 0 \neq f(u) + f(v)$

$$u = \begin{pmatrix} -1 \\ 1 \end{pmatrix}, \quad v = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$u+v = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad f(u+v) = 0 = f(u) + f(v)$$

Ex:  $f: \mathbb{R}^n \rightarrow \mathbb{R}$

$$f\left(\begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}\right) = \arg(v_1, \dots, v_n)$$

$$= \frac{1}{n}(v_1 + v_2 + \dots + v_n)$$

$$u = \begin{pmatrix} 2 \\ 3 \end{pmatrix}, \quad v = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$$

$$u+v = \begin{pmatrix} 5 \\ 5 \end{pmatrix}$$

$$f(u+v) = f(u) + f(v)$$

$$= \sum + \sum = \frac{1}{n} \sum + \frac{1}{n} \sum = \frac{1}{n} \cdot 1_n \in \mathbb{R}^n$$

This  $f$  is also a linear transformation.

$$a = \frac{1}{n} \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix} \in \mathbb{R}^n$$

$$f(v) = a^T v \quad (\text{inner product})$$

Ex:  $f: \mathbb{R}^n \rightarrow \mathbb{R}$

$$f\left(\begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}\right) = |v_1| + |v_2|$$

Not a linear map.

Inner product representation of a linear map. (from  $\mathbb{R}^n \rightarrow \mathbb{R}$ )

let  $v \in \mathbb{R}^n$ ,  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  be a linear map.

Let  $\{e_1, e_2, \dots, e_n\}$  be the std. basis of  $\mathbb{R}^n$ .

→  $v = v_1 e_1 + v_2 e_2 + \dots + v_n e_n$  where  $v = \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}$

$$f(v) = f(v_1 e_1 + v_2 e_2 + \dots + v_n e_n)$$

$$= v_1 f(e_1) + v_2 f(e_2) + \dots + v_n f(e_n) \quad \dots \text{ because } f \text{ is linear}$$

$$= \begin{bmatrix} f(e_1) & f(e_2) & \cdots & f(e_n) \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$

$a^T$

$$f(v) = a^T v$$

where

$$a = \begin{bmatrix} f(e_1) \\ f(e_2) \\ \vdots \\ f(e_n) \end{bmatrix}$$

Linear map as inner product representation is unique.

$$f(x) = a^T x = b^T x \Rightarrow (a^T - b^T)x = 0 \quad \forall x \in \mathbb{R}^n$$

$$\text{take } x = e_i \quad (a_i - b_i) = 0 \Rightarrow a_i = b_i \quad \forall i = 1, \dots, n$$

Ex:  $f: \mathbb{R}^3 \rightarrow \mathbb{R}$

$$f \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = 2v_1 + v_2 - v_3 + 4$$

$$= \underbrace{\begin{bmatrix} 2 & 1 & -1 \end{bmatrix}}_{a^T} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} + 4 \rightarrow \text{affine, they move from the initial original position.}$$

$$f(v) = a^T v + 4$$

### Affine functions.

A function  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  is called as an affine function

if & only if it can be represented as

$$f(v) = a^T v + b$$

Every linear map is an affine map but (\*\*\*)  
every affine map is not a linear map.

for some fixed  $a \in \mathbb{R}$  &  $b \in \mathbb{R}$ .

If  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is affine, then

$$f(\alpha u + \beta v) = \alpha f(u) + \beta f(v) \quad \boxed{\text{where } \alpha + \beta = 1}$$

$$\begin{aligned} f(\alpha u + \beta v) &= a^T (\alpha u + \beta v) + b \\ &= \alpha a^T u + \beta a^T v + (\alpha + \beta) b \\ &= \alpha (a^T u + b) + \beta (a^T v + b) \\ &= \alpha f(u) + \beta f(v) \end{aligned}$$



Linear functions  $\mathbb{R}^n \rightarrow \mathbb{R}$   
representation of linear  $f$  as inner products

Affine  $f : \mathbb{R}^n \rightarrow \mathbb{R}$

representation

## Affine maps

$f: \mathbb{R}^n \rightarrow \mathbb{R}$  is called as affine function

if  $\exists a \in \mathbb{R}^n$  &  $b \in \mathbb{R}$

s.t.  $f(v) = a^T v + b$   $\forall v \in \mathbb{R}^n$

$$f(\alpha u + \beta v) = \alpha f(u) + \beta f(v)$$

for  $\alpha, \beta \in \mathbb{R}$  s.t.  $\alpha + \beta = 1$ .

Ex: Recall several calculus.

$f: \mathbb{R}^n \rightarrow \mathbb{R}$  differentiable.

fix  $z \in \mathbb{R}^n$

$$f(x) \approx \hat{f}(x) = f(z) + \frac{\partial f}{\partial x_1} \Big|_{x=z} (x_1 - z_1) + \dots + \frac{\partial f}{\partial x_n} \Big|_{x=z} (x_n - z_n)$$

$$\hat{f}(x) = f(z) + (\nabla f)^T (x - z)$$

$$\nabla f \Big|_{x=z} = \begin{bmatrix} \frac{\partial f}{\partial x_1} & |_{x=z} \\ \vdots & \\ \frac{\partial f}{\partial x_n} & |_{x=z} \end{bmatrix}$$

evaluated at  $x.$

$$x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}, \quad z = \begin{pmatrix} z_1 \\ \vdots \\ z_n \end{pmatrix}$$

$\hat{f}$  is an affine function of  $x$ .

$$\hat{f}(x) = (\nabla f)^T x + (f(z) - (\nabla f)^T z)$$

When  $x$  is "close" to  $z$ , then  $\hat{f}(x)$ , an affine function, approximates the function  $f$  very well.

(\*\*\*)

Ex: #  $f: \mathbb{R}^2 \rightarrow \mathbb{R}$

$$f\left(\begin{pmatrix} v_1 \\ v_2 \end{pmatrix}\right) = f(v) = \bar{a}^T v + b$$

$$z = f(v) = [a_1 \ a_2] \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} + b$$

$$\begin{aligned} z &= a_1 v_1 + a_2 v_2 + b \\ \Rightarrow & a_1 v_1 + a_2 v_2 - z + b = 0 \end{aligned}$$

Ex: Regression model

$$y = x^T \beta + \alpha$$

$x$ : feature vector

$y$ : dependent variables

$y$ : house price

$$x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix},$$

$x_1$ : area of the house

$x_2$ : no. of bedrooms

$x_3$ : no. of bathrooms

Let  $V, W$  be form

$\rightarrow f: V \rightarrow W$  is

$f(\alpha v_1 + \beta v_2)$

•  $g: V \rightarrow W$  is a  
b.f.v such that

so for easier

Linear:  $\xrightarrow{5-10-20}$

Affine:  $\xrightarrow{5-10-20}$

$$\begin{matrix} \overset{(1)}{x}, & \overset{(2)}{x}, & \dots, & x \\ \parallel & \parallel & & \cdot \\ (\vdots) & (\vdots) & & (\vdots) \\ \cdot & \cdot & & \cdot \\ \overset{(1)}{y_1}, & \overset{(2)}{y_2}, & & \parallel y_N \end{matrix}$$

Norm of vector.

A function  $\|\cdot\| : \mathbb{R}^n \rightarrow \mathbb{R}$  is defined as a norm

if it satisfies following properties:

i)  $\|\mathbf{x}\| \geq 0$   $\forall \mathbf{x} \in \mathbb{R}^n$  non-negative property  
 $\|\mathbf{x}\| = 0$  if & only if  $\mathbf{x} = 0$  positive definiteness

ii)  $\|\alpha \mathbf{x}\| = |\alpha| \|\mathbf{x}\|$  absolute homogeneity

iii)  $\|\mathbf{x} + \mathbf{y}\| \leq \|\mathbf{x}\| + \|\mathbf{y}\|$  triangle inequality

Norm: basically

$\sqrt{\cdot}$

• Euclidean norm 2-norm (most used important)

$$\text{Ex: } \|x\|_2 = \sqrt{x^T x}$$

$$\text{i) } \|x\|_2 \geq 0 \quad \forall x \in \mathbb{R}^n$$

$$\|x\|_2 = 0 \Leftrightarrow x = 0$$

$$(\Leftarrow): x = 0, \text{ then } x_1^2 + \dots + x_n^2 = 0 \Rightarrow \|x\|_2 = 0$$

$$(\Rightarrow): \|x\|_2 = 0 \Rightarrow \|x\|_2^2 = 0 \Rightarrow x_1^2 + x_2^2 + \dots + x_n^2 = 0 \Rightarrow x_i = 0 \quad \forall i = 1, 2, \dots, n$$

$$\text{ii) } \|x\|_2 = \sqrt{\sum \|x\|_2^2}$$

$$\text{iii) triangle inequality } \|x+y\|_2 \leq \|x\|_2 + \|y\|_2$$

To prove.

Cauchy-Schwarz inequality  
 $x, y \in \mathbb{R}^n$

$$x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}; \quad y = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$$

$$|\overline{x^T y}| \leq \|x\|_2 \|y\|_2$$

$$\Rightarrow \left| \sum_{i=1}^n x_i y_i \right| \leq \sqrt{\sum_{i=1}^n x_i^2} \cdot \sqrt{\sum_{i=1}^n y_i^2}$$

C-S inequality

$$x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \quad y = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$$

$$|\overline{x^T y}| \leq \|x\|_2 \|y\|_2$$

$$\left| \sum_{i=1}^n x_i y_i \right| \leq \sqrt{\sum_{i=1}^n x_i^2} \cdot \sqrt{\sum_{i=1}^n y_i^2}$$

$$\text{Proof: set } \alpha = \|x\|_2, \quad \beta = \|y\|_2$$

$$\begin{aligned}
 0 \leq \| \beta x - \alpha y \|_2^2 &= (\beta x - \alpha y)^T (\beta x - \alpha y) \\
 &= \beta^2 x^T x - 2\beta \boxed{x^T y} - 2\alpha \boxed{y^T x} + \alpha^2 y^T y \\
 &= \alpha^2 \beta^2 - 2\alpha \beta x^T y + \alpha^2 \beta^2 \\
 \Rightarrow x^T y &\leq \alpha \beta \quad \Rightarrow x^T y \leq \|x\|_2 \|y\|_2 ; \text{ Apply on } -x \& y
 \end{aligned}$$

$$\begin{aligned}
 x^T y &\leq \|x\|_2 \|y\|_2 && x \& y \\
 -x^T y &\leq \|x\|_2 \|y\|_2 && -x \& y
 \end{aligned}$$

$$\Rightarrow |x^T y| \leq \|x\|_2 \|y\|_2 \quad \blacksquare$$

### Triangle inequality

$$\begin{aligned}
 \|x+y\|_2^2 &= (x+y)^T (x+y) = x^T x + x^T y + y^T x + y^T y \\
 &= \|x\|_2^2 + 2 \circled{y^T x} + \|y\|_2^2 \\
 &\leq \|x\|_2^2 + 2 \|x\|_2 \|y\|_2 + \|y\|_2^2 \\
 &= (\|x\|_2 + \|y\|_2)^2
 \end{aligned}$$

$$\Rightarrow \|x+y\|_2 \leq \|x\|_2 + \|y\|_2$$

Examples of affine f.

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Norm

11.11.2

$$\underline{\text{Ex:}} \quad x \in \mathbb{R}^n$$

$$\|\chi\|_2 = \sqrt{\chi_1^2 + \chi_2^2 + \dots + \chi_n^2} = \sqrt{\chi^\top \chi}$$

(i), (ii), (iii)

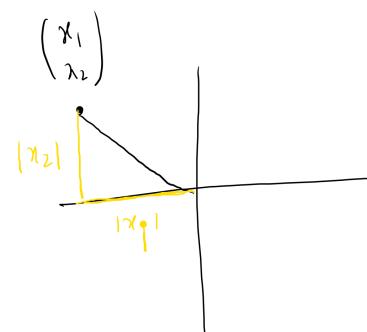
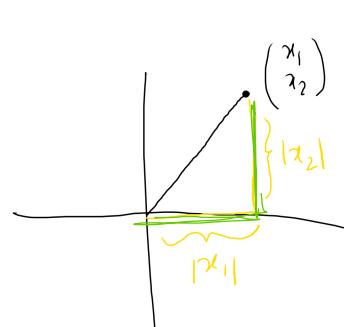
Ex:  $x \in \mathbb{R}^n$

p-norm

$$\|x\|_p = \left( |x_1|^p + \dots + |x_n|^p \right)^{1/p} = \sqrt[p]{\sum_{i=1}^n |x_i|^p} \quad p \geq 1$$

$$\|x\|_1 = |x_1| + |x_2| + \dots + |x_n|$$

$$\mathbb{R}^2 \quad x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$



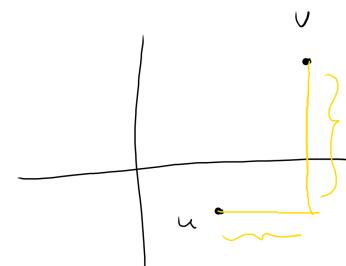
$$\|x\|_2 = \sqrt{x_1^2 + x_2^2}$$

$$\|x\|_1 = |x_1| + |x_2|$$

Distance between the vectors  $u, v \in \mathbb{R}^n$

$\|u - v\|_2 = \text{2-norm distance bet. } u \& v$

$$= \sqrt{\sum_{i=1}^n (u_i - v_i)^2}$$



$$\|u - v\|_1 = |u_1 - v_1| + |u_2 - v_2| + \dots + |u_n - v_n| \leftarrow \text{taxi-cab distance}$$

Ex: Let  $u = \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_d \end{pmatrix}$

$$u_1 \in \mathbb{R}^{n_1}, u_2 \in \mathbb{R}^{n_2}, \dots, u_d \in \mathbb{R}^{n_d}$$

$$u \in \mathbb{R}^n \Rightarrow n_1 + n_2 + \dots + n_d = n$$

$$u^T = [u_1^T \ u_2^T \ \dots \ u_d^T]$$

2 norm:

$$\|u\|_2 = \sqrt{\|u_1\|_2^2 + \|u_2\|_2^2 + \dots + \|u_d\|_2^2}$$

dist b/w 2 norm

$$\|u\|_2^2 = u \cdot u = (u_1 \ u_2 \ \dots \ u_d) \begin{pmatrix} u_1 \\ \vdots \\ u_d \end{pmatrix} = \underbrace{u_1 u_1 + \dots + u_d u_d}_{\text{OneNote}} = \|u_1\|_2^2 + \|u_2\|_2^2 + \dots + \|u_d\|_2^2$$

$$\Rightarrow \|u\|_2 = \sqrt{\|u_1\|_2^2 + \dots + \|u_d\|_2^2}$$

Angle between the vectors

let  $u, v \in \mathbb{R}^n$

$$\theta = \arccos \left( \frac{u^T v}{\|u\|_2 \|v\|_2} \right)$$

$\arccos$ : inverse cosine with values  $[0, \pi]$

$$u^T v = \|u\|_2 \|v\|_2 \cos \theta$$

$$\theta \in [0, \pi]$$

$$\theta = \arccos \left( \frac{u^T v}{\|u\|_2 \|v\|_2} \right)$$

i)  $u^T v = 0 \Rightarrow \theta = \frac{\pi}{2} \Rightarrow$  vectors  $u$  &  $v$  are orthogonal / perpendicular

ii)  $u^T v = \|u\|_2 \|v\|_2 \Rightarrow u$  &  $v$  are on the same line,  $\theta = 0$

iii)  $u^T v = -\|u\|_2 \|v\|_2 \Rightarrow u$  &  $v$  are on the same line,  $\theta = \pi$

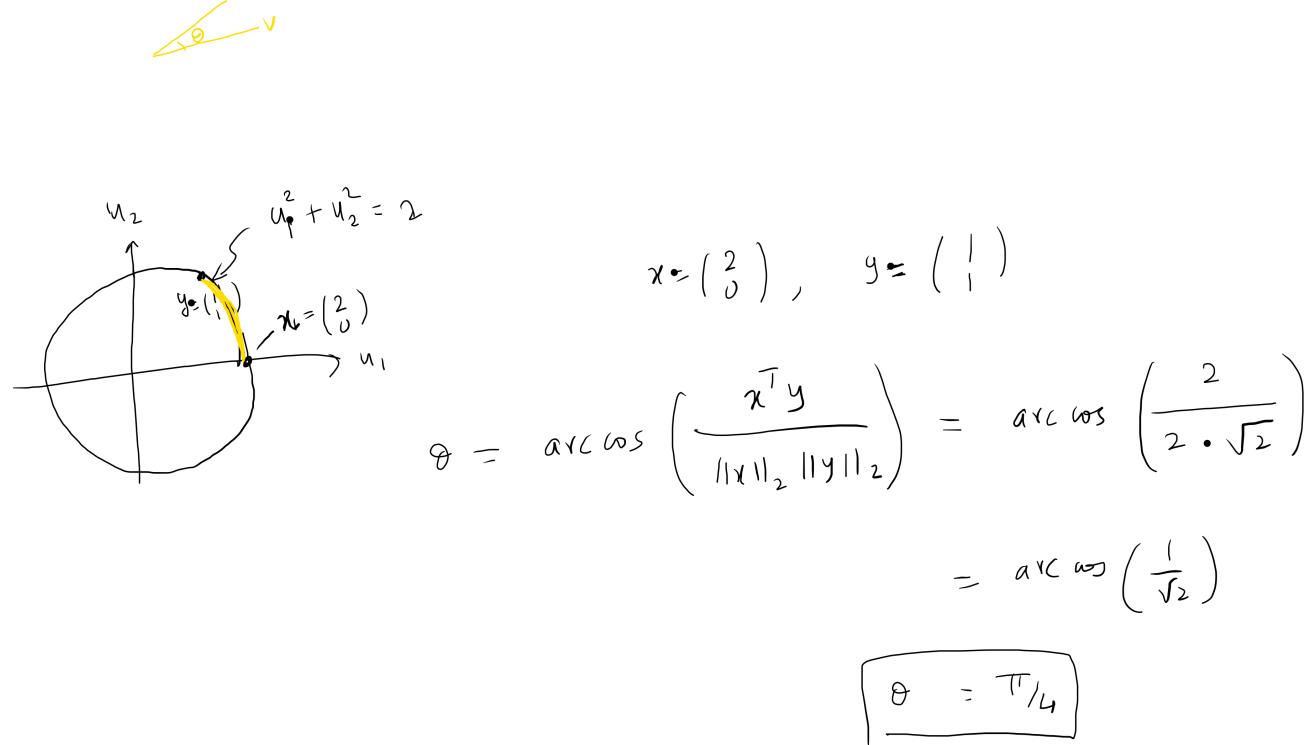
C-S inequality  $\frac{|u^T v|}{\|u\|_2 \|v\|_2} \leq 1$

$$\Rightarrow -1 \leq \frac{u^T v}{\|u\|_2 \|v\|_2} \leq 1$$

$$\|u-v\|_2 = \sqrt{\dots}$$

1 norm:

$$\|x\|_1 = |x_1|$$



## Computational complexity.

- number of floating point operations (flops)

additions / multiplications

$$x, y \in \mathbb{R}^n$$

$$x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$$

$$y = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$$

OneNote

$$\boxed{x+y} = \begin{pmatrix} x_1 + y_1 \\ x_2 + y_2 \\ \vdots \\ x_n + y_n \end{pmatrix}$$

'n' additions

$$\boxed{\alpha x} = \alpha \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} \alpha x_1 \\ \alpha x_2 \\ \vdots \\ \alpha x_n \end{pmatrix}$$

'n' multiplications

$$a^T x = [a_1 \ a_2 \ \dots \ a_n] \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

(n-1) additions

$$= \sum_{i=1}^n a_i x_i = a_1 x_1 + a_2 x_2 + \dots + a_n x_n$$

'n' multiplication

Computational complexity

$$n + (n-1) = \boxed{2n-1}$$

$$\|x\|_2 = \sqrt{x^T x}$$

class

$$\text{requires } (2n-1) + 1 = 2n \text{ flops}$$

2<sup>n-1</sup> - top

Norm

- $2, 1$
- geometrical interpretation

Angle

Computational complexity

flops

Matrix - vector multiplication

$$A \in \mathbb{R}^{m \times n}$$

$$x \in \mathbb{R}^n$$

$$A = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} ; \quad x = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

$$c = Ax \in \mathbb{R}^m$$

$$C = \begin{pmatrix} C_1 \\ C_2 \\ \vdots \\ C_m \end{pmatrix}$$

$$c_j = \sum_{k=1}^n a_{jk} x_k \quad \text{for } j = 1, 2, \dots, m$$

Row interpretation

Computational complexity

$m - \text{number of inner products of length } n \text{ vectors.}$

$m(2n-1) = 2mn - m$

$\approx 2mn$

$c = [a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n]$   
 $a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n$

$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n$

$\vdots$

$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n$

$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & & & \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$

$x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$

$i^{\text{th}} \text{ entry } c_i \text{ is the inner product of } i^{\text{th}} \text{ row of } A \text{ and } x.$

$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{pmatrix}$$

$x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$

Column interpretation

$$\Rightarrow c = Ax = \begin{pmatrix} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n \end{pmatrix}$$

$$= \begin{pmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{pmatrix} x_1 + \begin{pmatrix} a_{12} \\ a_{22} \\ \vdots \\ a_{m2} \end{pmatrix} x_2 + \cdots + \begin{pmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ a_{mn} \end{pmatrix} x_n$$

Linear function from  $\mathbb{R}^n \rightarrow \mathbb{R}^m$

A function  $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is called as  
a linear function if  $u, v \in \mathbb{R}^n$  and

scalars  $\alpha, \beta \in \mathbb{R}$

$$f(\alpha u + \beta v) = \alpha f(u) + \beta f(v)$$

superposition principle.

$$\text{Ex: } f: \mathbb{R}^n \rightarrow \mathbb{R}^{(m)=n}$$

$$f: \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \mapsto \begin{pmatrix} x_1 + x_2 \\ x_2 + x_3 \\ \vdots \\ x_n + x_1 \end{pmatrix}$$

Easy to verify that  
f is linear.

$$\text{Ex: } f: \mathbb{R}^n \rightarrow \mathbb{R}^{2n-1}$$

$$f: \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \mapsto \begin{pmatrix} x_1 \\ \frac{x_1+x_2}{2} \\ x_2 \\ \vdots \\ x_{n-1} \\ \frac{x_{n-1}+x_n}{2} \\ x_n \end{pmatrix}$$

$$f(\alpha x + \beta y) = f\left(\begin{array}{c} \alpha x_1 + \beta y_1 \\ \vdots \\ \alpha x_n + \beta y_n \end{array}\right) = \begin{pmatrix} \alpha x_1 + \beta y_1 \\ \frac{\alpha x_1 + \beta y_1 + \alpha x_2 + \beta y_2}{2} \\ \vdots \end{pmatrix}$$

$$= \alpha \begin{pmatrix} x_1 \\ \frac{x_1+x_2}{2} \\ \vdots \\ \frac{x_{n-1}+x_n}{2} \end{pmatrix} + \beta \begin{pmatrix} y_1 \\ \frac{y_1+y_2}{2} \\ \vdots \end{pmatrix} = \alpha f(x) + \beta f(y)$$

$\Rightarrow$  f is linear

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$\text{Ex: } f: \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \mapsto \begin{pmatrix} |x_1| \\ \vdots \\ |x_n| \end{pmatrix}$$

Not a linear transformation.

Ex: Let  $A \in \mathbb{R}^{m \times n}$

Define  $f_A: \mathbb{R}^n \rightarrow \mathbb{R}^m$

$$f(x) = \underbrace{Ax}_{\in \mathbb{R}^m} \quad \forall x \in \mathbb{R}^n$$

$$f(\alpha x + \beta y) = A(\alpha x + \beta y) = \alpha Ax + \beta Ay = \alpha f(x) + \beta f(y)$$

$\Rightarrow f$  is a linear transform.

Can every linear transformation be represented as matrix-vector multiplication??

Let  $e_1, e_2, \dots, e_n \in \mathbb{R}^n$  be std. basis vectors.

$$x \in \mathbb{R}^n \Rightarrow x_1 e_1 + x_2 e_2 + \dots + x_n e_n$$

Let  $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$  be any linear function.

$$f(x) = f(x_1 e_1 + x_2 e_2 + \dots + x_n e_n) = x_1 f(e_1) + x_2 f(e_2) + \dots + x_n f(e_n)$$

linear comb.  
of 'n'  
vectors in

$$= x_1 e_1 + x_2 e_2 + \dots + x_m e_m \in \mathbb{R}^m$$

f(x) = Af

where  $Af = \begin{bmatrix} f(e_1) & f(e_2) & \dots & f(e_n) \end{bmatrix}_{m \times n}$

$x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \in \mathbb{R}^n$

OneNote

$$\mathbb{R}^m$$

Two important subspaces: $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$  is linear.

$$N_f = \{x \in \mathbb{R}^n \mid f(x) = 0\} \subseteq \mathbb{R}^n = \text{Nullspace of } f$$

$$R_f = \{y \in \mathbb{R}^m \mid \exists x \in \mathbb{R}^n \text{ s.t. } f(x) = y\} \subseteq \mathbb{R}^m$$

$\uparrow f$

= Image or range space

Claim:  $N_f \subseteq \mathbb{R}^n$  is a subspace of  $\mathbb{R}^n$ Given:  $\alpha, \beta \in \mathbb{R}$  &  $x, y \in N_f$ 

To show:  $\alpha x + \beta y \in N_f$ ,

$$f(\alpha x + \beta y) = \alpha f(x) + \beta f(y) = \alpha \cdot 0 + \beta \cdot 0 = 0$$

$\uparrow$

$\alpha x + \beta y \in N_f$

Claim:  $\text{Im}(f) = R_f \subseteq \mathbb{R}^m$  is a subspace of  $\mathbb{R}^m$ .

Take:  $y_1, y_2 \in R_f$ ,  $\alpha, \beta \in \mathbb{R}$

To show:  $\alpha y_1 + \beta y_2 \in R_f$

$$y_1 \in R_f \Rightarrow \exists x_1 \text{ s.t. } f(x_1) = y_1$$

$$y_2 \in R_f \Rightarrow \exists x_2 \text{ s.t. } f(x_2) = y_2$$

$$\begin{aligned} \alpha y_1 + \beta y_2 &= \alpha f(x_1) + \beta f(x_2) \\ &= f(\alpha x_1 + \beta x_2) \end{aligned}$$

$\Rightarrow \alpha y_1 + \beta y_2$  has a pre-image  $\alpha x_1 + \beta x_2 \in \mathbb{R}^n$

$$\Rightarrow \alpha y_1 + \beta y_2 \in R_f$$

Given an  $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ , a linear  $f$ :

$$\exists A_f \in \mathbb{R}^{m \times n} \text{ s.t.}$$

$$f(x) = A_f x$$

$$\begin{aligned} N(A_f) &= \{x \in \mathbb{R}^n \mid A_f x = 0\} \subseteq \mathbb{R}^n \\ R(A_f) &= \{y \in \mathbb{R}^m \mid \exists x \in \mathbb{R}^n \text{ s.t. } A_f x = y\} \\ &\subseteq \mathbb{R}^m \end{aligned}$$

↓  
Nullspace of  $A_f$

Null space  
 Range space of  $A_f$

Matrix - vector multiplication

→ row - interpretation

→ column - interpretation.

Linear functions from  $\mathbb{R}^n \rightarrow \mathbb{R}^m$

Null space

Image space

Linear function  $\leftrightarrow A_f \in \mathbb{R}^{m \times n}$   
 $\mathbb{R}^n \rightarrow \mathbb{R}^m$

$f: \mathbb{R}^n \rightarrow \mathbb{R}^m$

Let  $A_f \in \mathbb{R}^{m \times n}$

$\sim$   $\underline{\underline{A}}^T$   $\overline{\overline{f}}$   $\overline{\overline{f}}^T$   $\overline{\overline{f}} \cdot \overline{\overline{f}}^T$

$$f(x) = A_f x = \begin{pmatrix} \vdots \\ A_1^T \\ \vdots \\ A_m^T \end{pmatrix} \underbrace{|}_{m \times n} \underbrace{x}_{n \times 1} = \begin{pmatrix} \vdots \\ \vdots \\ \vdots \end{pmatrix}$$

OneNote

$$f(x) = \begin{pmatrix} f_1(x) \\ f_2(x) \\ \vdots \\ f_m(x) \end{pmatrix} = \begin{pmatrix} A_1^T x \\ A_2^T x \\ \vdots \\ A_m^T x \end{pmatrix}$$

$$f_i : \mathbb{R}^n \rightarrow \mathbb{R} \quad i=1, 2, \dots, m$$

$f_i(x) = A_i^T x$

Affine function from  $\mathbb{R}^n$  to  $\mathbb{R}^m$

A function  $g : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is called as an affine function if there exists a matrix

$A_g \in \mathbb{R}^{m \times n}$  and  $b_g \in \mathbb{R}^m$  s.t.

$$g(x) = \boxed{A_g x} + \boxed{b_g} \in \mathbb{R}^m \quad \text{for } x \in \mathbb{R}^n$$

$$g(x) = \begin{pmatrix} g_1(x) \\ \vdots \\ g_m(x) \end{pmatrix} = \begin{pmatrix} f_1(x) \\ \vdots \\ f_m(x) \end{pmatrix} + \begin{pmatrix} b_1 \\ \vdots \\ b_m \end{pmatrix}$$

$$g(x) = \begin{pmatrix} f_1(x) + b_1 \\ \vdots \\ f_m(x) + b_m \end{pmatrix}$$

*affine*

$$g_i : \mathbb{R}^n \rightarrow \mathbb{R}$$

$i=1, 2, \dots, m$

$$t_i : \mathbb{R} \rightarrow \mathbb{R}$$

linear

Ex:  $g$  is an affine function from  $\mathbb{R}^n$  to  $\mathbb{R}^m$

if & only if

$$g(\alpha x + \beta y) = \alpha g(x) + \beta g(y)$$

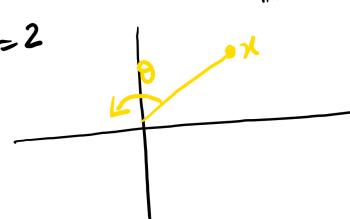
whenever  
 $\alpha, \beta \in \mathbb{R}$   
 $\alpha + \beta = 1$   
 $\text{& } x, y \in \mathbb{R}^n$

---

Examples :

$$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$$

Ex:  $m=n=2$



$f :=$  Rotation by an angle  $\theta$  in anti-clockwise direction.

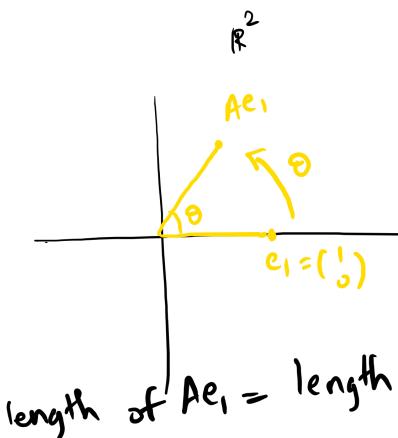
Find the matrix of this linear transformation.

$$x \in \mathbb{R}^2 \Rightarrow x_1 e_1 + x_2 e_2$$

&  $f = \text{Rotation:}$

$$f(x) = f(x_1 e_1 + x_2 e_2) = f(e_1)x_1 + f(e_2)x_2$$

$$= [f(e_1) \ f(e_2)] \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

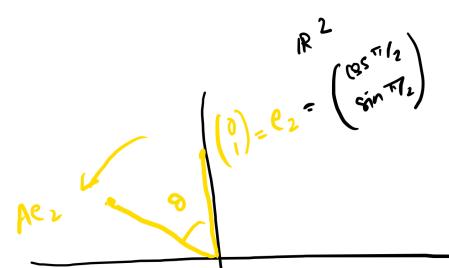


$$= Af \in \mathbb{R}^2$$

$$e_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} = r \begin{pmatrix} \cos 0 \\ \sin 0 \end{pmatrix}$$

$$Ae_1 = r \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} = \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} = f(e_1)$$

length of  $Ae_1$  = length of  $e_1$



$$Ae_2 = r \begin{pmatrix} \cos(\frac{\pi}{2} + \theta) \\ \sin(\frac{\pi}{2} + \theta) \end{pmatrix} = \begin{pmatrix} -\sin \theta \\ \cos \theta \end{pmatrix}$$

$$= f(e_2)$$

$$Af = [f(e_1) \ f(e_2)] = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \in \mathbb{R}^{2 \times 2}$$

Rotator matrix

Rotation action does NOT change the length of the vector.

(in 2-norm)

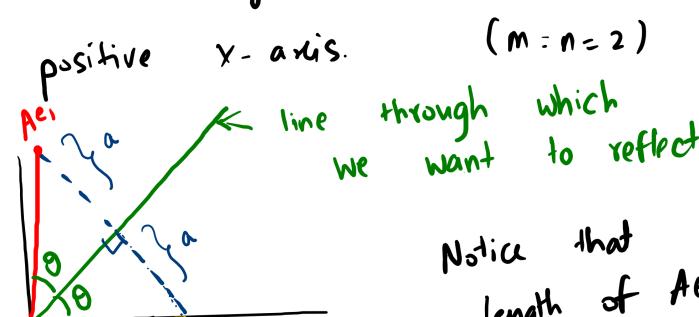
$$\|x\|_2 = \|Af x\|_2$$

Rotation will not change angle b/w the vectors.

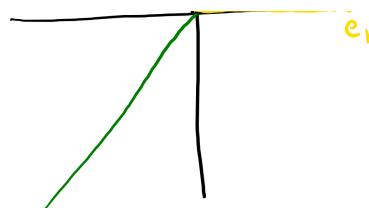
$$\langle x, y \rangle = \langle Ax^k, Af^j \rangle$$

Ex: Reflection through a line making an angle  $\theta$

with positive x-axis. ( $m:n=2$ )

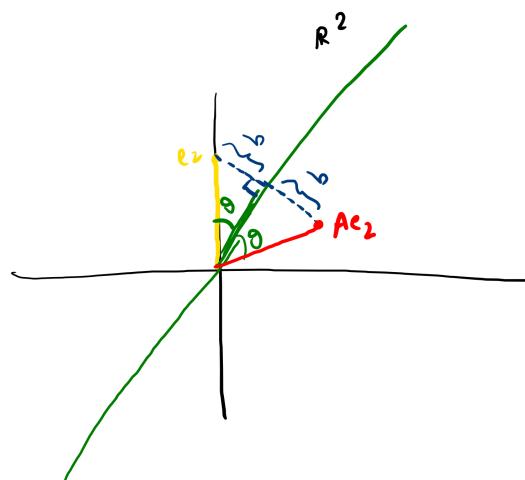


Notice that length of  $AP_1$  is same



$$Ae_1 = \begin{pmatrix} \cos 2\theta \\ \sin 2\theta \end{pmatrix}$$

as length of  $e_1 = 1$   
 $\|Ae_1\|_2 = \|e_1\|_2 = 1$



$$\|Ae_2\|_2 = \|e_2\|_2 = 1$$

$$Ae_2 = \begin{pmatrix} \sin(\pi + 2\theta) \\ \cos(\pi + 2\theta) \end{pmatrix}$$

$$Ae_2 = \begin{pmatrix} \sin(2\theta) \\ -\cos(2\theta) \end{pmatrix}$$

Rotating  $2\theta$  in clockwise direction

Matrix of reflection & angle  $\theta$  action thru' line passing thru' origin with positive X-axis

$$= \begin{bmatrix} \cos(2\theta) & \sin(2\theta) \\ \sin(2\theta) & -\cos(2\theta) \end{bmatrix} \rightarrow \text{Reflector matrix}$$

## Affine functions

- Affine combination

Examples of linear maps

$$\mathbb{R}^2 \rightarrow \mathbb{R}^2$$

- Rotators

$$\mathbb{R}^2 \rightarrow \mathbb{R}^2$$

- Reflectors

